

# Model-Based Design Toolbox MPC57xx Series

## Quick Start Guide

**An Embedded Target for the MPC57xx Family of Processors**  
**Version 3.2.0**

**Target Based Automatic Code Generation Tools**  
For MATLAB™/Simulink™/Stateflow™ Models working with Simulink Coder™ and Embedded Coder®



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# 1 Installation

Installing the Model-Based Design Toolbox is the first step in setting up and running automatic C code generation from MATLAB/Simulink for NXP's embedded target processors and development boards.

## 1.1 System Requirements

For a flowless development experience the minimum recommended PC platform is:

- *Windows® OS*: any x64 processor
- At least 4 GB of RAM
- At least 6 GB of free disk space.
- Internet connectivity for web downloads.

### Operating System Supported

|            | SP Level | 64-bit |
|------------|----------|--------|
| Windows 7  | SP1      | X      |
| Windows 10 |          | X      |

## 1.2 Installation Steps

NXP's Model-Based Design Toolbox is delivered as MATLAB Toolbox Package that can be installed offline or online from MathWorks Add-ons. This document shows how to install the offline package, assuming you have already downloaded the file from NXP's official web page.

To have the toolbox installed and configured properly the following actions should be executed:

1. Run the MATLAB toolbox package file \*.mltbx downloaded from [NXP's Model-Based Design Toolbox web page](#)
2. Register and install the toolbox license file into `..\My Documents\MATLAB\Add-Ons\Toolboxes\NXP_MBDToolbox_MPC57xx\code\lic`
3. Set the Target Compiler Environment Variables
4. Setup the MATLAB path for Model-Based Design Toolbox

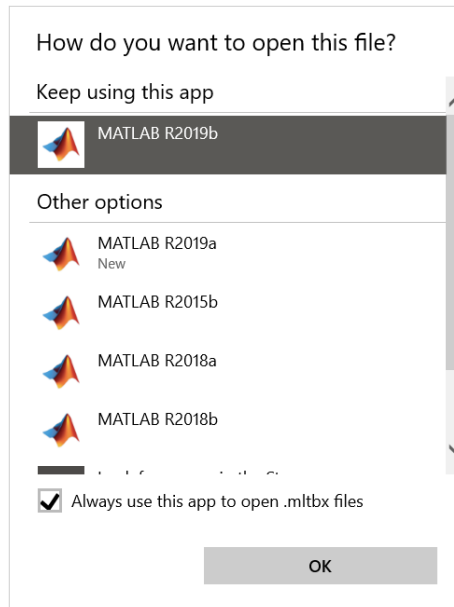
Each of these actions is explained in the following sub-chapters.

## 1.2.1 Run Add-on installer

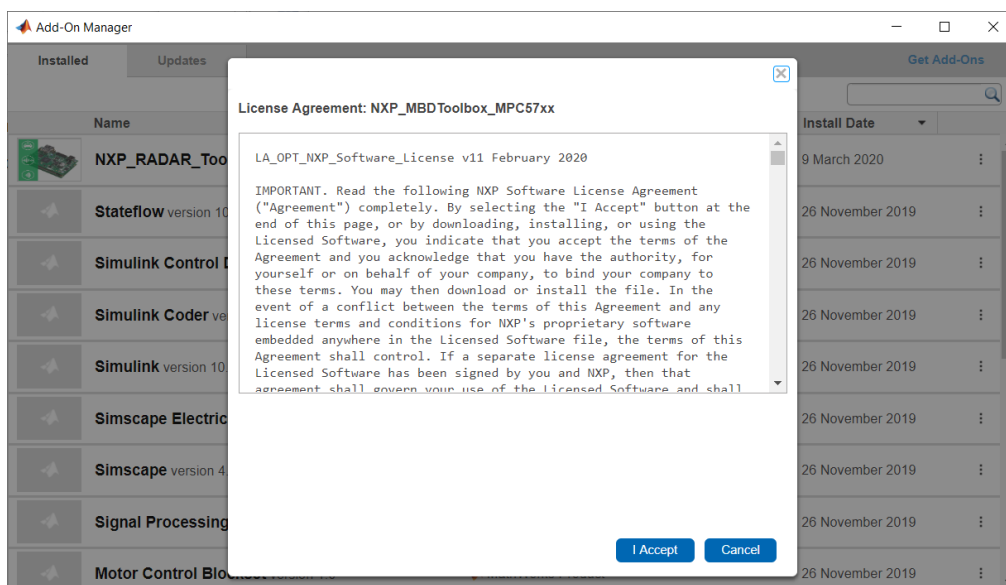
Install the NXP's Model-Based Design Toolbox by double-clicking the \*.mltbx file. This will activate the MATLAB Add-ons installer that will automatically start the installation process.

You will be prompted with the following options:

1. The NXP's Model-Based Design Toolbox Installation Wizard dialog will appear. Select a MATLAB Version to proceed.

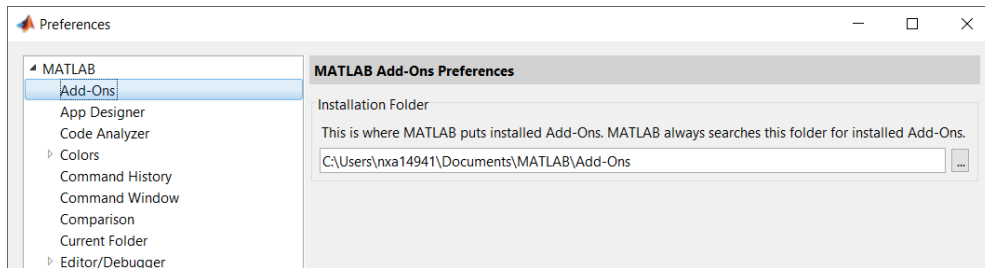


2. Indicate acceptance of the NXP Software License Agreement by selecting "I agree to the terms of the license" to proceed.

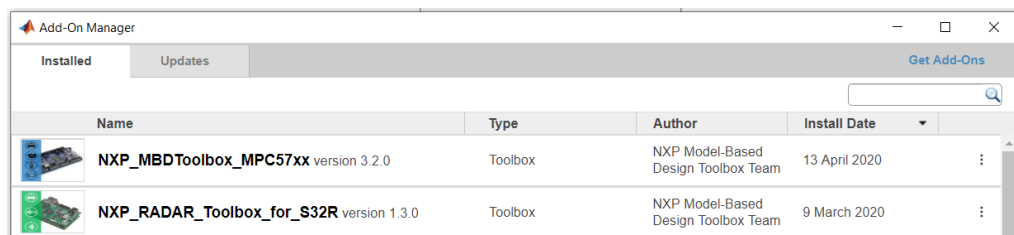
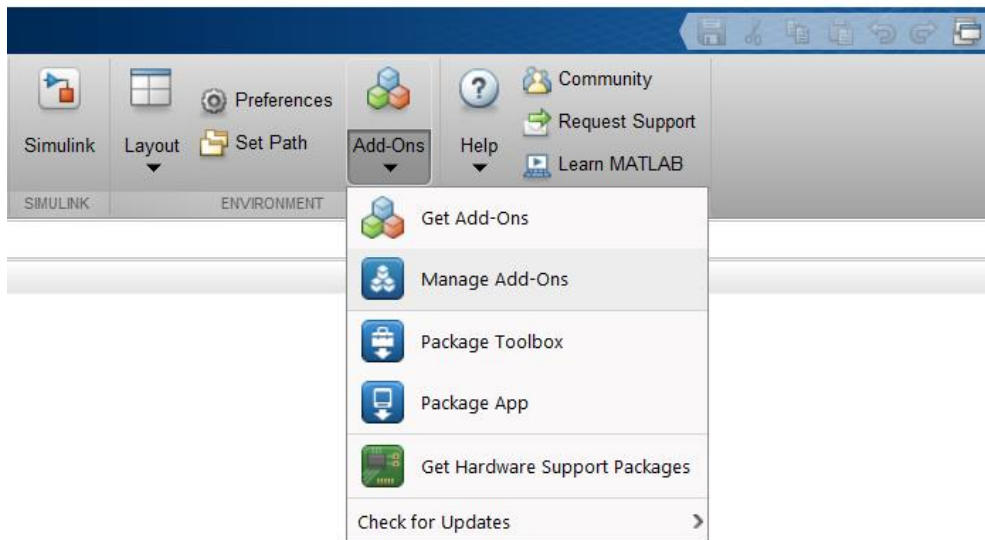


- Click “OK” to start the MATLAB installation process. The rest of the process is silent and under MATLAB control. All the files will be automatically copied into default Add-Ons folder within the MATLAB

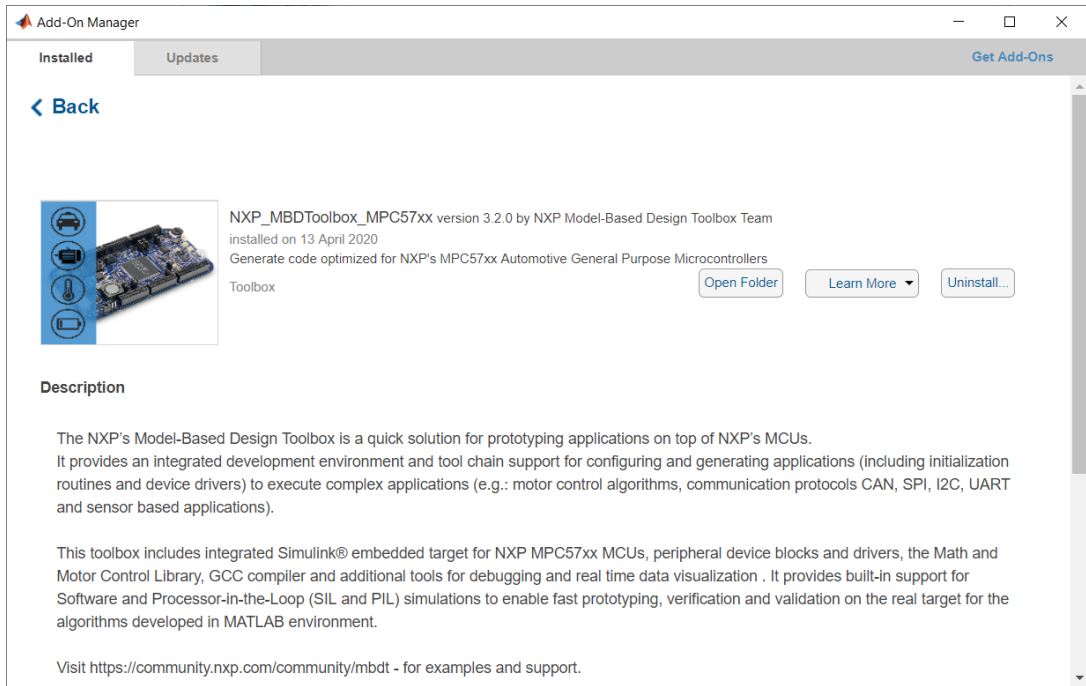
The default location can be changed before installation by changing the Add-Ons path from MATLAB Preferences



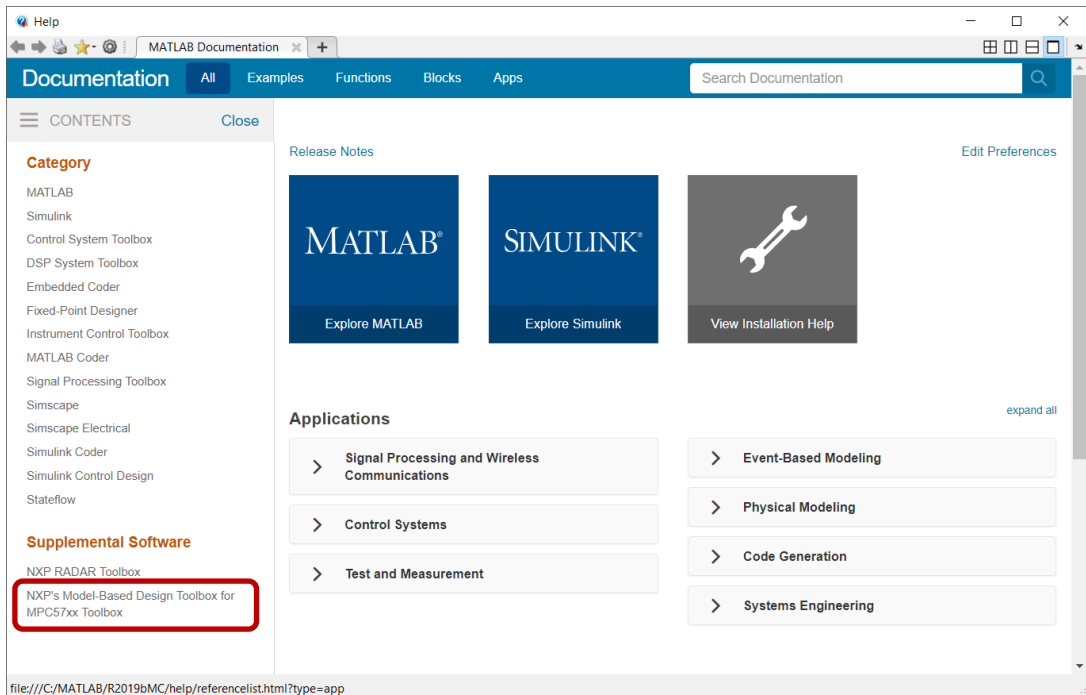
- After a couple of minutes (2-5min), the NXP’s Model-Based Design Toolbox should be visible as a new Add-ons.



- More details about the NXP’s Model-Based Design Toolbox can be found by clicking on View Details



6. NXP's Model-Based Design Toolbox documentation, help and examples are fully integrated with the MATLAB development environment. Get more details by accessing the standard Help and Supplemental Software section

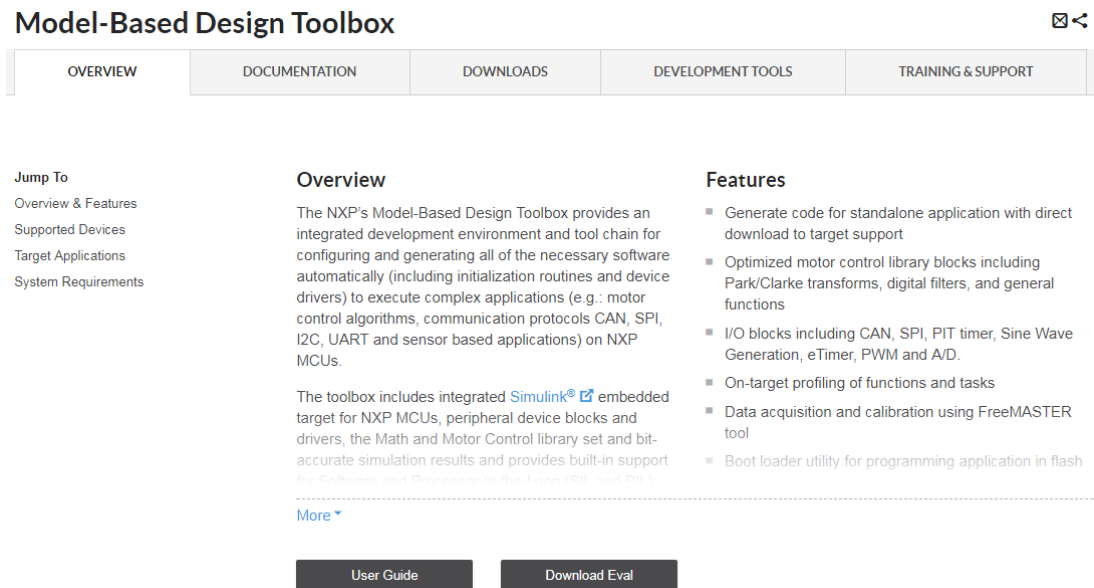


## 1.2.2 License Registration & Installation

The NXP's Model-Based Design Toolbox is available free of charge, however, a license is required. If you need to get a license it can be obtained by following the path outlined below. If you encounter issues getting a license please submit a ticket at <https://www.nxp.com/support/support:SUPPORTHOME> describing the issue.

Please perform the following steps to obtain your license:

1. Go to [www.nxp.com/mbdt](http://www.nxp.com/mbdt) and click on “Download Eval”



The screenshot shows the 'Model-Based Design Toolbox' website. At the top, there is a navigation bar with tabs for OVERVIEW, DOCUMENTATION, DOWNLOADS, DEVELOPMENT TOOLS, and TRAINING & SUPPORT. The 'OVERVIEW' tab is selected. Below the navigation bar, there is a 'Jump To' section with links for Overview & Features, Supported Devices, Target Applications, and System Requirements. The main content area is divided into three columns: Overview, Features, and a 'More' link. The Overview column contains text about the toolbox's capabilities and a link to the User Guide. The Features column lists several key features such as code generation, optimized motor control blocks, I/O blocks, on-target profiling, data acquisition, and boot loader utility. At the bottom of the page, there are two buttons: 'User Guide' and 'Download Eval'.

2. Once you have logged in, the “Product Information” page for the Model-Based Design Toolbox appears.  
Select the appropriate toolbox you wish you evaluate to bring up the Software Terms and Conditions page.
3. Click “I Agree” to consent to the software license agreement.
4. If you need to download the tool, click on the linked file name. Otherwise, click on the “License Keys” tab.
5. Verify the correct tool is identified and click on “Generate”.
6. Enter your Disk Serial Number as the Host ID. If you do not know your Disk Serial Number, go to “Locating the Host ID” in the document **Model\_Based\_Design\_Toolbox\_MPC57xx\_Series\_Licensing\_Guide.pdf** to learn how to locate your Disk Serial Number, which is needed to generate your license.
7. Click “Generate”
8. Either click on “Save All” or copy and paste the file into a text editor and save the file as “license.lic” to the folder “..\MATLAB\Add-Ons\Toolboxes\NXP\_MBDToolbox\_MPC57xx\code\lic”

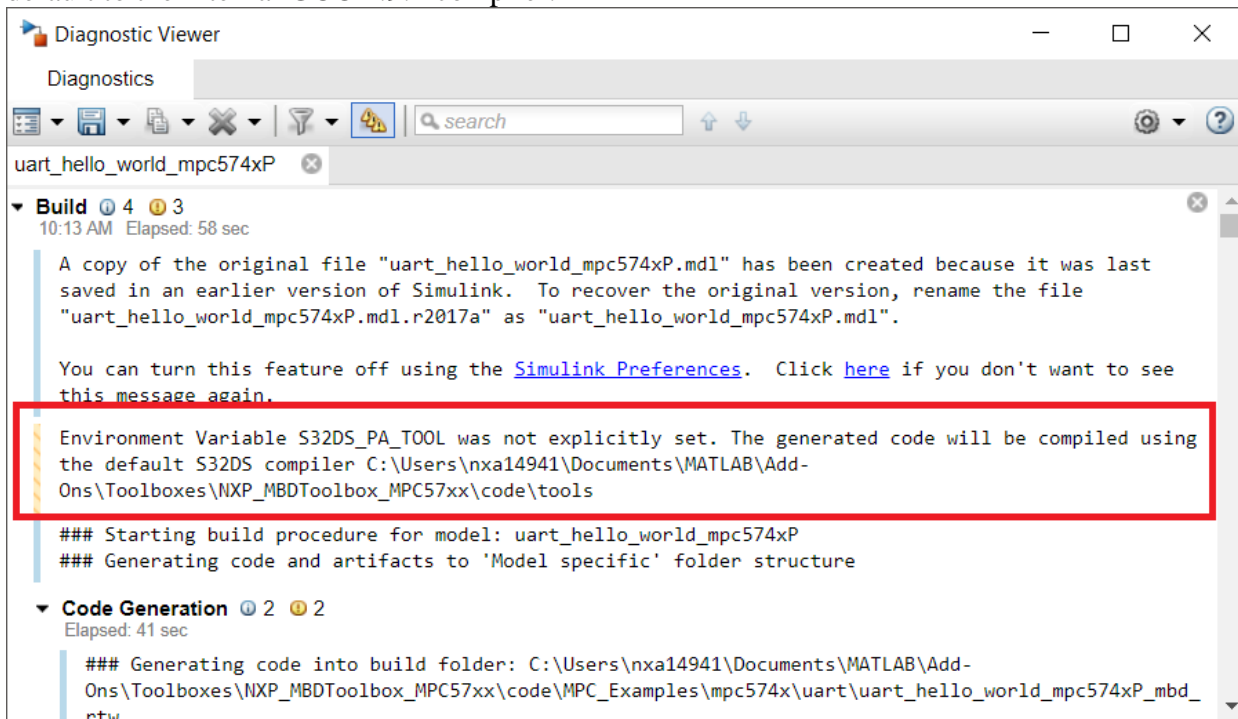
### 1.2.3 Setting up the Target Compilers

The target compiler for the Model-Based Design Toolbox needs to be configured. Use the notation below to set up these compiler environmental variables. Ensure a system environment variable called `<COMPILER_STRING>_TOOL`, corresponding to the compiler(s) you have installed, is defined to compiler path value as shown below:

```
S32DS_PA_TOOL = {Toolbox installation path}/tools or  
                {S32 Design Studio installation path}/  
GHS_TOOL = {GHS installation path}/comp_201714/  
DIAB_TOOL = {DIAB installation path}/diab/5.9.6.2/
```

Note: Paths shown are for illustration, your installation path may be different. Once environmental variables are setup you will need to restart MATLAB for the IDE environment to see these system variables.

In case there is no compiler installed, the NXP's Model-Based Design Toolbox is going to default to the internal GCC 4.9.4 compiler.



### 1.2.4 Setting the Path for Model-Based Design Toolbox

If the toolbox installation as Add-ons was successful, then the MATLAB will automatically detect the NXP's Model-Based Design Toolbox. Nonetheless, in special circumstances, you might need to run a special script to instruct the MATLAB to recognize the NXP's Model-Based Design Toolbox. This is done by changing the MATLAB Current Directory to the toolbox installation directory (e.g.: `..\MATLAB\Add-Ons\Toolboxes\NXP_MBDToolbox_MPC57xx\code`) and running the "mbd\_mpc\_path" script.



```
>> mbd_mpc_path
Treating 'C:\Users\xxxxx\Documents\MATLAB\Add-
Ons\Toolboxes\NXP_MBDToolbox_MPC57xx\code' as MBD Toolbox installation
root.
MBD Toolbox path prepended.
Successful.
>>
```

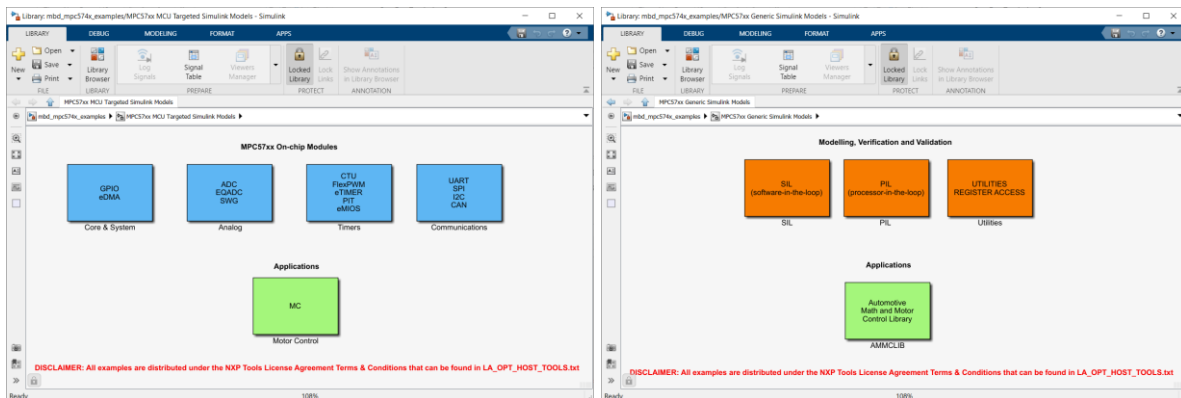
## 2 Run Models

### 2.1 Examples Library & Help

NXP's Model-Based Design Toolbox comes with an Examples Library collection that lets you test different MCU on-chip modules and run complex applications.

The Examples Library can be opened from “{Model Based Design Install Directory}\MPC\_Examples\” folder.

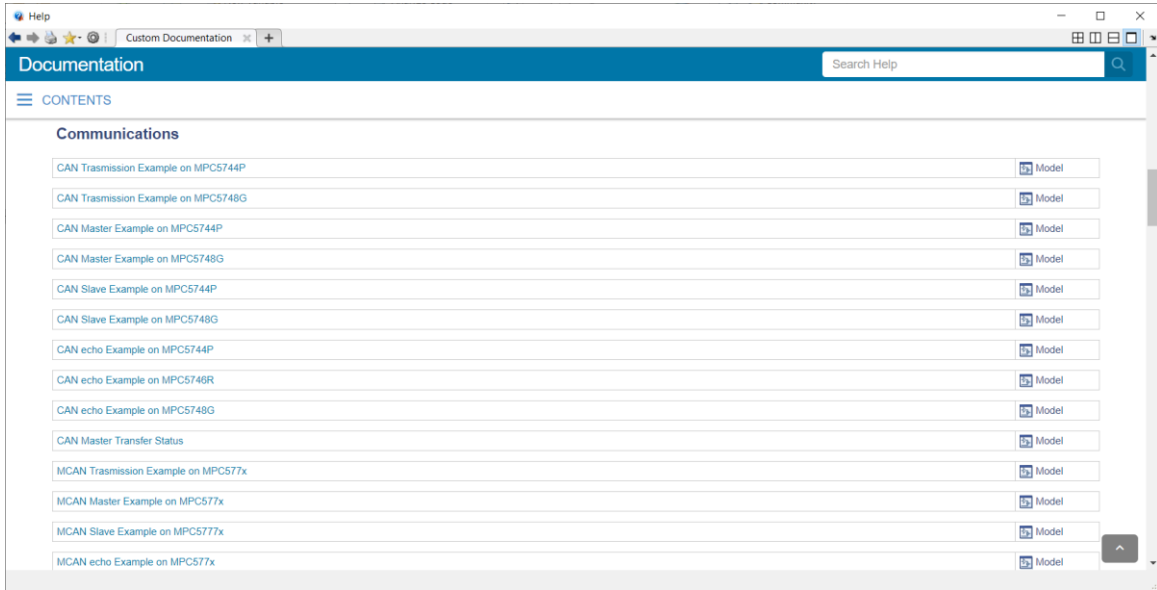
Note: the example library is divided into two sections: custom & generic examples. The generic examples can be executed on all the processors and boards supported with none or minimal changes. The custom examples are targeted for a specific processor and board and are highly dependent on peripherals and pins available.



Each category contains multiple examples that showcase different Model-Based Design Toolbox capabilities that are clarified in three layers:

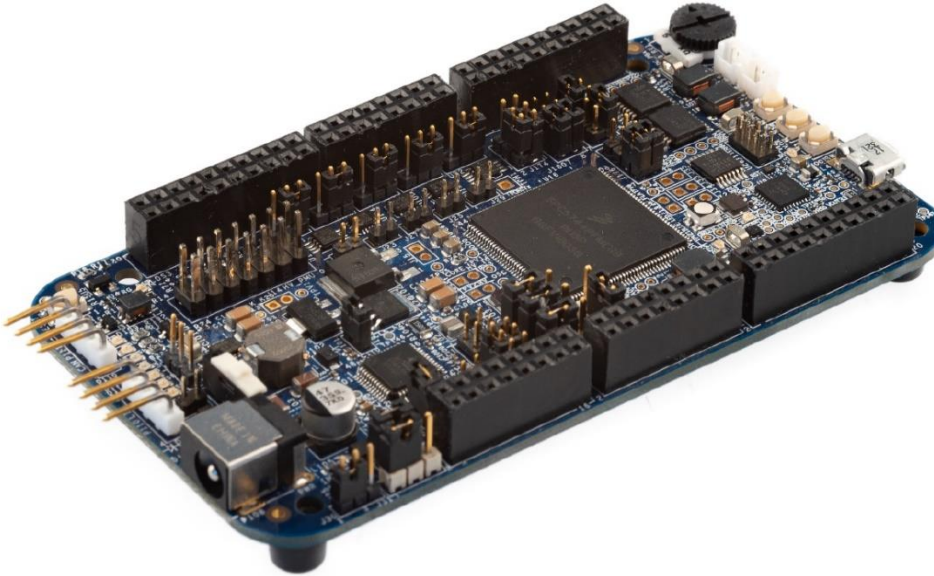
- **On-chip modules** and peripherals examples cover the basic functionalities of the MCU;
- **Modeling, Verification and Validation** examples cover the SIL, PIL and additional blocks supported by toolbox to help faster prototyping;
- **Applications** cover the AMMCLIB and Motor Control scenarios;

The examples are also available from standard MATLAB Help for NXP's Model-Based Design Toolbox Example



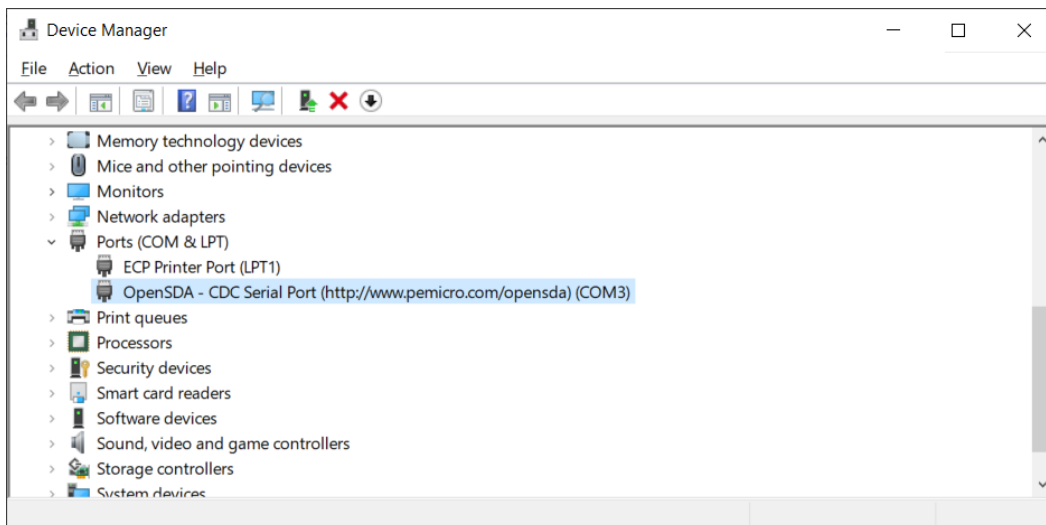
## 2.2 Hardware Setup

All examples provided with the Model-Based Design Toolbox were developed on DEVKIT-MPC5744P as the primary target. Additional information about this development kit can be found on NXP official web page [here](#).



Before running any example on the DEVKIT-MPC5744P a proper communication [setup](#) between the board and the host PC must be enabled. Please follow the next steps to ensure a working setup:

1. Place J43/J44/J45 jumpers on positions 1-2 to power the DEVKIT-MPC5744P via the USB micro connector;
2. Connect the EVB micro USB connector J12 to a host PC USB connector using supplied USB cable;
3. Allow the PC to automatically configure the USB drivers if needed. Windows OS should automatically detect the DEVKIT-MPC5744P revE and should assign a virtual COM port to the host;

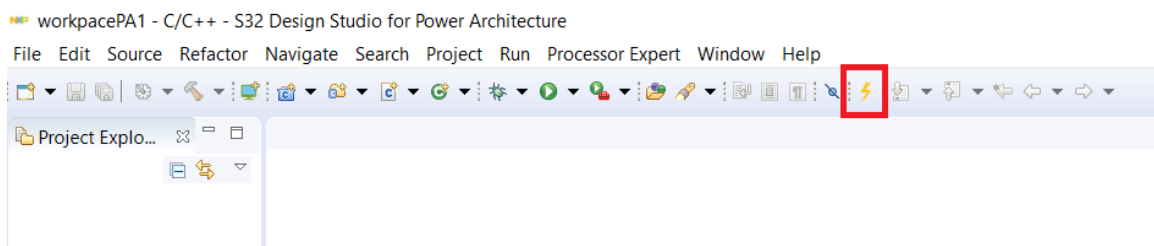


4. When powered through USB, LEDs DS1, DS2 and DS5 should light green;

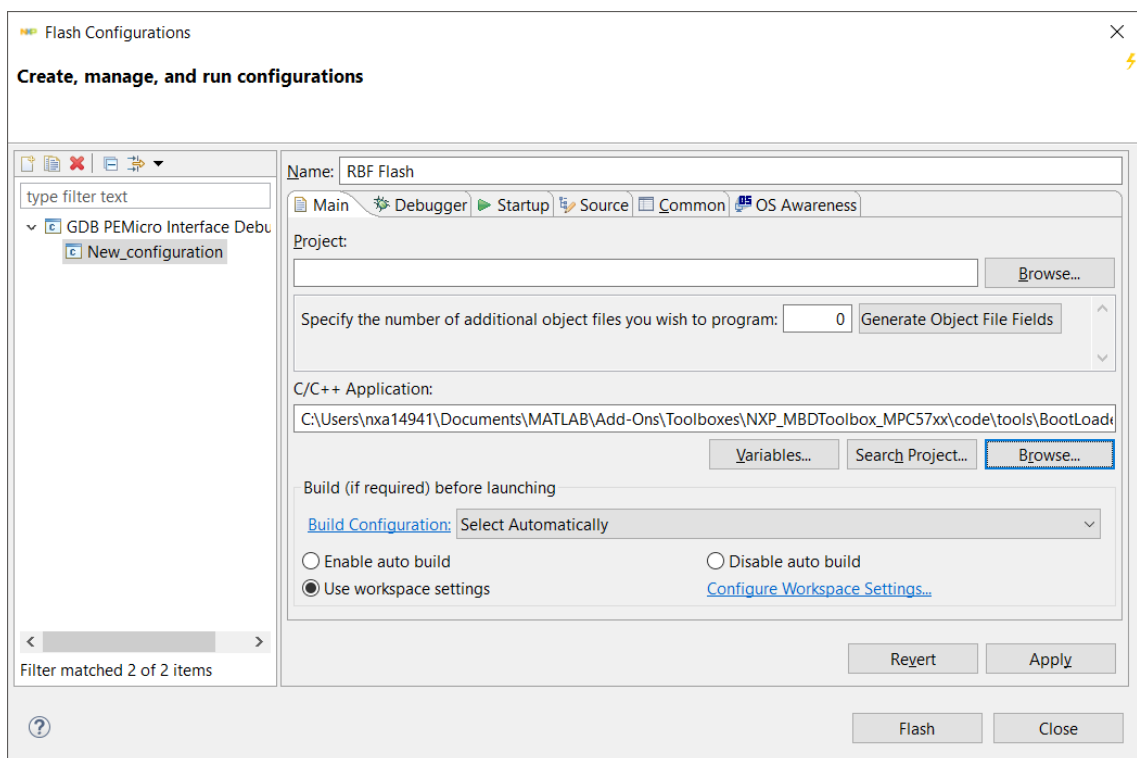
## 2.3 BootLoader Setup

To be able to download the applications from MATLAB/Simulink to the target we need to program a special application called RBF into the MCU flash memory. For the first time programming, you need to have the [S32 Design Studio for PA IDE](#) installed. Follow the next steps to flash the RBF image to the processor flash memory.

1. Click on the **Flash icon** to open the wizard that allows you to connect with the target and flash the boot loader algorithm



2. The Flash Wizard will appear on your screen. Add a **new** configuration and name it RBF Flash.



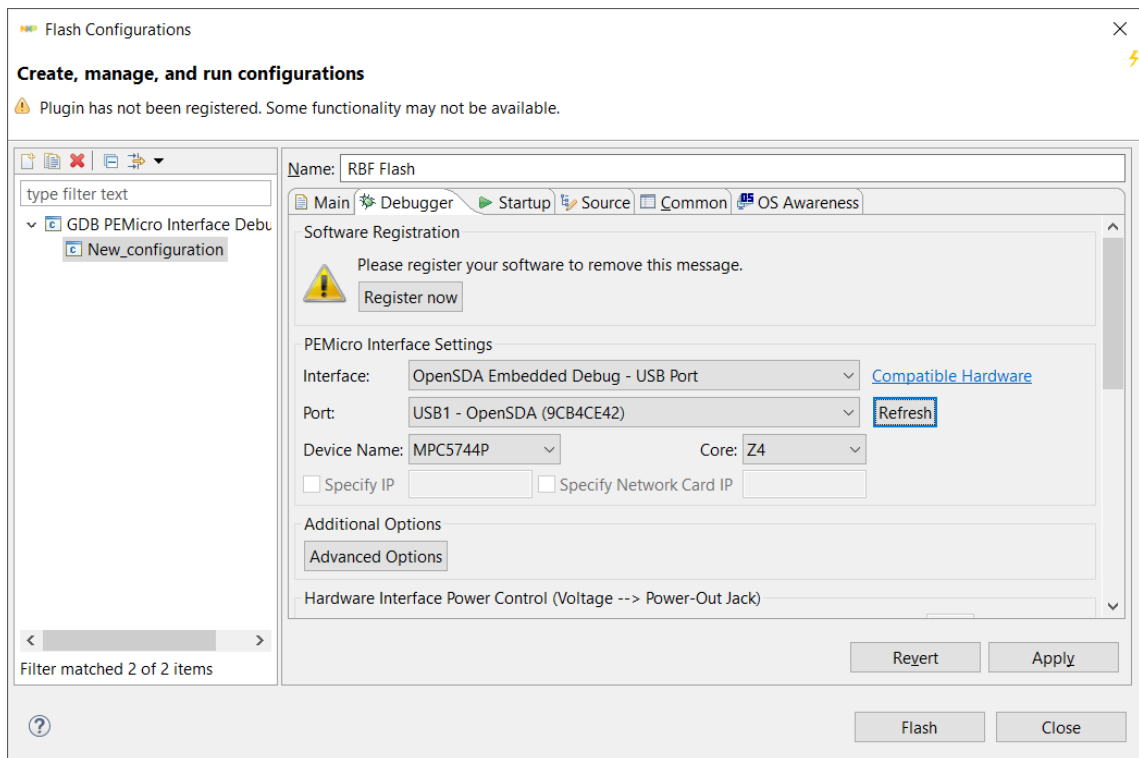
3. Click on the **C/C++ Application Browse** button to navigate to the {Model-Based Design Toolbox installation folder}\code\tools\BootLoader\RBF\_Files and choose the appropriate RBF image to be flashed on your setup.

Note: each file contains in its name the interfaces allowed for Flash Tool download communication. Choose the one that is suitable for your processor and communication

interface. In this case, we are going to use the UART0 (openSDA) to download the code from the host PC to the DEVKIT-MPC5744P revE board.

| Name                                       | Date modified      | Type      | Size  |
|--|--------------------|-----------|-------|
| MPC574xP_S32DS_UART0_CAN0_OpenSDA_RevE.rbf | 12/18/2019 2:40 PM | RBF File  | 17 KB |
| MPC574xP_S32DS_UART1_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 43 KB |
| MPC574xP_S32DS_UART1_CAN0_OpenSDA.rbf      | 2/14/2019 3:34 PM  | RBF File  | 43 KB |
| MPC5744B_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 45 KB |
| MPC5744C_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 45 KB |
| MPC5745B_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 45 KB |
| MPC5745C_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 45 KB |
| MPC5746B_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 45 KB |
| MPC5746C_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 45 KB |
| MPC5746G_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 46 KB |
| MPC5746R_20MHz.rbf                         | 3/16/2020 9:42 AM  | RBF File  | 36 KB |
| MPC5747C_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 46 KB |
| MPC5747G_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 46 KB |
| MPC5748C_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 46 KB |
| MPC5748G_S32DS_UART2_CAN0.rbf              | 2/14/2019 3:34 PM  | RBF File  | 46 KB |
| MPC5777C_S32DS_UART0_CAN0.srec             | 12/18/2019 2:40 PM | SREC File | 46 KB |

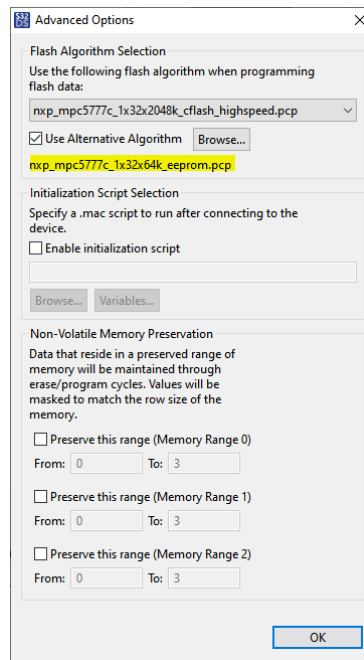
#### 4. Configure the **Debugger** interface to connect with the target.



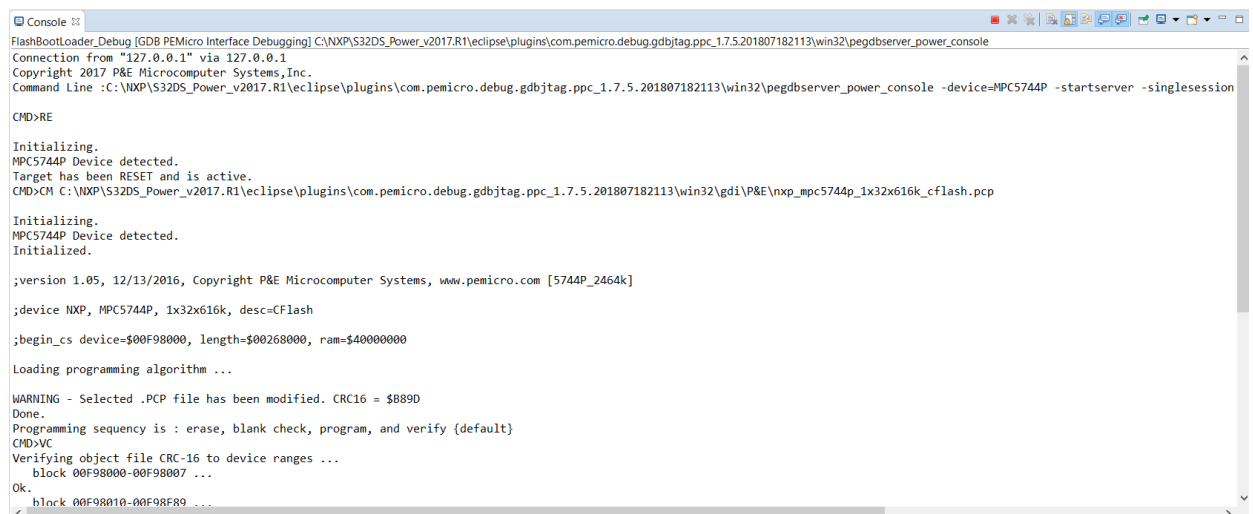
5. **Only for MPC5775B/E and MPC5777C**, the flashing algorithm must be changed. In the Flash configuration window (previous point 4), press the Advanced Options button. In the newly opened window, check the “Use Alternative Algorithm” checkbox and press the Browse button.

Select

C:\NXP\S32DS\_Power\_v2.1\eclipse\plugins\com.pemicro.debug.gdbjtag.ppc\_1.9.9.201907200403\win32\gdi\P&E path and choose the nxp\_mpc5777c\_1x32x64k\_eeeprom.pcp file.



6. Click on the **Flash** button to start the flash programming sequence. The debugger will connect with the target selected and will start to flash the RBF image into the non-volatile memory of the target.

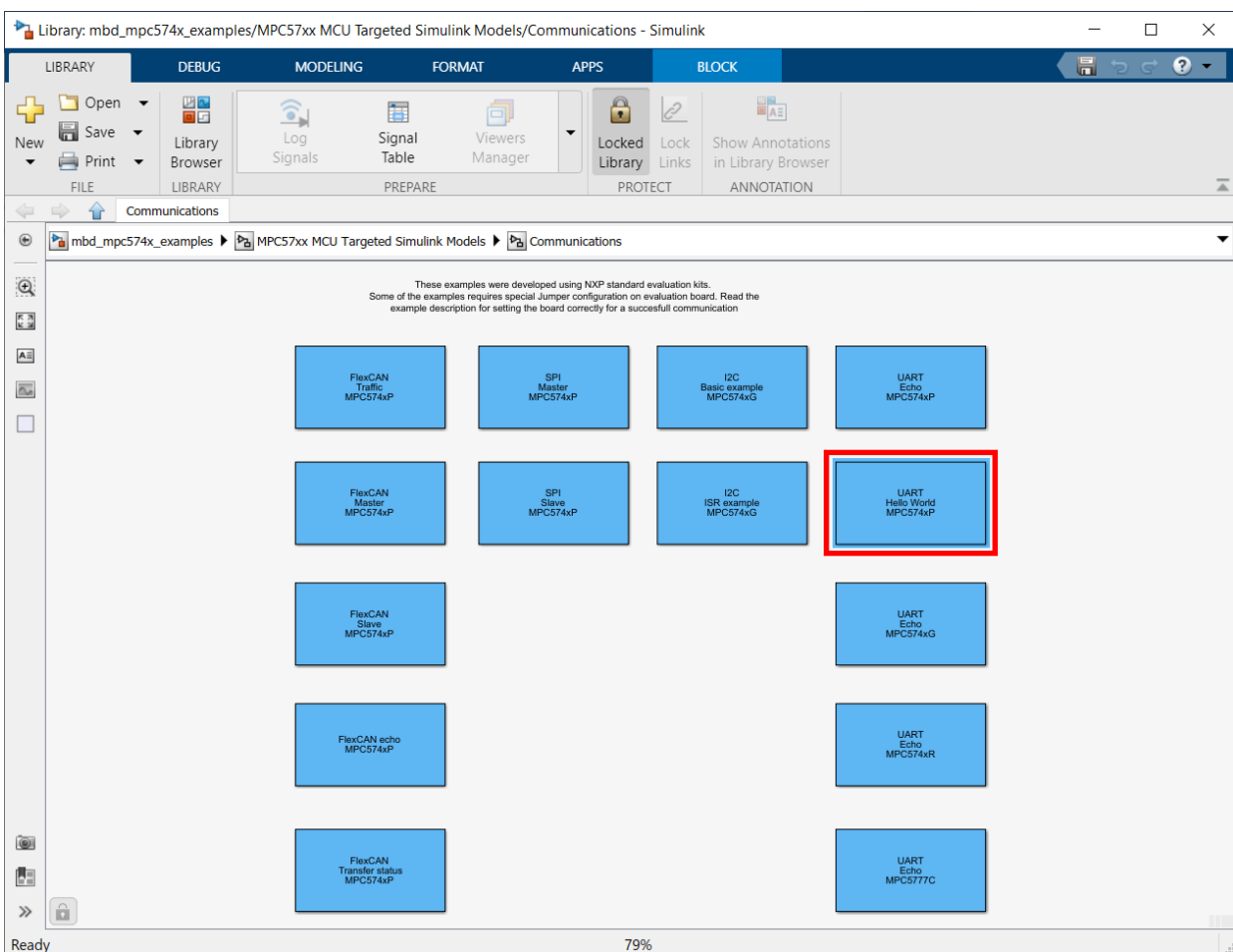


At this point, the target should be ready for receiving applications from MATLAB/Simulink environment over the UART interface connected via OpenSDA.

## 2.4 Hello World Example

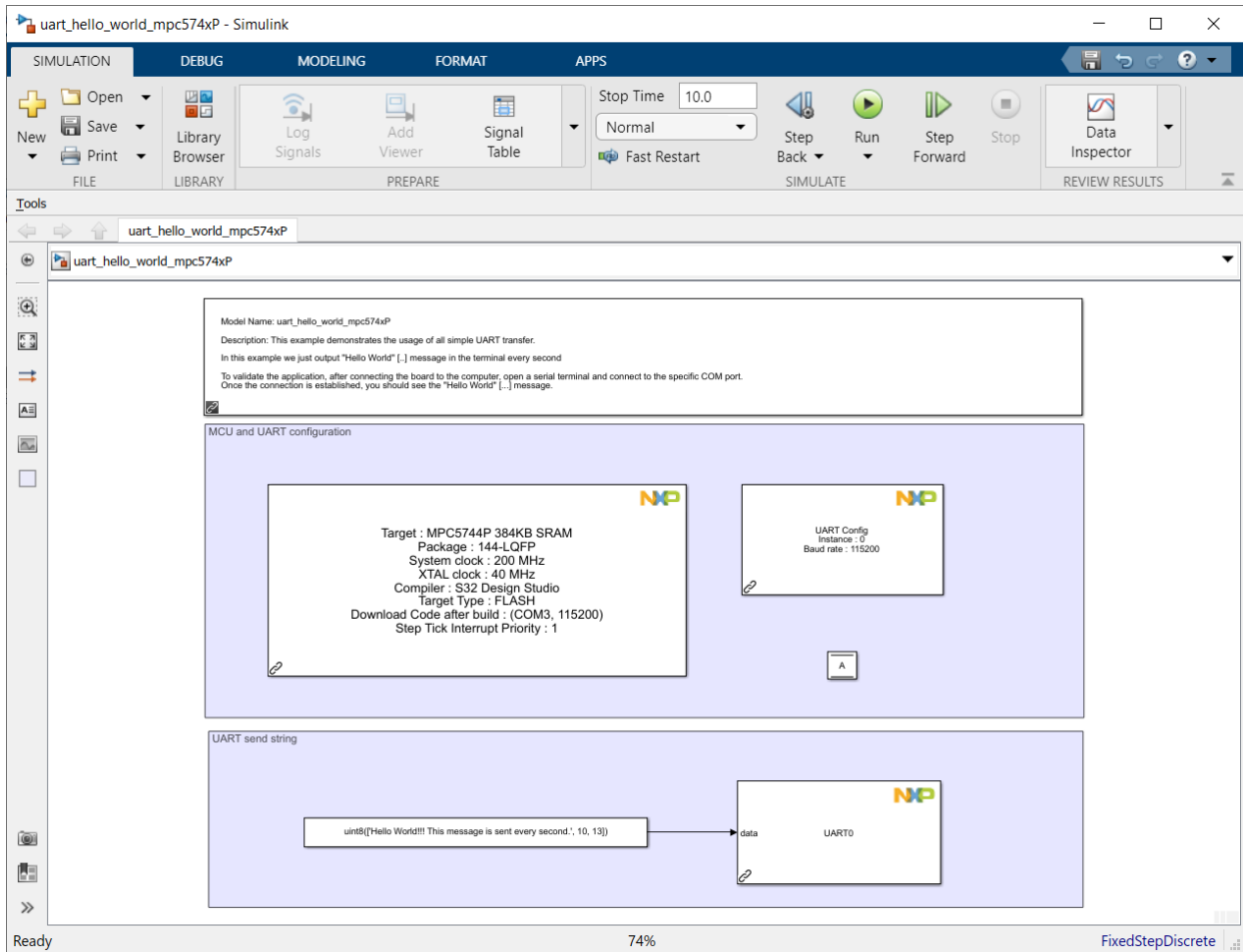
If the hardware and BootLoader setup is completed successfully and a virtual COM port is created and visible in Control Panel -> Device Manager -> Port (COM & LPT), then all requirements for running a Model-Based Design Toolbox for MPC57xx Examples are fulfilled.

Open the Examples Library and go to Communications block and double click on UART Hello World.



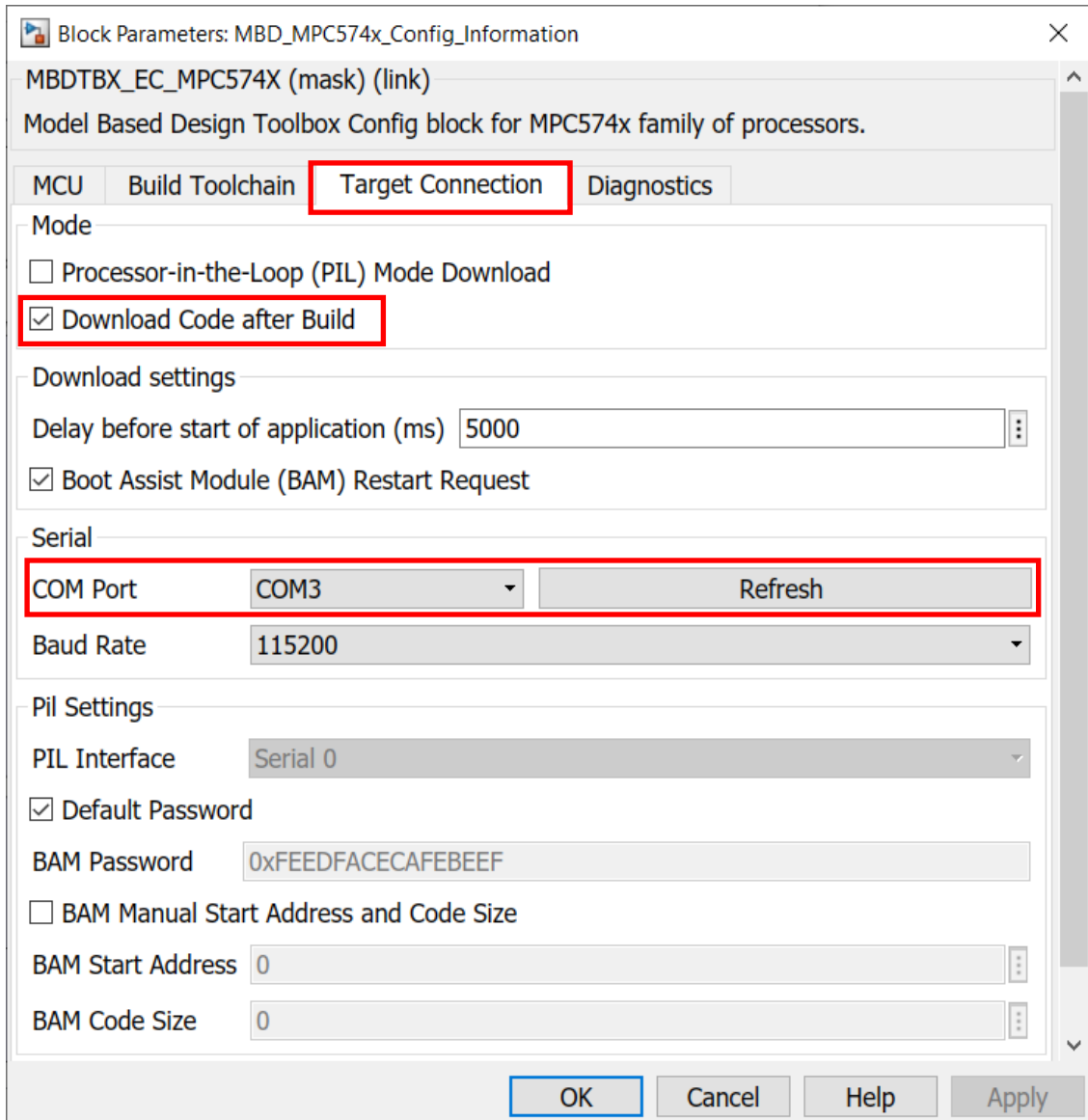
The Simulink `uart_hello_world_mpc574xP.mdl` model will open. This model programs the MPC5744P MCU to send a message over the UART.





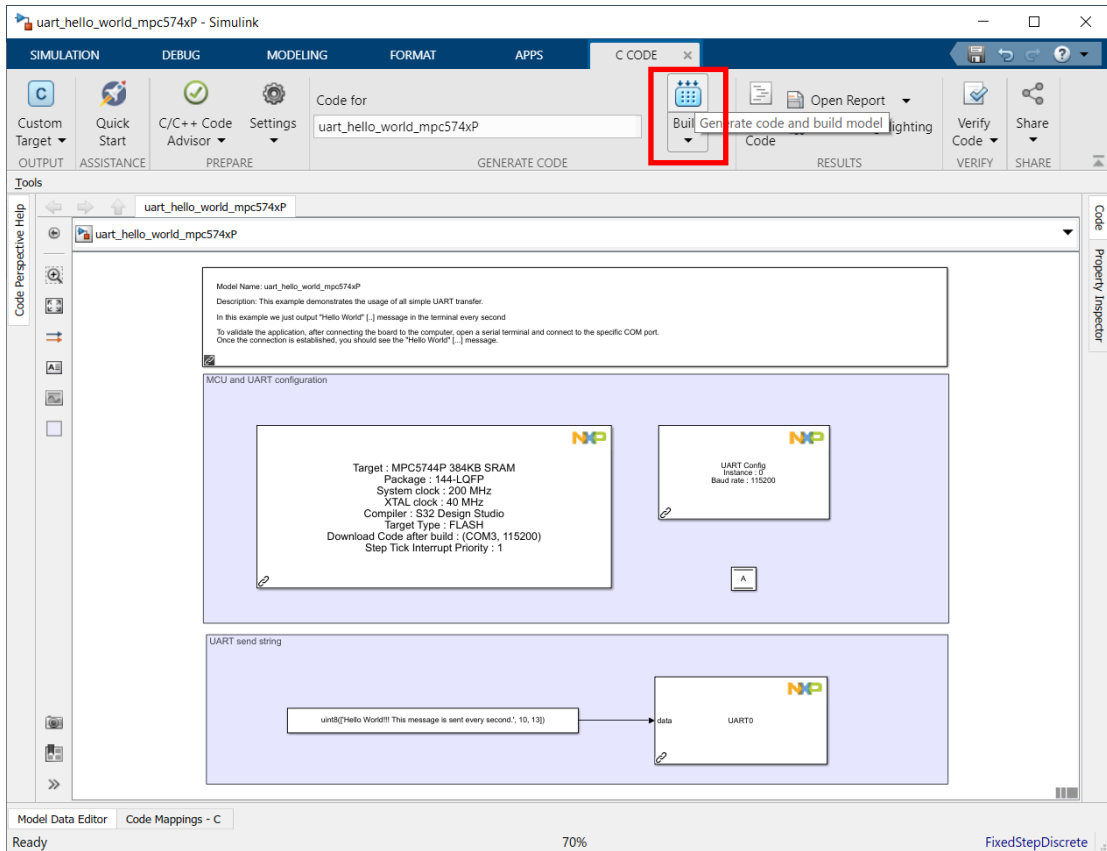
Follow the next steps to run the example:

1. Double click on MBD\_MPC574x\_Config\_Information block and set up the Download Config parameters according to with your PC and HW setup

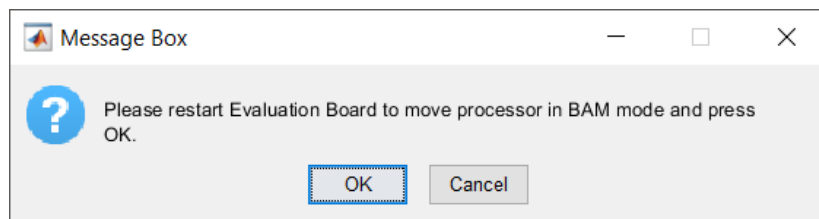


2. Apply and close this window.

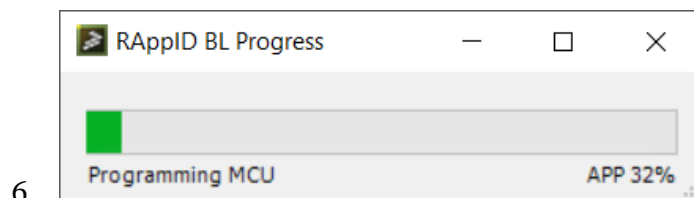
- Press the **Build Model** button and wait until the code is generated, compiled and downloaded to the evaluation board.



- Wait until the application is built and the following message is displayed on the screen. Press the board reset button and then (within 5 seconds) press the OK button to start the application programming to the target.

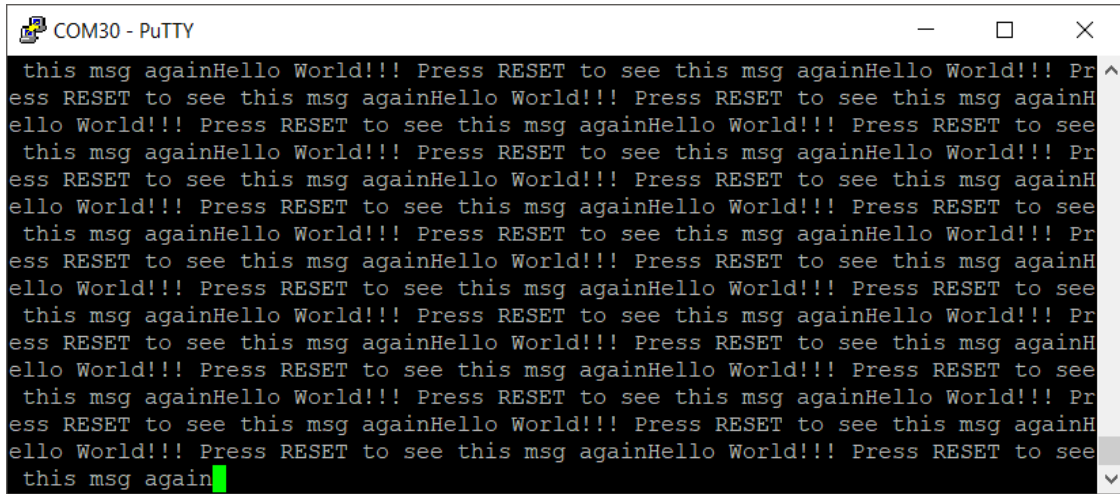


- Wait until the BootLoader finishes the flashing of the application to the target processor.



- Open any UART terminal for the virtual COM port assigned and set up the baud rate at 115200, data bits 8 and parity none.
- Press the reset button on the evaluation board.

9. The MPC5744P MCU sends “Hello World!!! Press RESET to see this msg again” message over the UART and the UART terminal should display it.



The image shows a screenshot of a PuTTY terminal window titled "COM30 - PuTTY". The terminal displays a repeating message: "this msg againHello World!!! Press RESET to see this msg again". The message is repeated multiple times, with a green cursor at the end of the last line. The terminal window has standard window controls (minimize, maximize, close) in the top right corner.

Congratulations! You succeeded with running your first example created with Model-Based Design Toolbox for MPC57xx

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