

NVIC_SetPriority **FIX**

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2:24 PM

```
#if CPU_COMPONENTS_INIT
void Components_Init(void)
{

    /*! gpio1 Auto initialization start */
    GPIO_DRV_Init(gpio1_InpConfig1,gpio1_OutConfig1);
    /*! gpio1 Auto initialization end */
    /*! uartCom0 Auto initialization start */
    OSA_InstallIntHandler(UART0_RX_TX_IRQn, UART0_VP12_IRQHandler);
    UART_DRV_Init(FSL_UARTCOM0,&uartCom0_State,&uartCom0_InitConfig0);
    UART_DRV_InstallRxCallback(FSL_UARTCOM0, uartCom0_RxCallback, uart0RxBuff, NULL, true);
    NVIC_SetPriority(UART0_RX_TX_IRQn, 8U);
    /*! uartCom0 with DMA Auto initialization end */
    /*! uartCom1 Auto initialization start */
    OSA_InstallIntHandler(UART1_RX_TX_IRQn, UART1_VP12_IRQHandler);
    UART_DRV_Init(FSL_UARTCOM1,&uartCom1_State,&uartCom1_InitConfig0);
    UART_DRV_InstallRxCallback(FSL_UARTCOM1, uartCom1_RxCallback, uart1RxBuff, NULL, true);
    NVIC_SetPriority(UART1_RX_TX_IRQn, 8U);
    /*! uartCom1 with DMA Auto initialization end */
    /*! i2cCom0 Auto initialization start */
    OSA_InstallIntHandler(I2C0_IRQn, i2cCom0_IRQHandler);
    I2C_DRV_MasterInit(FSL_I2CCOM0, &i2cCom0_MasterState);
    I2C_DRV_MasterSetBaudRate(FSL_I2CCOM0, &i2cCom0_MasterConfig0);
    NVIC_SetPriority(I2C0_IRQn, 6U);
    /*! i2cCom0 Auto initialization end */
    /*! i2cCom2 Auto initialization start */
    OSA_InstallIntHandler(I2C2_IRQn, i2cCom2_IRQHandler);
    I2C_DRV_MasterInit(FSL_I2CCOM2, &i2cCom2_MasterState);
    I2C_DRV_MasterSetBaudRate(FSL_I2CCOM2, &i2cCom2_MasterConfig0);
    NVIC_SetPriority(I2C2_IRQn, 6U);
    /*! i2cCom2 Auto initialization end */
    /* ### XFormat "XF1" init code ... */
}
#endif /* CPU_COMPONENTS_INIT */
```