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Layerscape Software Development Kit v19.09

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Layerscape Software Development Kit User Guide Supports: LSDK 19.09-update-311219

Last updated December 30 2019

About This Document

About QorIQ Layerscape Software Development Kit (LSDK)

LSDK is a complete Linux kit for NXP QorIQ Arm-based SoC's and the reference and evaluation boards that are available for them.

It is a *hybrid form* of a Linux distribution because it combines the following major components to form a complete Linux system.

- NXP firmware components including:
 - Trusted Firmware-A (TF-A), a reference implementation of secure world software for Armv7-A and Armv8-A.
 - NXP peripheral firmware components for DPAA1, DPAA2, and PPFE.
- NXP boot loaders. Two are offered:
 - U-Boot, based on denx.de plus patches.

LSDK 19.09 Generation

<https://www.nxp.com/design/software/embedded-software/linux-software-and-development-tools/layercape-software-development-kit-v19.09:LAYERSCAPE-SDK>

```
$ tar xvzf flexbuild_lsdk1909_update_221019.tgz  
$ cd flexbuild_lsdk1909_update_221019  
$ source setup.env  
$ flex-builder -h
```

Two main commands

flex-builder

commands to make and build the images to be downloaded on LS evaluation board.

flex-installer

to install generated or downloaded Linux on the SD or on the board itself.

flex-builder

Usage: flex-builder [-c <component>] [-m <machine>] [-a <arch>] [-b <boottype>]
or: flex-builder [-i <instruction>] [-m <machine>] [-a <arch>] [-b <boottype>]

Most used example with autobuild:

```
flex-builder -m ls1046ardb -a arm64 # auto build all firmware, linux, apps components and LSDK userland for ls1046ardb
flex-builder -i auto -a arm64 # auto build all firmware, linux, apps components and LSDK userland for all arm64 machines
```

Most used example with separate command:

```
flex-builder -i mkrfcs # generate Ubuntu main arm64 userland by default
flex-builder -i mkrfcs -r ubuntu:mate # generate Ubuntu-Mate arm64 GUI desktop userland
flex-builder -i mkrfcs -r yocto:tiny # generate Yocto-base arm64 tiny userland
flex-builder -i mkrfcs -r centos # generate CentOS arm64 userland
flex-builder -i mklinux -a arm64 # generate lsdk_linux_arm64_LS_tiny.itb including rootfs_yocto_arm64_tiny.cpio.gz
flex-builder -c linux -a arm64 # build linux component with default linux repo and default branch/tag for all arm64 machines
flex-builder -c atf -m ls1046ardb -b sd # build ATF images for SD boot on LS1046ardb
flex-builder -i mkfw -m ls1046ardb -b sd # generate composite firmware for SD boot on ls1046ardb
flex-builder -i mkbootpartition -a arm64 # generate boot partition tarball applicable for a variety of userland used on arm64 platforms
flex-builder -c apps -a arm64 # build all apps components (dpdk, fmc, restool, optee_os, secure_obj, edgescale, etc) for arm64
flex-builder -i merge-component -a arm64 # merge all components packages and kernel modules into target userland
flex-builder -i packrfcs -a arm64 # pack and compress target userland as .tgz
flex-builder -i download -m ls1043ardb # download prebuilt userland
flex-builder -i list # show the list of enabled config, machines and components
flex-builder -i repo-fetch # fetch all git repositories of components from remote repos if not exist locally
flex-builder -i repo-update # update all components to the latest TOP commits of current branches
flex-builder docker # create or attach to Ubuntu docker container to run Flexbuild in docker
flex-builder clean # clean all previously generated images except distro rootfs, optionally
```

Most used options:

```
-m, --machine target machine, supports ls1012zfrwy,ls1021atwr,ls1028ardb,ls1043ardb,ls1046ardb,ls1088ardb_pb,ls2088ardb,lx2160ardb, etc
-a, --arch target arch of processor, valid argument: arm64, arm64:be, arm32, arm32:be, ppc64, ppc32, arm64 by default
-b, --boottype type of boot media, valid argument: nor, sd, emmc, qspi, xspi, nand, default all types if unspecified
-c, --component component to be built, valid argument: firmware, apps, linux, uboot, atf, rcw, mc_utils, restool,
edgescale, fmc, openssl, vpp, dpdk, ovs_dpdk, pktgen_dpdk, openstack_nova, optee_os, libpkcs11, secure_obj, etc
-r, --rootfs specify flavor of target rootfs, valid argument: ubuntu|yocto|centos:main|devel|lite|tiny|edgescale|cloud
-i, --instruction instruction to do for dedicated operation
-s, --secure enable security feature in case of secure boot
```

See docs/flexbuild_usage.txt and docs/lsdk_build_install.txt for more information about the available commands.

Available from shell linux command prompt once source setup.env

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flex-installer

Usage: flex-installer [-i <instruction>] [-b <bootpartition>] [-r <rootfs>] [-f <firmware>] [-d <device>] [-m <machine>]

OPTION:

- i, --instruction Instruction to execute, valid argument as below:
 - 'auto' Automatically partition and format the target storage drive, then download and install distro images
 - 'pf' Only partition and format the target storage drive without installing distro images
 - 'download' Only download distro images without installation
 - 'install' Only install the specified image, can be omitted by default
 - 'list' Show the list of supported machines and installation environment
 - 'mksdcard' Create sdcard.img including composite firmware and distro images
- b, --bootpart Boot partition image to be programmed into SD/USB/SATA storage drive
- r, --rootfs The first distro rootfs image by default to be programmed into target storage drive
- R, --rootfs2 The second distro rootfs image for dual distros installation
- d, --device Device name of the target SD/USB/SATA storage drive in Linux
- p, --partition Specify configurable partitions of target disk, default as "-p 4P=100M:1G:6G:-1" if not specified
- f, --firmware Composite firmware to be programmed into SD card
- F, --force Force partition and format target disk regardless of the data in disk
- e, --efi Used for the case of UEFI as bootloader instead of U-Boot, valid argument: dtb or acpi
- m, --machine Target machine name to specify the name of composite firmware for automatical deployment
- u, --url Specify URL of distro webserver to override the default one for automatically downloading distro
- v, --version Print version info
- h, --help Print help info

*Available from shell linux command prompt once **source setup.env***

flex-installer

Examples:

- Automatically download aaauto -m ls1046ardb -d /dev/mmcblk0 (default latest LSDK distro)

```
$ flex-installer -i auto:lsdk1906 -m lx2160ardb -d /dev/sdx (specify LSDK version)
```

You can specify one or several of '-b <bootpartition> -r <rootfs> -R <second-rootfs> -f <firmware> -u <url>' options to override the default settings

- Install local distro images with single distro:

```
$ flex-installer -b bootpartition_arm64_lts_4.19.tgz -r rootfs_lsdk1906_LS_arm64_main.tgz -f firmware_ls1046ardb_uboot_sdboot.img -d /dev/sdx
```

- Install local distro images with dual distros:

```
$ flex-installer -b bootpartition_arm64_lts_4.19.tgz -r rootfs_lsdk1906_LS_arm64_main.tgz -R rootfs_buildroot_LS_arm64_devel.tgz -f <firmware> -d /dev/sdx
```

(run 'setenv devpart_root 3;boot' in U-Boot to boot the second distro from partition 3)

- On ARM board running TinyDistro, first partition target disk, then download local distro images onto board and install as below:

```
$ flex-installer -i pf -d /dev/mmcblk0 (or /dev/sdx)
```

```
$ cd /run/media/mmcblk0p3 nd install LSDK distro images to target storage drive on host machine or ARM board:
```

```
$ flex-installer -i (or sdx3) and download distro images to this partition via wget or scp
```

```
$ flex-installer -b bootpartition_arm64_lts_xx.tgz -r rootfs_lsdk1906_LS_arm64_main.tgz -d /dev/mmcblk0 (or /dev/sdx)
```

- Only download distro images:

```
$ flex-installer -i download -m ls1046ardb
```

- only install composite firmware:

```
$ flex-installer -f firmware_lx2160ardb_uboot_sdboot.img -d /dev/mmcblk0 (or /dev/sdx)
```

- Install distro into sdcard.img with loop device

```
$ flex-installer -i mkcard -m ls1046ardb
```

Note: '-e dtb' or '-e acpi' option is needed if UEFI is used as bootloader, no need in case of U-Boot.

*Available from shell linux command prompt once **source setup.env***

References

- Basic flexbuild usage instructions in the sources: flexbuild/docs
 - [Layerscape Software Development Kit User Guide 19.09](#) (REV 19.09_311219) updated
- Plenty of git resources online
 - Basic one: <http://rogerdudler.github.io/git-guide/>