

ES_LPC11U6x

Errata sheet LPC11U6x

Rev. 1.1 — 28 July 2014

Errata sheet

Document information

Info	Content
Keywords	LPC11U66JBD48; LPC11U67JBD48; LPC11U67JBD64; LPC11U67JBD100; LPC11U68JBD48; LPC11U68JBD64; LPC11U68JBD100; LPC11U6x errata
Abstract	This errata sheet describes both the known functional problems and any deviations from the electrical specifications known at the release date of this document. Each deviation is assigned a number and its history is tracked in a table.



Revision history

Rev	Date	Description
1.1	20140728	<ul style="list-style-type: none">• Corrected USB_ROM.1 work-around.• Corrected part marking information.• Parts added: LPC11U67JBD100, LPC11U67JBD64, LPC11U66JBD48.
1	20140115	Initial version.

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1. Product identification

The LPC11U6x devices typically have the following top-side marking for LQFP100 packages:

LPC11U6xJBD100
 xxxxxx xx
 xxxyywwxR[x]

The LPC11U6x devices typically have the following top-side marking for LQFP64 packages:

LPC11U6xJ
 xxxxxx xx
 xxxyywwxR[x]

The LPC11U6x devices typically have the following top-side marking for LQFP48 packages:

LPC11U6xJ
 xx xx
 xxxyy
 wwR[x]

Field 'yy' states the year the device was manufactured. Field 'ww' states the week the device was manufactured during that year.

Field 'R' identifies the device revision. This Errata Sheet covers the following revisions of the LPC11U6x:

Table 1. Device revision table

Revision identifier (R)	Revision description
'A'	Initial device revision

2. Errata overview

Table 2. Errata summary table

Functional problems	Short description	Revision identifier	Detailed description
USB_ROM.1	The USB ROM driver routine hwUSB_ResetEP() accidentally corrupts the subsequent word of memory while clearing the STALL bit of the selected endpoint.	'A'	Section 3.1
USB_ROM.2	The USB ROM stack doesn't split EP0 transfer into multiple packets of 8 bytes (MAXP allowed) in low speed mode.	'A'	Section 3.2

Table 3. AC/DC deviations table

AC/DC deviations	Short description	Revision identifier	Detailed description
n/a	n/a	n/a	n/a

Table 4. Errata notes table

Errata notes	Short description	Revision identifier	Detailed description
n/a	n/a	n/a	n/a

3. Functional problems detail

3.1 USB_ROM.1

Introduction:

The on-chip USB2.0 full-speed device controller uses the USB endpoint (EP) Command/Status List organized in memory to store the EPs command/status information. Bit 29 indicates the STALL status of the corresponding EP. The USB ROM driver routine `hwUSB_ResetEP()`, which is called during `SET_CONFIGURATION` and `SET_INTERFACE` requests for all EPs present in the corresponding configuration/interface, clears the STALL bit of the selected EPs in Command/Status List as part of EP reset procedure.

Problem:

During the EP reset procedure executed by the USB ROM driver routine `hwUSB_ResetEP()`, it not only clears the STALL bit of the selected EP but also corrupts the subsequent word of memory. This issue is caused by a software bug in the `hwUSB_ResetEP()` routine.

Below is a summary of the runtime errors resulting from this issue:

- Case 1. When reset procedure is invoked on an EP which is at the end of the EP list, this bug will accidentally corrupt the memory area following the EP Command/Status List. In the current version of USB ROM driver this area is used for storing the receiver buffer address for control endpoint (EP0). This corruption causes erratic behavior on control OUT transaction.
- Case 2. When reset procedure is invoked on an EP which is in the beginning or middle of the EP list, this bug will accidentally clear the STALL bit of the subsequent EP in list.
 - If `hwUSB_ResetEP()` is called during `SET_CONFIGURATION`, clearing the STALL bit of the subsequent EP has no consequence since STALL condition is cleared for all EPs during `SET_CONFIGURATION` procedure.
 - If `hwUSB_ResetEP()` is called during `SET_INTERFACE` when selecting an ALT interface, this issue could clear STALL condition (if exists) on the subsequent EP. This condition is very rare.

Work-around:

The software work-around to address Case 1 is to specify one extra EP in the `max_num_ep` field of the `USBD_API_INIT_PARAM_T` structure passed to the ROM driver's `hw->init()` routine. This extra EP provides a padding buffer to avoid corruption to the subsequent word of memory. This workaround is demonstrated with the line of code highlighted in red in function `usb_init()` in the following example.

If your system is affected with Case 2, user should check the "ep_halt" member of `USB_CORE_CTRL_T` structure in the `SET_INTERFACE` event and set STALL bit for any EP which got cleared due to this bug. This condition is very rare. This workaround is demonstrated with the function `StallWorkAround ()` in the following example. Notice that `StallWorkAround` is set to be an interface event in the `usb_init()` function (highlighted in bold).

```

typedef volatile struct _EP_LIST {
    uint32_t buf_ptr;
    uint32_t buf_length;
} EP_LIST;

ErrorCode_t StallWorkAround(USBD_HANDLE_T hUsb)
{
    ErrorCode_t ret = LPC_OK;
    USB_CORE_CTRL_T *pCtrl = (USB_CORE_CTRL_T *) hUsb;
    EP_LIST *epQueue;
    int32_t i;

    /* WORKAROUND for Case 2:
    Code clearing STALL bits in endpoint reset routine corrupts memory area
    next to the endpoint control data.
    */
    if (pCtrl->ep_halt != 0) { /* check if STALL is set for any endpoint */
        /* get pointer to HW EP queue */
        epQueue = (EP_LIST *) LPC_USB->EPLISTSTART;
        /* check if the HW STALL bit for the endpoint is cleared due to bug. */
        for (i = 1; i < pCtrl->max_num_ep; i++) {
            /* check OUT EPs */
            if ( pCtrl->ep_halt & (1 << i)) {
                /* Check if HW EP queue also has STALL bit = _BIT(29) is set */
                if (( epQueue[i << 1].buf_ptr & _BIT(29)) == 0) {
                    /* bit not set, cleared by BUG. So set it back. */
                    epQueue[i << 1].buf_ptr |= _BIT(29);
                }
            }
            /* Check IN EPs */
            if ( pCtrl->ep_halt & (1 << (i + 16))) {
                /* Check if HW EP queue also has STALL bit = _BIT(29) is set */
                if (( epQueue[(i << 1) + 1].buf_ptr & _BIT(29)) == 0) {
                    /* bit not set, cleared by BUG. So set it back. */
                    epQueue[(i << 1) + 1].buf_ptr |= _BIT(29);
                }
            }
        }
    }

    return ret;
}

/* Initialize USB sub system */
static ErrorCode_t usbd_init(void)
{
    USBD_API_INIT_PARAM_T usb_param;
    USB_CORE_DESCS_T desc;
    ADC_INIT_PARAM_T adc_param;
    ErrorCode_t ret = LPC_OK;

```

```
/* enable clocks and pinmux */
usb_pin_clk_init();

/* initialize USB ROM API pointer. */
g_pUsbApi = (const USBD_API_T *) LPC_ROM_API->usbApiBase;
/* initialize call back structures */
memset((void *) &usb_param, 0, sizeof(USB_D_API_INIT_PARAM_T));
usb_param.usb_reg_base = LPC_USB0_BASE;
/* WORKAROUND for Case 1
For example When EP0, EP1_IN, EP1_OUT and EP2_IN are used we need to specify
usb_param.max_num_ep as 3 here. But as a workaround for this issue specify
usb_param.max_num_ep as 4. So that extra EPs control structure acts as padding
buffer to avoid data corruption. Corruption of padding memory doesn't affect the
stack/program behavior.
*/
usb_param.max_num_ep = 3 + 1;
usb_param.USB_Interface_Event = StallWorkAround;

usb_param.mem_base = USB_STACK_MEM_BASE;
usb_param.mem_size = USB_STACK_MEM_SIZE;

/* Set the USB descriptors */
desc.device_desc = (uint8_t *) &USB_DeviceDescriptor[0];
desc.string_desc = (uint8_t *) &USB_StringDescriptor[0];
/* Note, to pass USBCV test full-speed only devices should have both
descriptor arrays point to same location and device_qualifier set to 0.
*/
desc.high_speed_desc = (uint8_t *) &USB_FsConfigDescriptor[0];
desc.full_speed_desc = (uint8_t *) &USB_FsConfigDescriptor[0];
desc.device_qualifier = 0;

/* USB Initialization */
ret = USBD_API->hw->Init(&g_hUsb, &desc, &usb_param);
if (ret == LPC_OK) {
}
```

3.2 USB_ROM.2

Introduction:

When USB device operates in low-speed mode the maximum packet length (MAXP) for control transfer and interrupt transfers is restricted to 8 bytes. Hence when more than 8 bytes needs to be transferred, the data should be split into multiple 8 byte packets. But the current ROM stack splits the control transfer into multiples of 64 bytes only.

Problem:

Device will not enumerate when used in low-speed mode.

Work-around:

The software work-around for this issue is to override the cases where the ROM stack would queue a large transfer and split them into smaller 8 byte packet transfers. Since low speed USB allows only interrupt endpoints, a workaround for HID class implementation is shown below:

```
static ErrorCode_t HID_LowSpeedPatch(USBD_HANDLE_T hUsb, void *data, uint32_t event)
{
    USB_CORE_CTRL_T *pCtrl = (USB_CORE_CTRL_T *) hUsb;
    USB_HID_CTRL_T *pHidCtrl = (USB_HID_CTRL_T *) data;
    ErrorCode_t ret = ERR_USBD_UNHANDLED;
    uint16_t cnt = 0, len = 0;

    switch (event) {
    case USB_EVT_SETUP:
        if (pCtrl->SetupPacket.bmRequestType.BM.Type == REQUEST_STANDARD) {

            switch (pCtrl->SetupPacket.bRequest) {
            case USB_REQUEST_GET_DESCRIPTOR:
                /* handle HID descriptors first */
                switch (pCtrl->SetupPacket.wValue.WB.H) {
                case HID_HID_DESCRIPTOR_TYPE:
                    pCtrl->EP0Data.pData = pHidCtrl->hid_desc;
                    len = ((USB_COMMON_DESCRIPTOR *)
                        pHidCtrl->hid_desc)->bLength;
                    ret = LPC_OK;
                    break;

                case HID_REPORT_DESCRIPTOR_TYPE:
                    ret = pHidCtrl->HID_GetReportDesc(pHidCtrl,
                        &pCtrl->SetupPacket,
                        &pCtrl->EP0Data.pData, &len);
                    break;

                case HID_PHYSICAL_DESCRIPTOR_TYPE:
                    if (pHidCtrl->HID_GetPhysDesc == 0) {
                        ret = (ERR_USBD_STALL); /* HID Physical Descriptor is not
                            supported */
                    }
                    else {
```



```

        ret = pHidCtrl->HID_GetPhysDesc(pHidCtrl,
        &pCtrl->SetupPacket, &pCtrl->EP0Data.pData, &len);
    }
    break;

    default:
        ret = pCtrl->USB_ReqGetDescriptor(pCtrl);
        break;
    }
    break;

    case USB_REQUEST_GET_CONFIGURATION:
        ret = pCtrl->USB_ReqGetConfiguration(pCtrl);
        break;

    case USB_REQUEST_GET_INTERFACE:
        ret = pCtrl->USB_ReqGetInterface(pCtrl);
        break;

    default:
        break;
    }
}
else if ((pCtrl->SetupPacket.bmRequestType.BM.Type == REQUEST_CLASS) &&
        (pCtrl->SetupPacket.bmRequestType.BM.Recipient ==
REQUEST_TO_INTERFACE) &&
        pCtrl->SetupPacket.bRequest == HID_REQUEST_GET_REPORT) {

    pCtrl->EP0Data.pData = pCtrl->EP0Buf; /* point to data to be sent */
    /* allow user to copy data to EP0Buf or change the pointer to his own
buffer */
    ret = pHidCtrl->HID_GetReport(pHidCtrl, &pCtrl->SetupPacket,
        &pCtrl->EP0Data.pData, &pCtrl->EP0Data.Count);
}
break;

case USB_EVT_IN:
    if (pCtrl->SetupPacket.bmRequestType.BM.Dir == REQUEST_DEVICE_TO_HOST) {
        ret = LPC_OK;
    }
    break;

}
if (ret == LPC_OK) {
    if ((len != 0) && (pCtrl->EP0Data.Count > len)) {
        pCtrl->EP0Data.Count = len;
    }
    cnt = (pCtrl->EP0Data.Count > USB_MAX_PACKET0) ? USB_MAX_PACKET0 :
pCtrl->EP0Data.Count;
    cnt = USB_API->hw->WriteEP(pCtrl, 0x80, pCtrl->EP0Data.pData, cnt);
    pCtrl->EP0Data.pData += cnt;
}

```

```
        pCtrl->EP0Data.Count -= cnt;
    }
    else if (ret == ERR_USBD_UNHANDLED) {
        ret = g_defaultHidHdlr(hUsb, data, event);
    }

    return ret;
}
```

To install this patch handler do the following:

1. declare a global variable: static USB_EP_HANDLER_T g_defaultHidHdlr;
2. install the override handler during initialization phase:

```
ret = USBD_API->hid->init(hUsb, &hid_param);
if (ret == LPC_OK) {
    g_defaultHidHdlr = pCtrl->ep0_hdlr_cb[pCtrl->num_ep0_hdls - 1];
    /* store the default CDC handler and replace it with ours */
    pCtrl->ep0_hdlr_cb[pCtrl->num_ep0_hdls - 1] = HID_LowSpeedPatch;
    ....
}
```

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5. Contents

1	Product identification	3
2	Errata overview	3
3	Functional problems detail	5
3.1	USB_ROM.1	5
3.2	USB_ROM.2	8
4	Legal information	11
4.1	Definitions	11
4.2	Disclaimers	11
4.3	Trademarks	11
5	Contents	12

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