

# WORKSHOP - USING SERIAL BOOTLOADER EXAMPLE

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26, APRIL, 2016



EXTERNAL USE

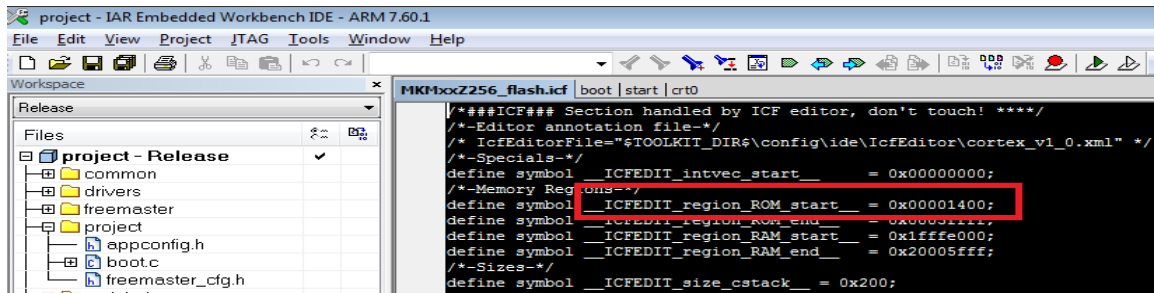


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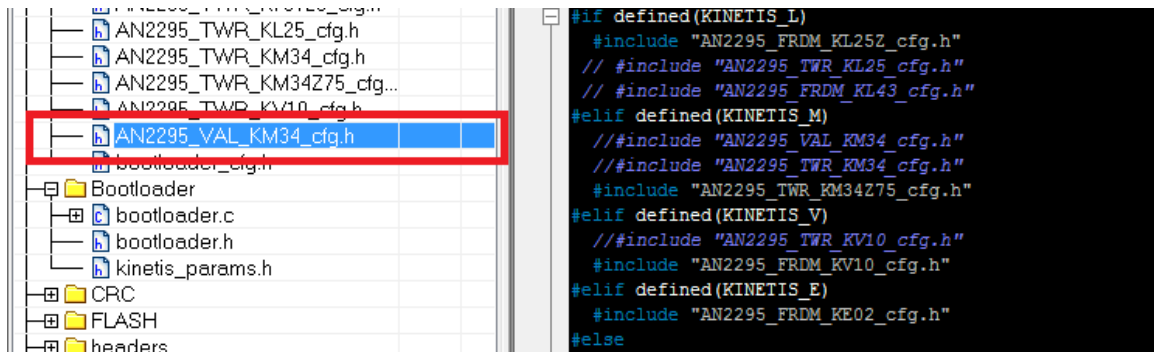
# Bootloader workshop agenda

1. Short theory about the bootloader.

2. Create a short application on TWR-KM34Z75 with all needed modifications (using KM34Z75 bare metal drivers).

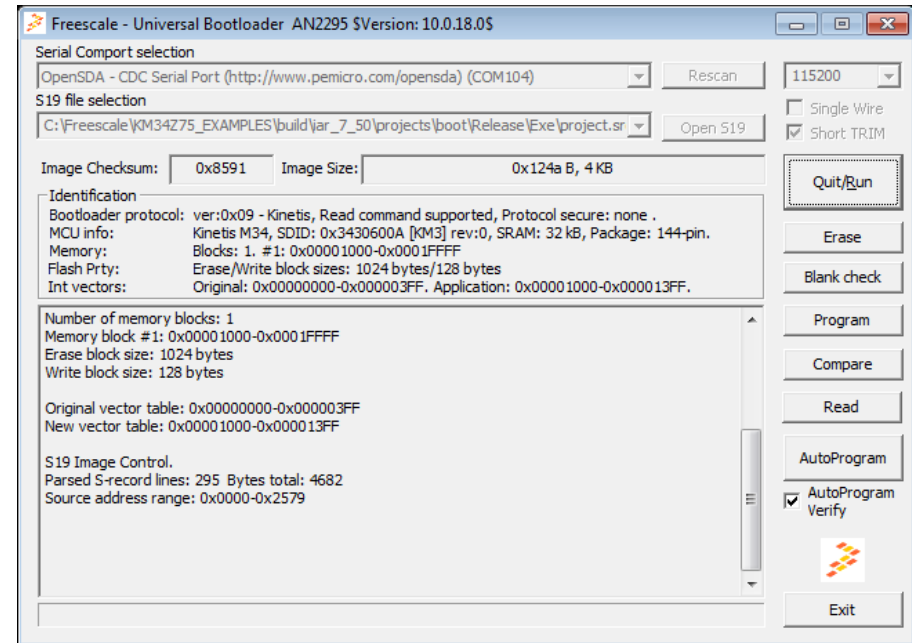
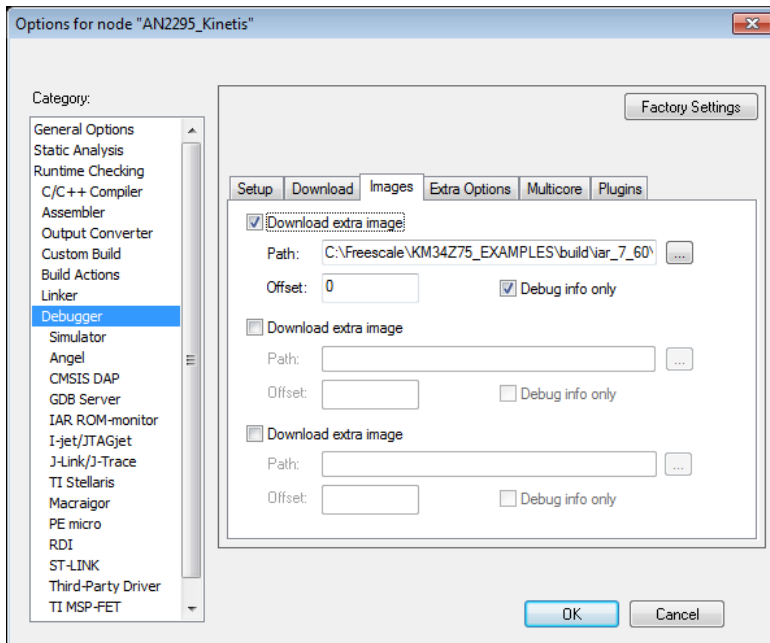


3. Correct configuration of the bootloader for (Kineticis M).



# Bootloader workshop agenda

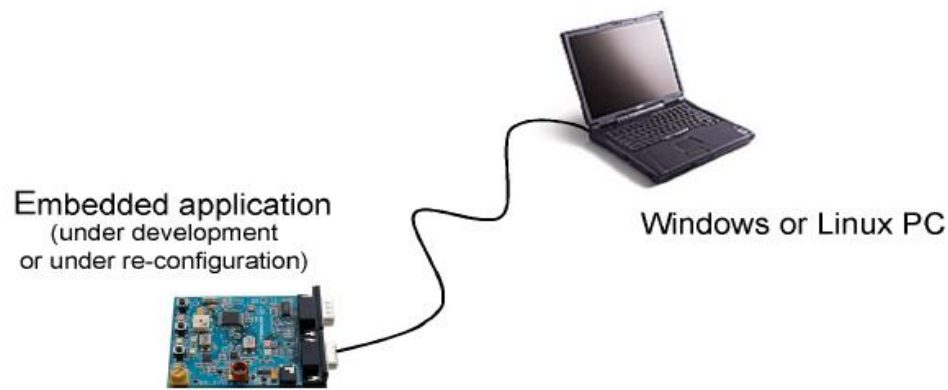
## 4. Using master PC application and final boot-loading procedure with extra image debugging in IAR (bootloader + user app).



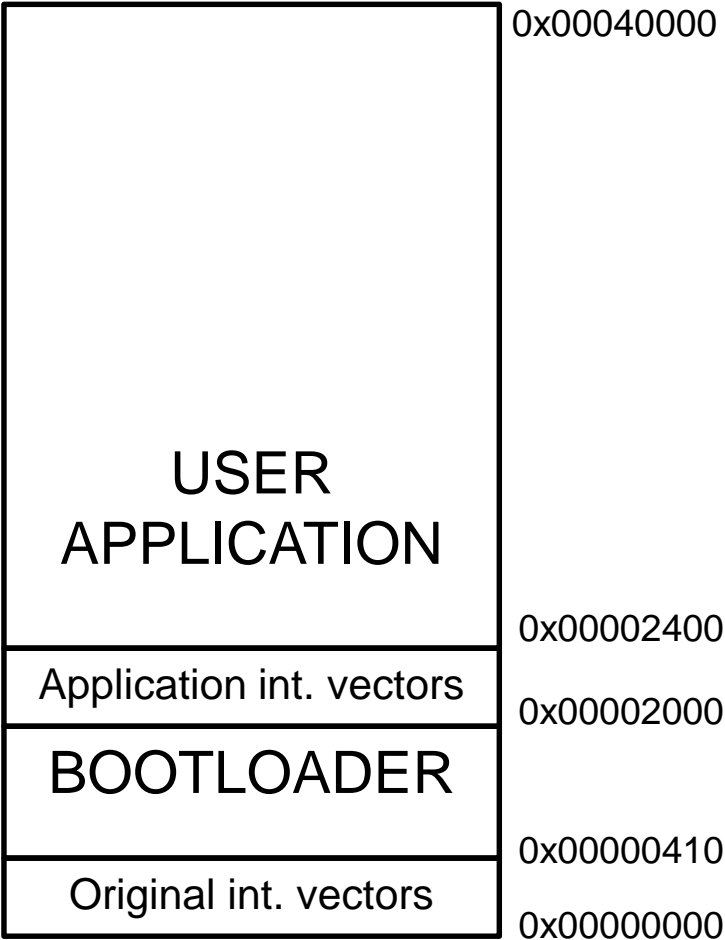
## 5. Q&A

# “Short” about the theory of universal serial Bootloader

- A short program allows possibility to update existing firmware in MCU “in-circuit”
- Not intended to replace any of debugging tools
- Consist of Master PC app and Embedded slave application
- Uses simple SCI
- Offers a zero-cost solution to applications already equipped with a serial interface (USB)
- Supported platforms ?



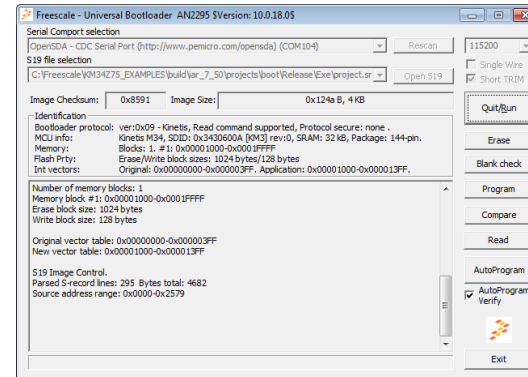
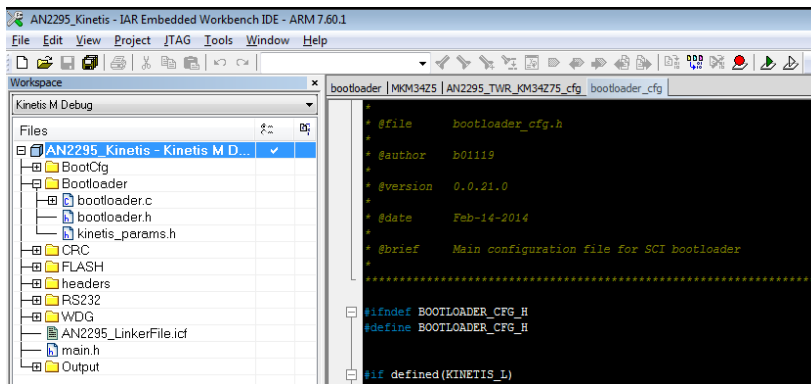
# Memory structure of Kinetis M serial Bootloader



# Pre-requisites

The following are needed to complete this work shop:

- Boards:
  - TWR-KM34Z75M (USB cable B-mini)
- Software:
  - IAR Embedded Workbench 7.60.1 or later: <http://iar.com>
  - AN2295SW Universal Bootloader sw package
  - Master Universal Bootloader AN2295 ver: 10.0.18.0

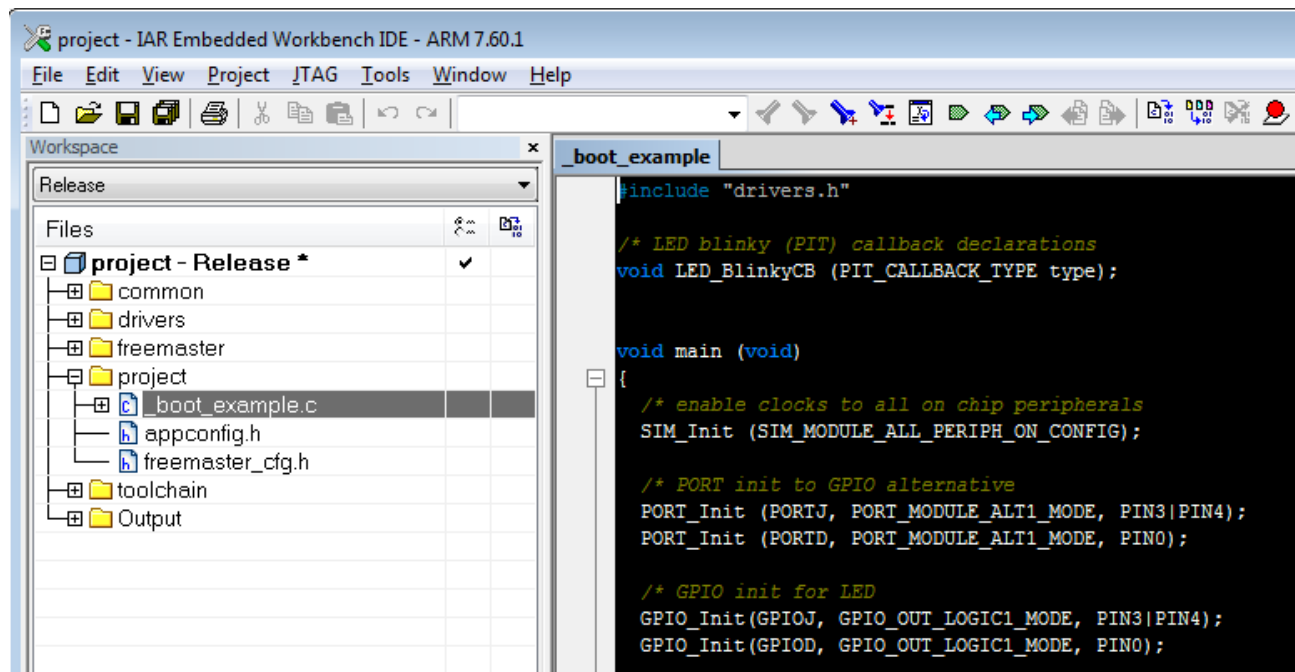


# Prepare the user application

Go to the location where you installed the KM34 bare metal examples, and open the IAR Workspace found at:

*<KM34Z75 bare\_ installation path>*

*KM34Z75\_EXAMPLES\build\iar\_7\_50\projects\\_boot\_example\  
project.eww*



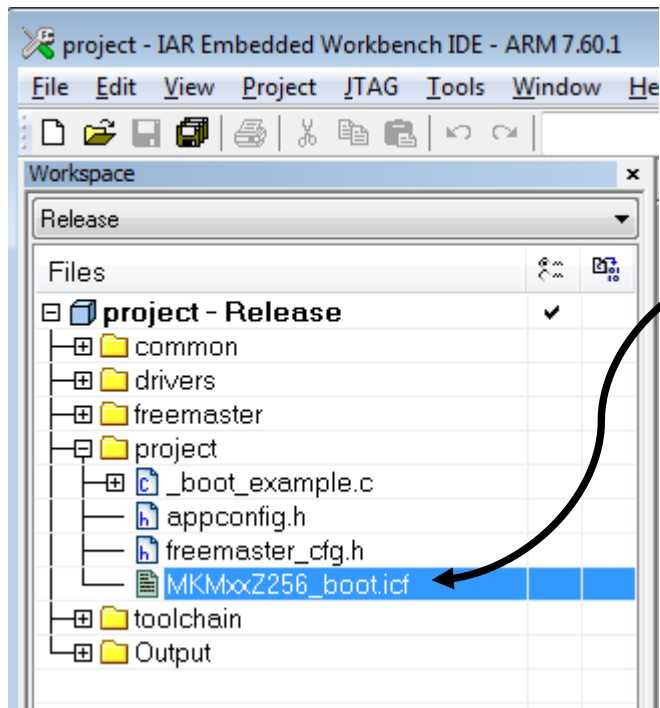
# Prepare the user application

Add bootloader linker file ***MKMxxZ256\_boot.icf*** into the project structure:

<KM34Z75 bare\_ installation path>

***KM34Z75\_EXAMPLES\build\iar\_7\_50\projects\\_boot\_example\***

***MKMxxZ256\_boot.icf***



Název položky	Datum změny	Typ
Release	26.4.2016 10:00	Složka souborů
settings	26.4.2016 10:01	Složka souborů
MKMxxZ256_boot.icf	21.4.2016 13:05	Soubor ICF
project.board	14.4.2016 14:26	Soubor BOARD
project.dep	26.4.2016 10:01	Soubor DEP
project.ewd	21.4.2016 13:01	Soubor EWD
project.ewp	26.4.2016 10:01	Soubor EWP
project.ewt	26.4.2016 10:01	Soubor EWT
project	14.11.2014 21:13	IAR IDE Workspace



# Prepare the user application

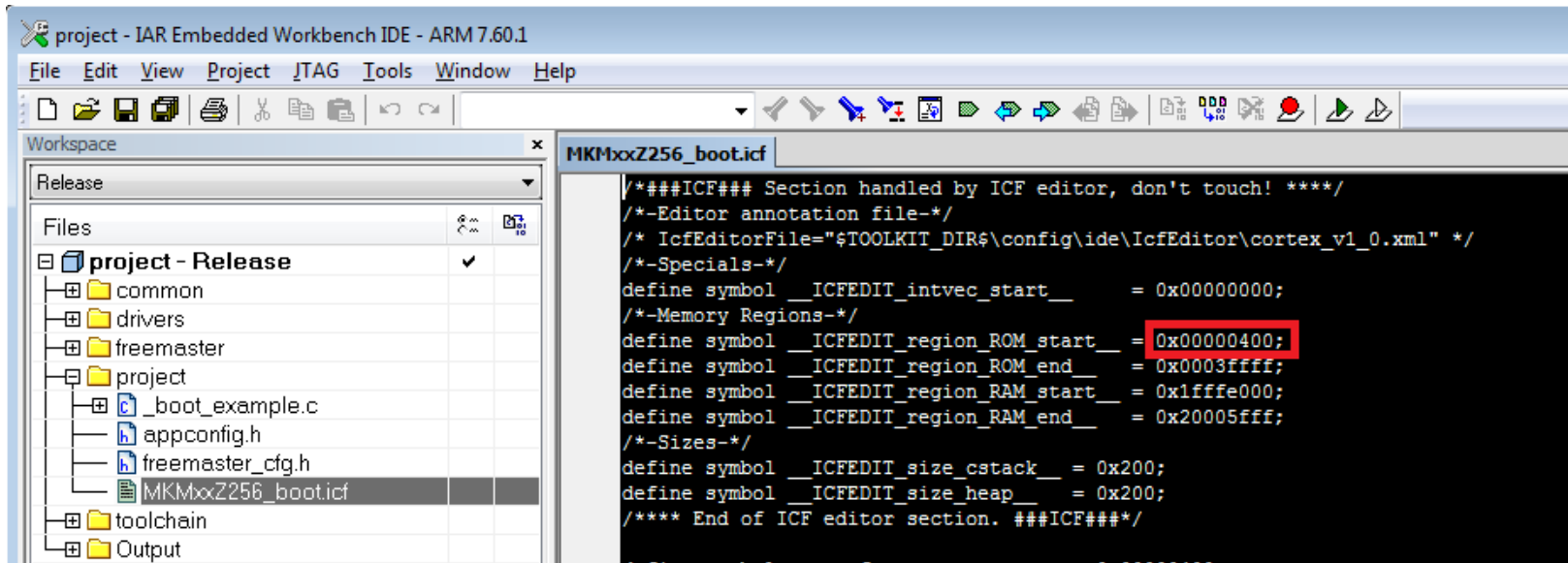
Now we will change flash starting address of the user application in linker file *MKMxxZ256\_boot.icf*:

```
define symbol __ICFEDIT_region_ROM_start__ = 0x00000400;
```

User application must be moved above the bootloader region:

```
define symbol __ICFEDIT_region_ROM_start__ = 0x00002400;
```

Protected vs non-protected version (*0x2400* vs *0x1400*)



The screenshot shows the IAR Embedded Workbench IDE interface. The workspace on the left displays a project named 'project - Release' with a file tree including folders like 'common', 'drivers', 'freemaster', and 'project'. The 'project' folder is expanded, showing files like '\_boot\_example.c', 'appconfig.h', 'freemaster\_cfg.h', and 'MKMxxZ256\_boot.icf'. The main editor window displays the content of 'MKMxxZ256\_boot.icf'. The code defines several symbols for memory regions and sizes. The line `define symbol __ICFEDIT_region_ROM_start__ = 0x00000400;` is highlighted with a red box. Other symbols include `__ICFEDIT_intvec_start__ = 0x00000000;`, `__ICFEDIT_region_ROM_end__ = 0x0003ffff;`, `__ICFEDIT_region_RAM_start__ = 0x1ffffe000;`, `__ICFEDIT_region_RAM_end__ = 0x20005fff;`, `__ICFEDIT_size_cstack__ = 0x200;`, and `__ICFEDIT_size_heap__ = 0x200;`. The code is enclosed in ICF editor annotations: `/*###ICF### Section handled by ICF editor, don't touch! ****/` and `**** End of ICF editor section. ###ICF###*/`.

# Prepare the user application

Protected vs non-protected version (*0x2400 vs 0x1400*)

```
/** Bootloader flash protection */  
#define BOOTLOADER_FLASH_PROTECTION          0
```

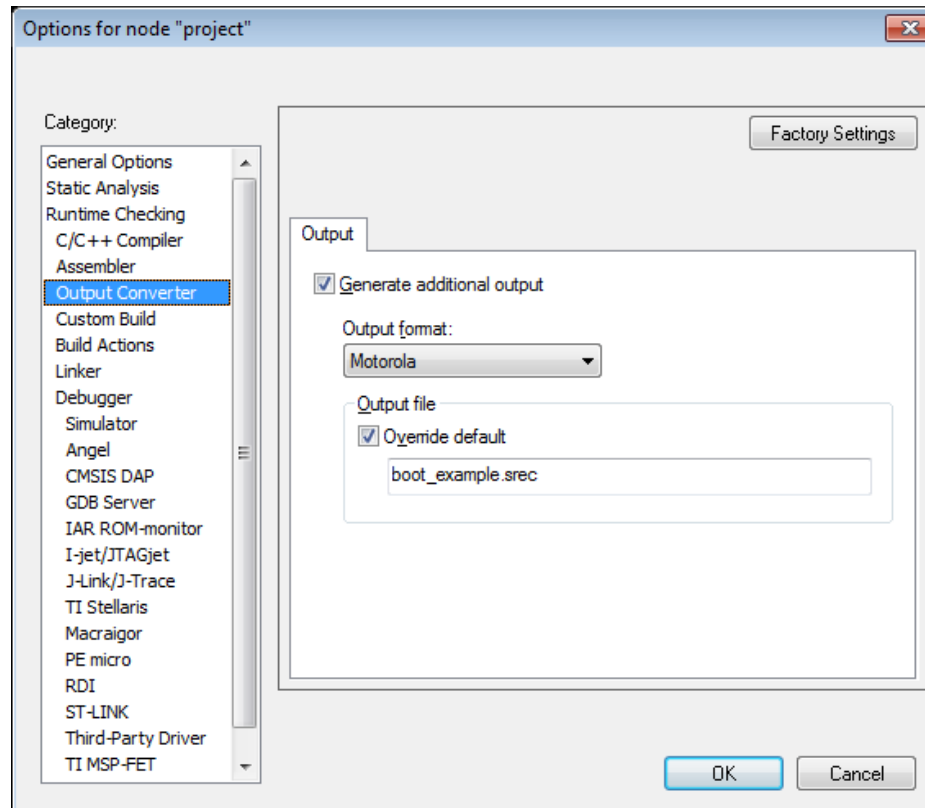
```
/** Bootloader flash protection */  
#define BOOTLOADER_FLASH_PROTECTION          1
```

Actual size of the bootloader is ~2,3KB (0x900). This region cannot be in collision with user application.

Minimal protection are for the KM34Z75 is  $(256\text{KB} / 32) = 0x2000$ .

# Prepare the user application

1. Go to the “Output Converter” category and set the settings according to the following picture:
  - a) Change the Output format to Motorola
  - b) Flag the “Override default” box



## Prepare the user application

2. Click OK button and rebuild the boot\_example project.
  - a) Please remember to set the project as active.
  - b) Generated “boot\_example.srec” file will be in location:

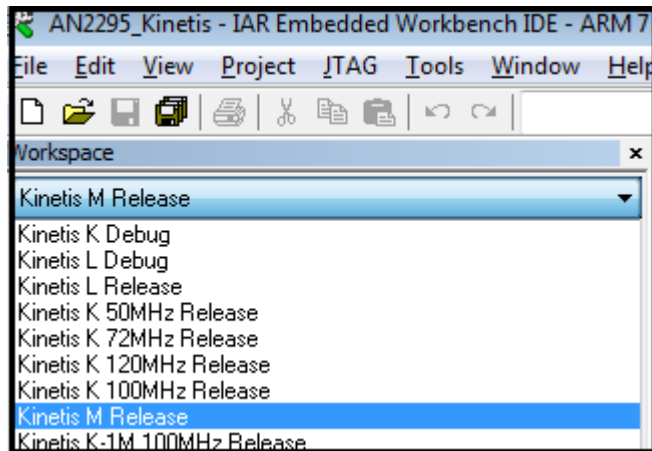
*<KM34Z75 bare\_ installation path>  
KM34Z75\_EXAMPLES\build\iar\_7\_50\projects\\_boot\_example\  
Release\Exe\boot\_example.srec*

# Bootloader configuration

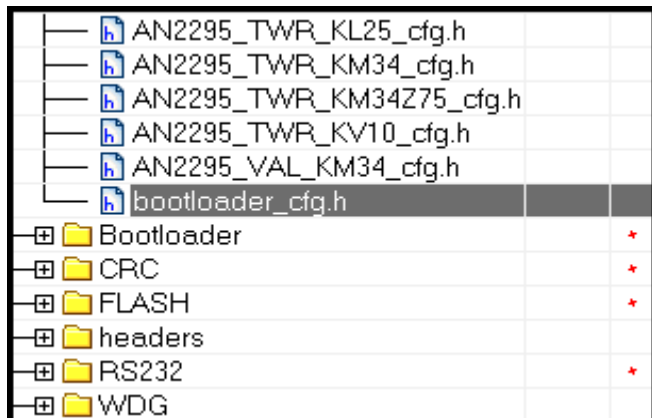
1. Plug in the TWR-KM34Z75M via the included USB cable:
  - It will begin to install some drivers, this is normal and should be allowed to complete before downloading the application.
2. Go the location where you installed the AN2295 universal bootloader software, and open the IAR Workspace found at:  
*<AN2295 software installation path>*  
*lan2295sw\src\Kinetis\IAR\AN2295\_Kinetis.eww*
3. Now we will change some configuration options of the bootloader application specific for the TWR-KM34Z75 board.

# Bootloader configuration

- Set target to *Kinetis M Release*



- Check file *bootloader\_cfg.h*, if correct header file is included:



```
#elif defined(KINETIS_M)
// #include "AN2295_VAL_KM34_cfg.h"
// #include "AN2295_TWR_KM34_cfg.h"
#include "AN2295_TWR_KM34Z75_cfg.h"
```

# Bootloader configuration

- Actual settings corresponds to UART via open SDA interface
- We can modify the config file *AN2295\_TWR\_KM34Z75\_cfg.h*:
  - *Important parameters are:*

```
/* Actual used UART module */
#define BOOT_UART_BASE UART2_BASE_PTR

/* Actual used UART module */
/* A range of UART baudrates is (9600 - 115200) */
#define BOOT_UART_BAUD_RATE 115200

/** GPIO & UART pins initialization */

#define BOOT_UART_GPIO_PORT PORTI_BASE_PTR

/* setting of multiplexer for UART alternative of pin */
#define BOOT_PIN_UART_ALTERNATIVE 2

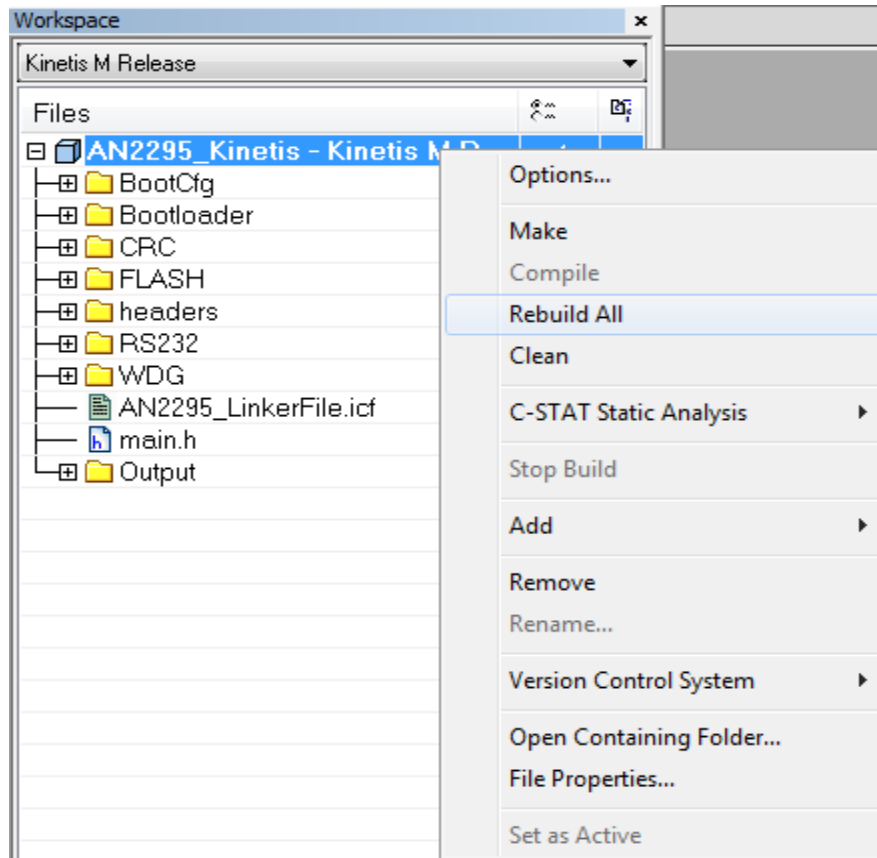
/* setting of multiplexer for GPIO alternative of pin */
#define BOOT_PIN_GPIO_ALTERNATIVE 1

#define BOOT_UART_GPIO_PIN_RX 6

#define BOOT_UART_GPIO_PIN_TX 7
```

# Bootloader configuration

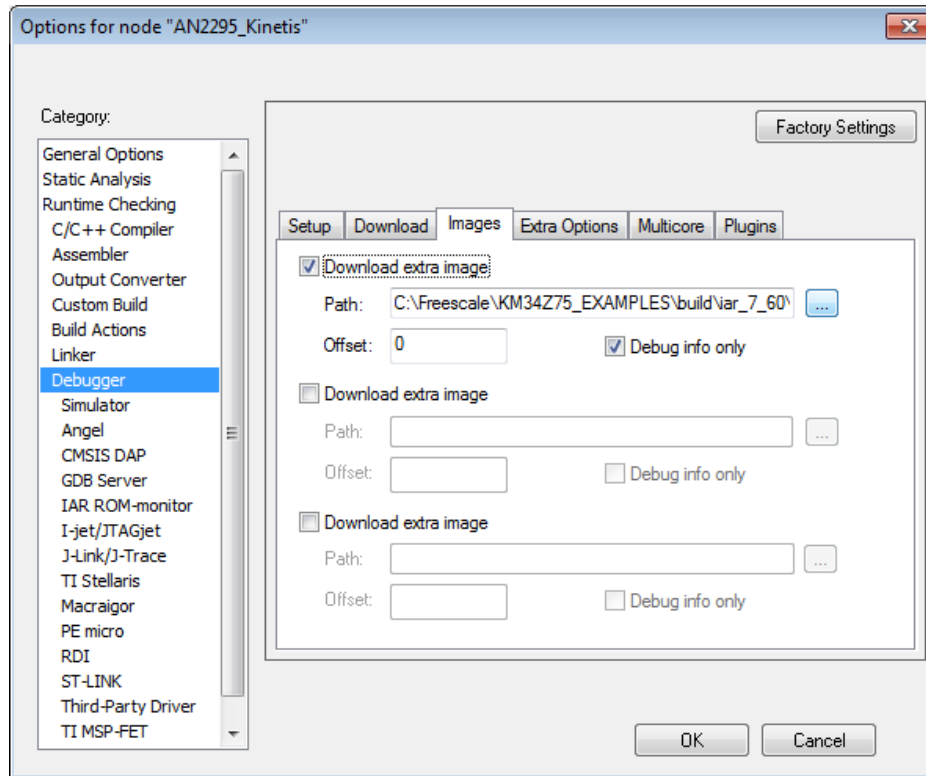
- Rebuilt the complete bootloader application and program:





# Bootloader configuration

- Now we can extra image of the user application (only debug info):



\* This feature allows debugging of both application (bootloader & usr app) in the same time.

# Bootloader configuration

- Download bootloader to TWR-KM34 using OpenSDA interface:

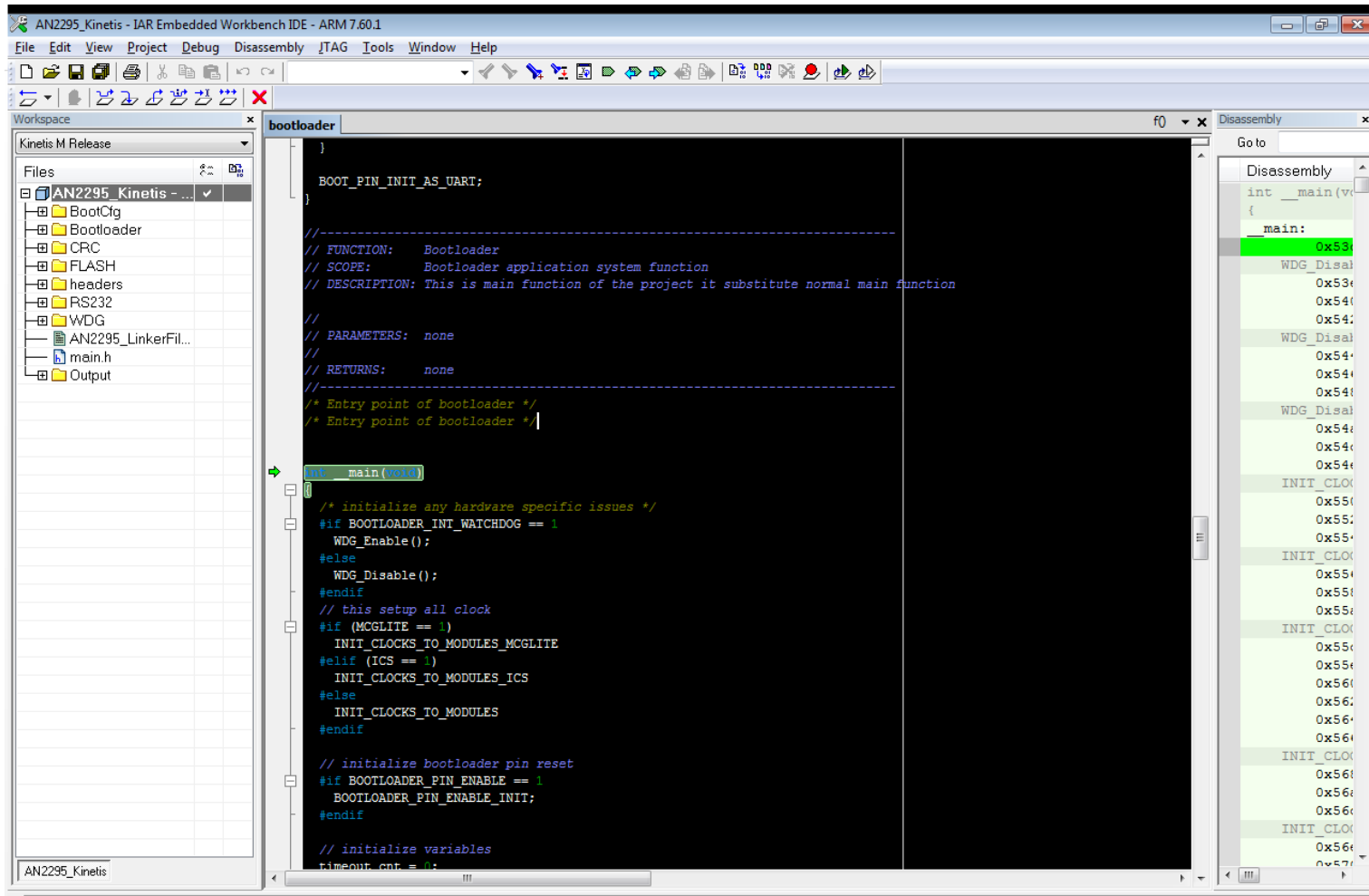
The image shows the PEMICRO Connection Manager dialog box. The title bar reads "PEMICRO Connection Manager". Below the title bar, there is a message: "You have selected to display this dialog on startup. Specify communications parameters and click OK." The dialog is divided into several sections:

- Connection port and Interface Type:** Interface: OpenSDA Embedded Tower Debug - USB Port; Port: OpenSDA on USB1 (Name=43503E4E) (Autodetected); Interface Detected: ; Firmware Version: ;
- Device Selection:** Architecture: ARM; Vendor: NXP; Family: KMx; Device: KM34Z256M7; Advanced button.
- BDM Communication Speed:** PC Parallel Port wait states: IO\_DELAY\_CNT = 0; Debug Shift Speed = (3) : Shift Frequency = 4.545Mhz; BDM\_SPEED = 3.
- MCU Internal Bus Frequency (For programming):** 0.
- Reset Options:**  Delay after Reset and before communicating to target for 0 milliseconds (decimal).
- Power Control for Cyclone / TraceLink / Multilink Universal FX:** Regulator Output Voltage: 3V; Power Down Delay: 250 mS; Power Up Delay: 250 mS.

At the bottom, there are three buttons: **Connect (Reset)**, **Hotsync**, and **Abort**. Below the buttons, there is a checkbox:  Show this dialog before attempting to contact target (Otherwise only display on Error).

# Bootloader configuration

Now everything is prepared for boot-loading procedure. 😊



The screenshot displays the IAR Embedded Workbench IDE for an ARM7.60.1 project named 'AN2295\_Kinetis'. The workspace shows a project tree with folders for 'BootCfg', 'Bootloader', 'CRC', 'FLASH', 'headers', 'RS232', 'WDG', and 'Output'. The main editor window shows the 'bootloader.c' file with the following code:

```
BOOT_PIN_INIT_AS_UART;
}

//-----
// FUNCTION:   Bootloader
// SCOPE:      Bootloader application system function
// DESCRIPTION: This is main function of the project it substitute normal main function

//
// PARAMETERS: none
//
// RETURNS:   none
//-----

/* Entry point of bootloader */
/* Entry point of bootloader */

int __main(void)
{
    /* initialize any hardware specific issues */
    #if BOOTLOADER_INT_WATCHDOG == 1
        WDG_Enable();
    #else
        WDG_Disable();
    #endif
    // this setup all clock
    #if (MCGLITE == 1)
        INIT_CLOCKS_TO_MODULES_MCGLITE
    #elif (ICS == 1)
        INIT_CLOCKS_TO_MODULES_ICS
    #else
        INIT_CLOCKS_TO_MODULES
    #endif

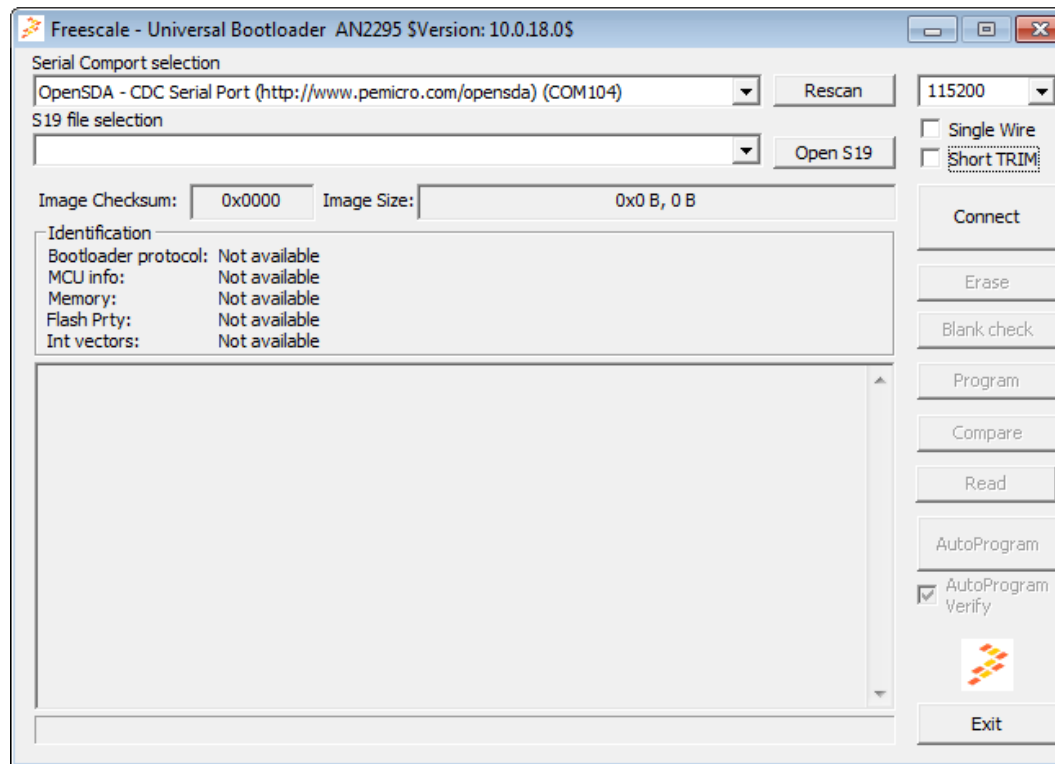
    // initialize bootloader pin reset
    #if BOOTLOADER_PIN_ENABLE == 1
        BOOTLOADER_PIN_ENABLE_INIT;
    #endif

    // initialize variables
    TIMEOUT_CNT = 0;
}
```

The disassembly window on the right shows the assembly code for the 'main' function, starting at address 0x53. The code includes instructions for enabling or disabling the watchdog timer (WDG\_Disal) and initializing clocks (INIT\_CLO).

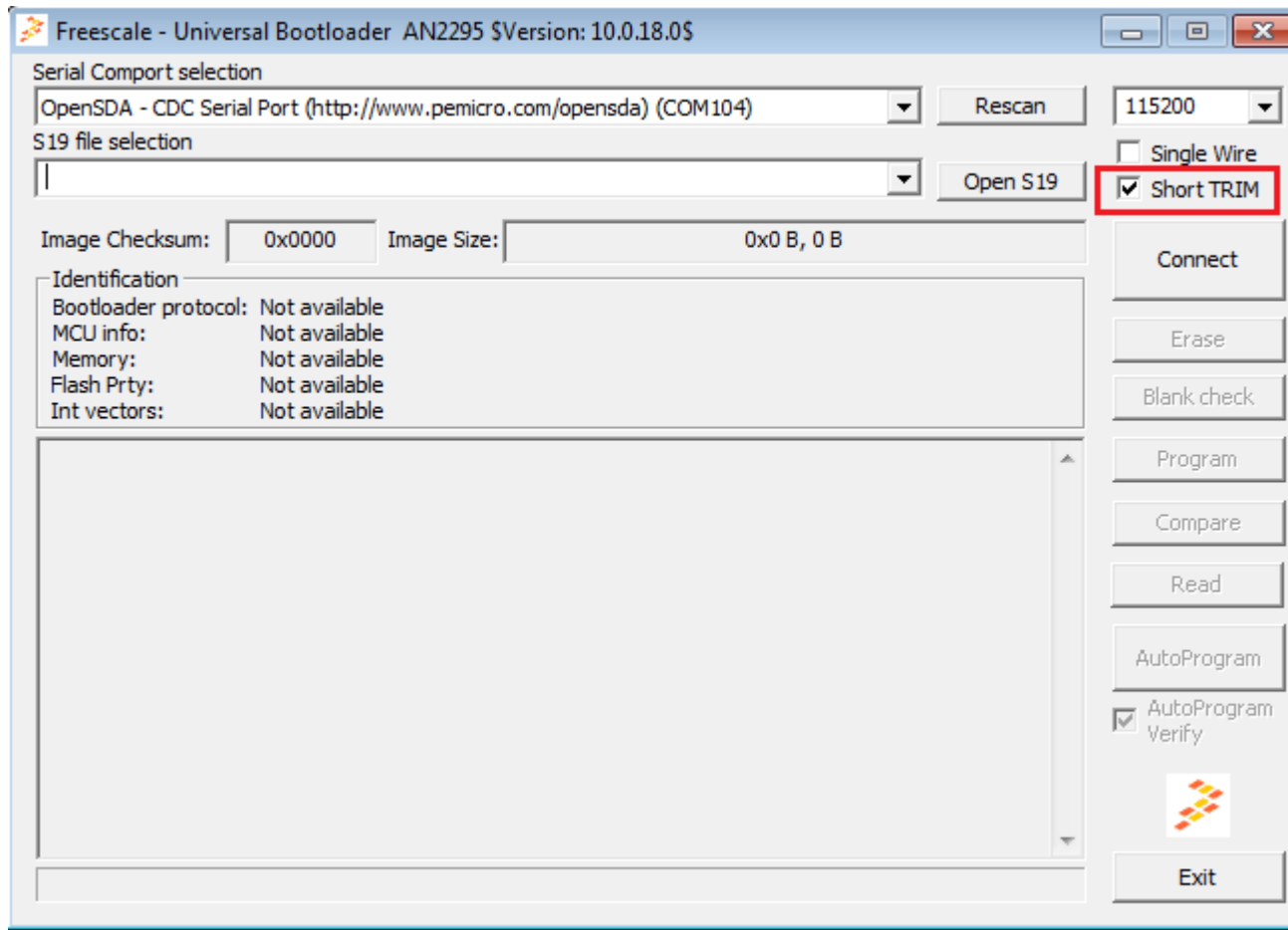
# Boot-loading procedure with master PC application

1. Go to the location where you installed the AN2295 universal bootloader software and open the master PC application located here:  
*<AN2295 software installation path>*  
*lan2295sw\masters\release\win\_hc08sprg.exe*



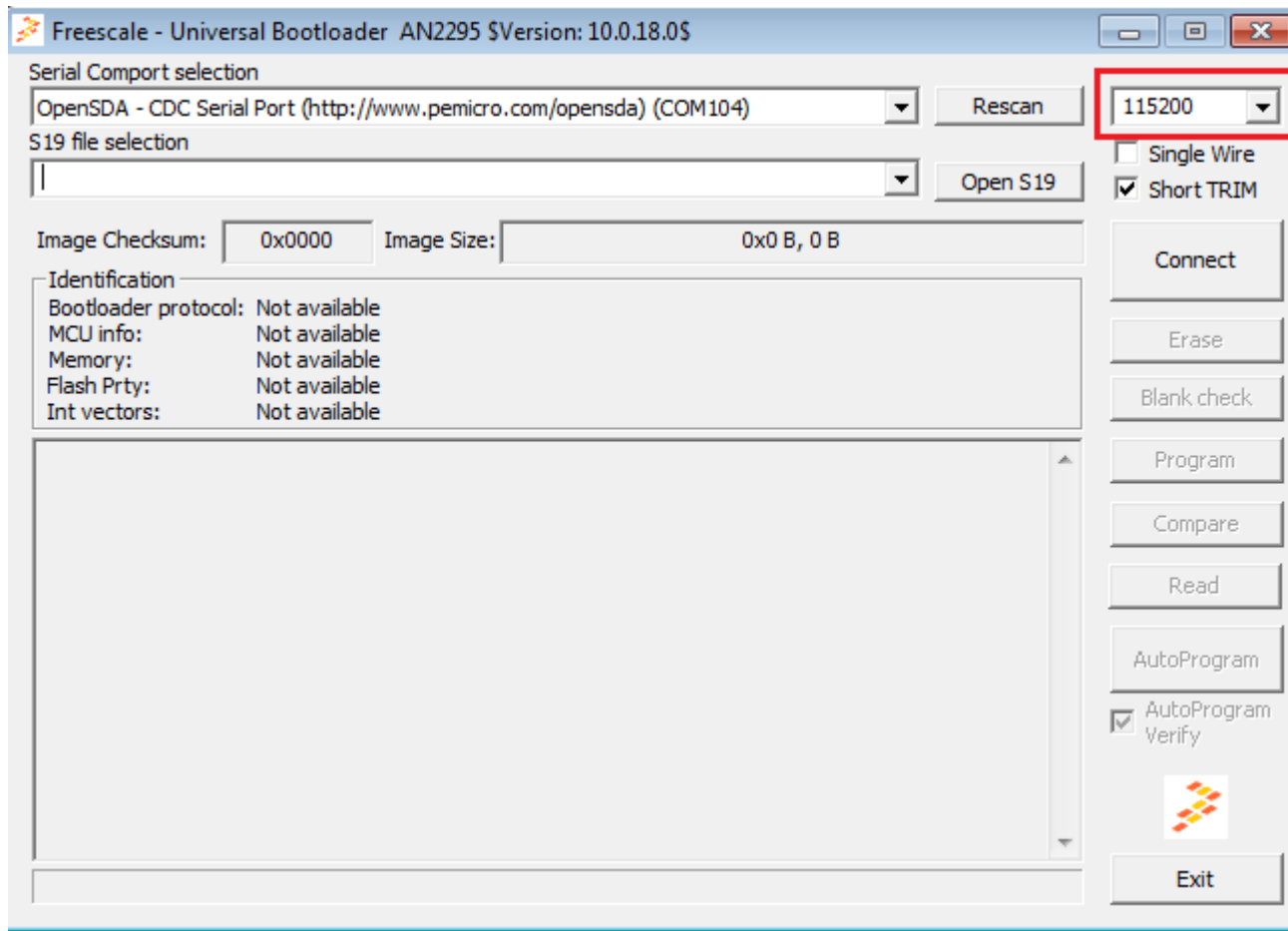
# Boot-loading procedure with master PC application

1. Check the Short TRIM checkbox due to using UART via USB.



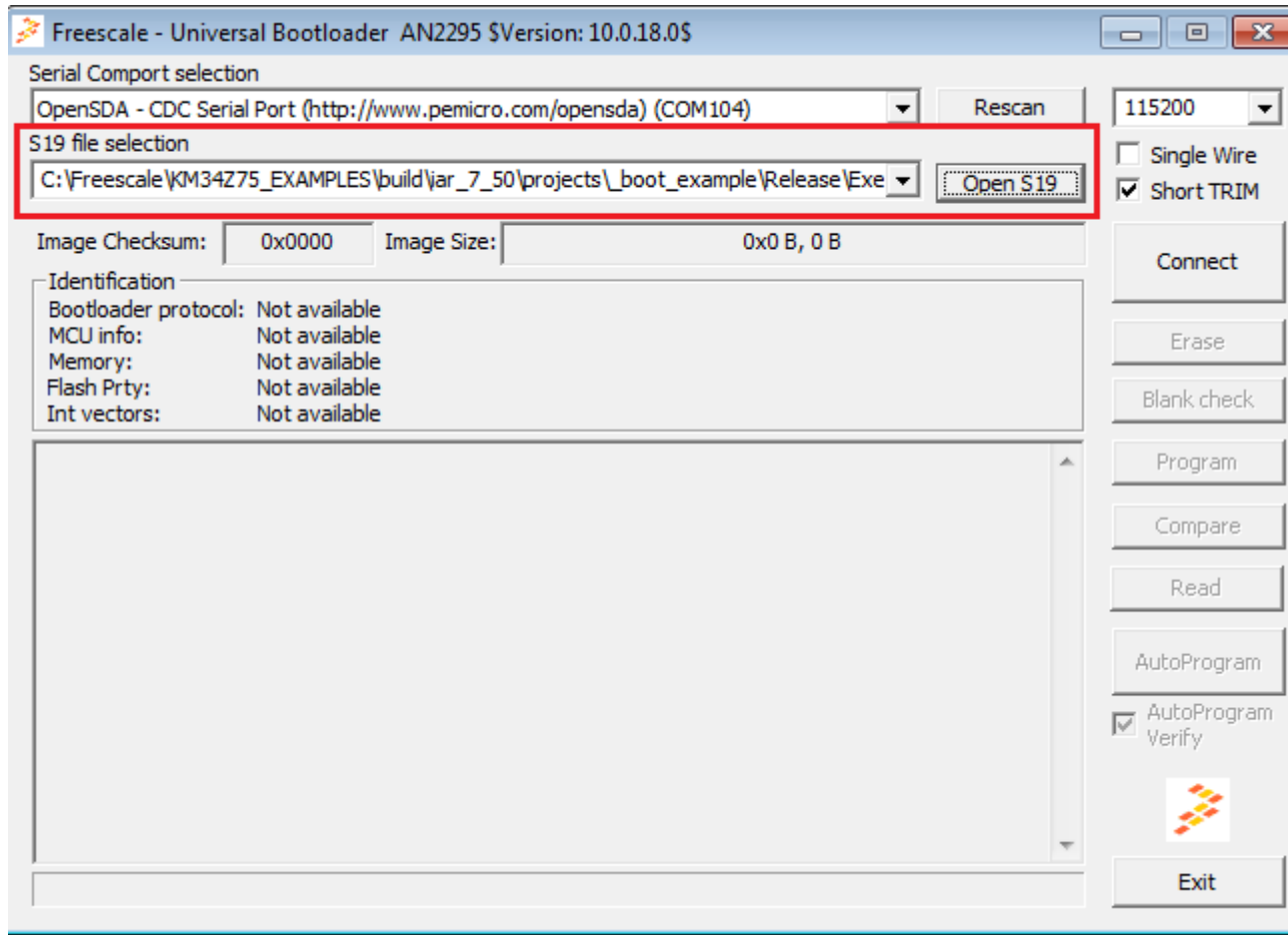
# Boot-loading procedure with master PC application

1. Set the correct baud rate of UART (in example 115200 Baud).



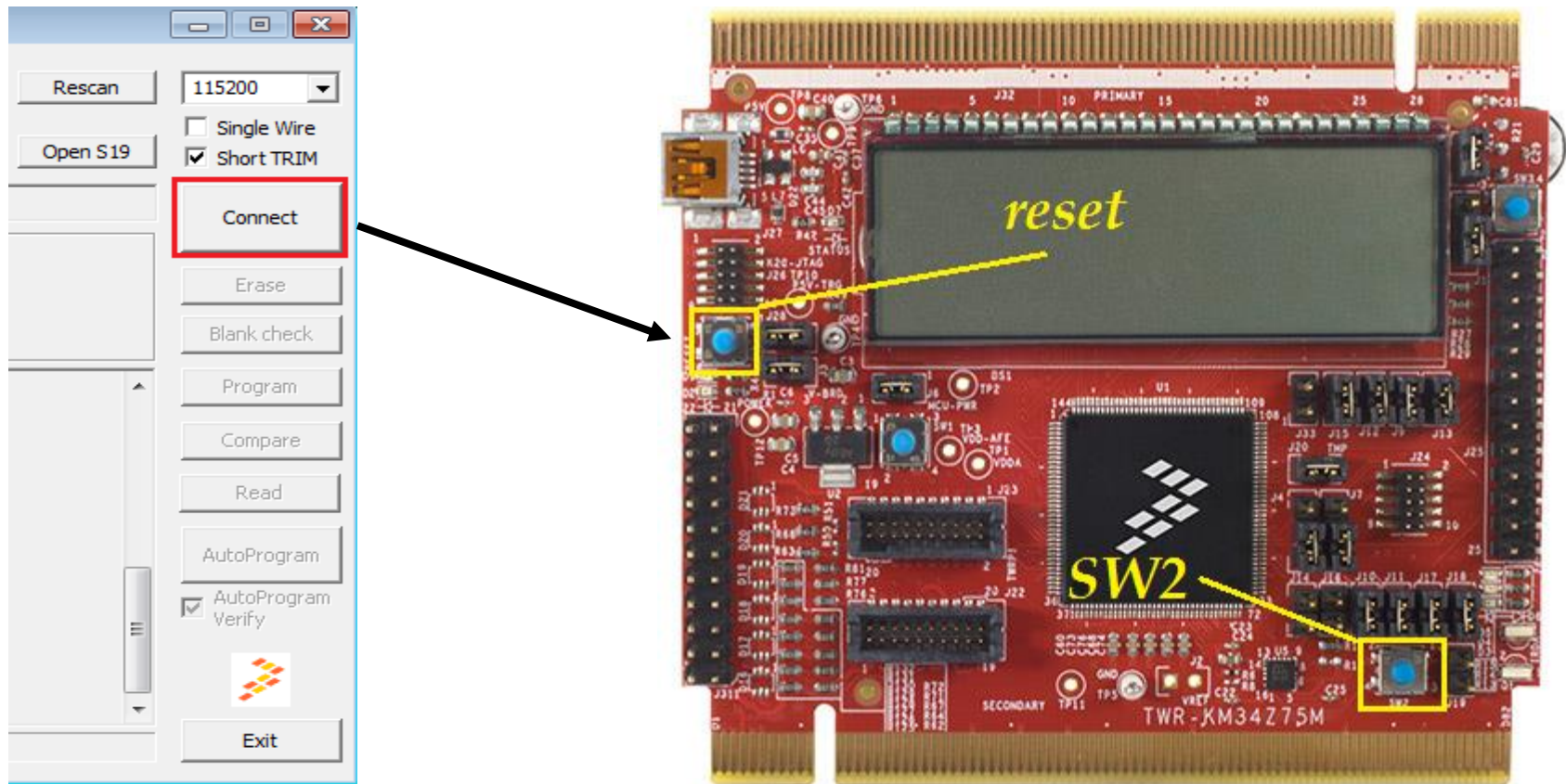
# Boot-loading procedure with master PC application

1. Open generated S19 file of user example application.



# Boot-loading procedure with master PC application

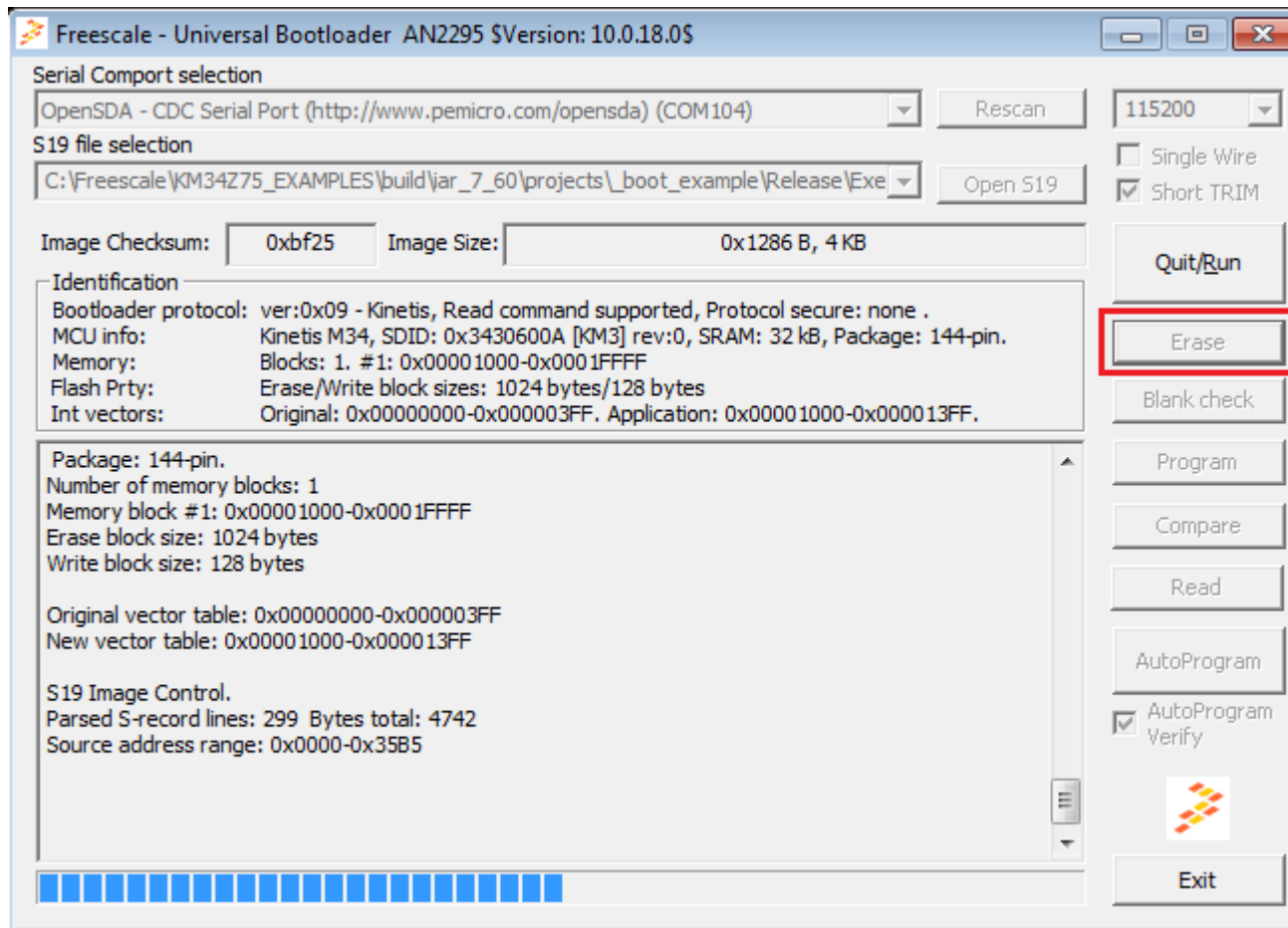
1. Plug TWR-KM34Z75M board to PC.
2. Try to connect Master application: Master app->Button Connect-> Board->reset button->switch SW2->go to bootloader





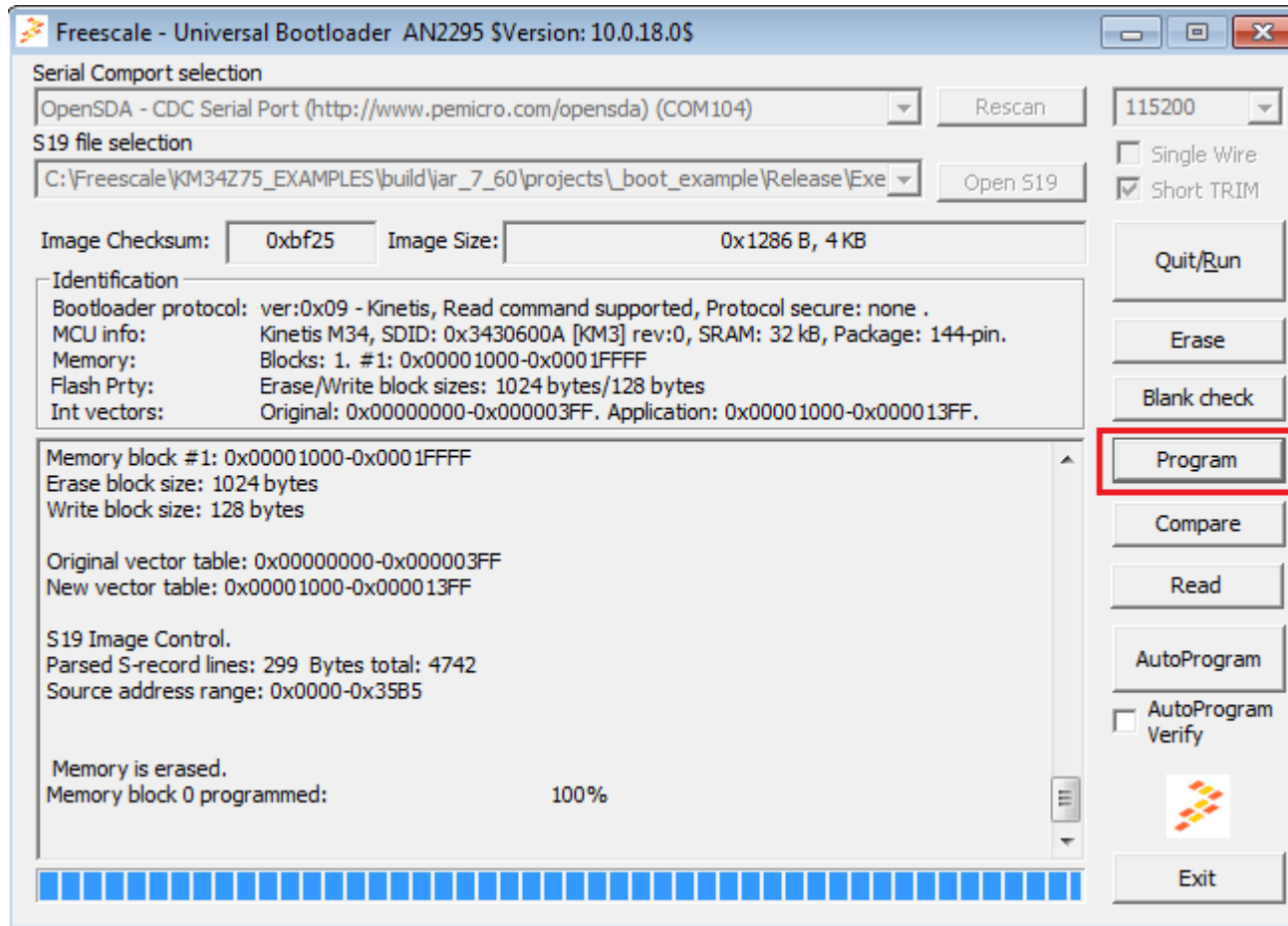
# Boot-loading procedure with master PC application

1. Now you are connected with the bootloader on TWR-KM34 board. First must be erased the application part of flash memory:



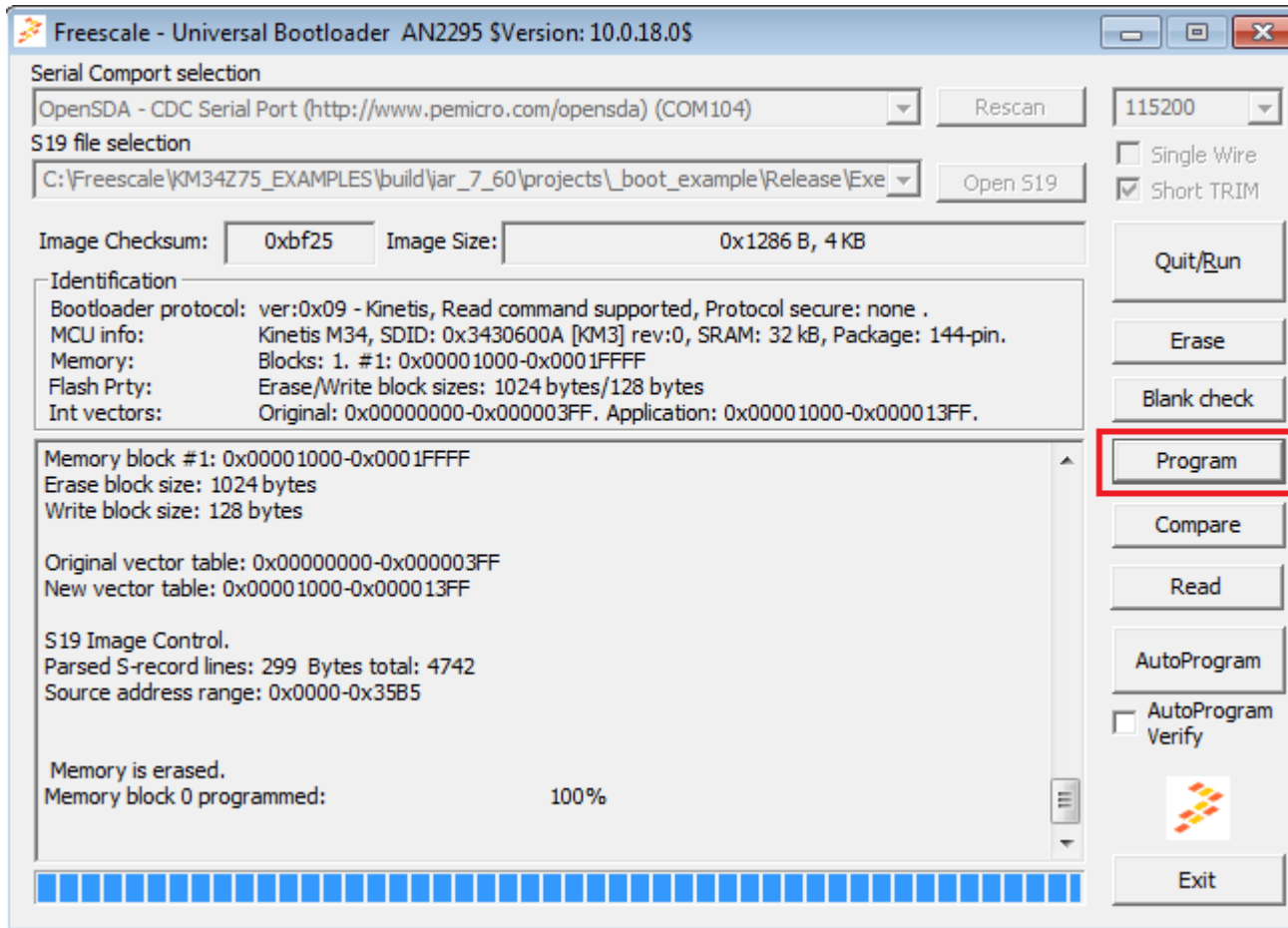
# Boot-loading procedure with master PC application

1. After the correct flash memory erasing we can continue with self-programming by using button **Program**:



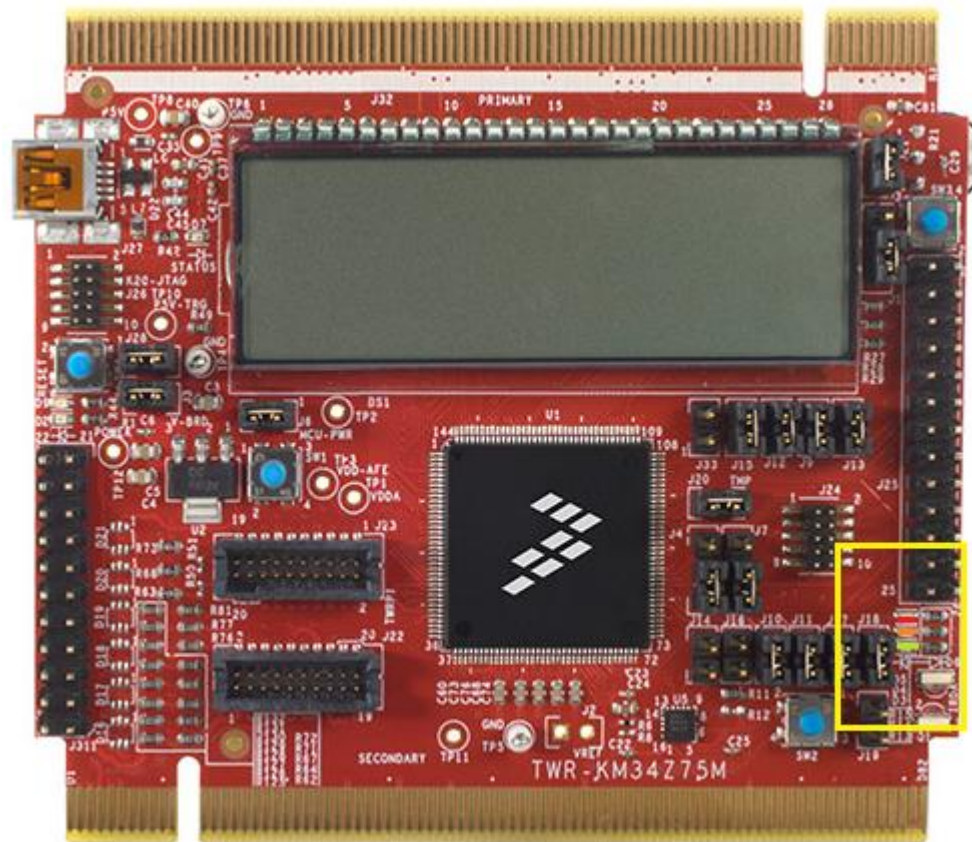
# Boot-loading procedure with master PC application

1. Now the application was successfully loaded into the MCU, we can leave Master Bootloader application by using button **Quit/Run**:



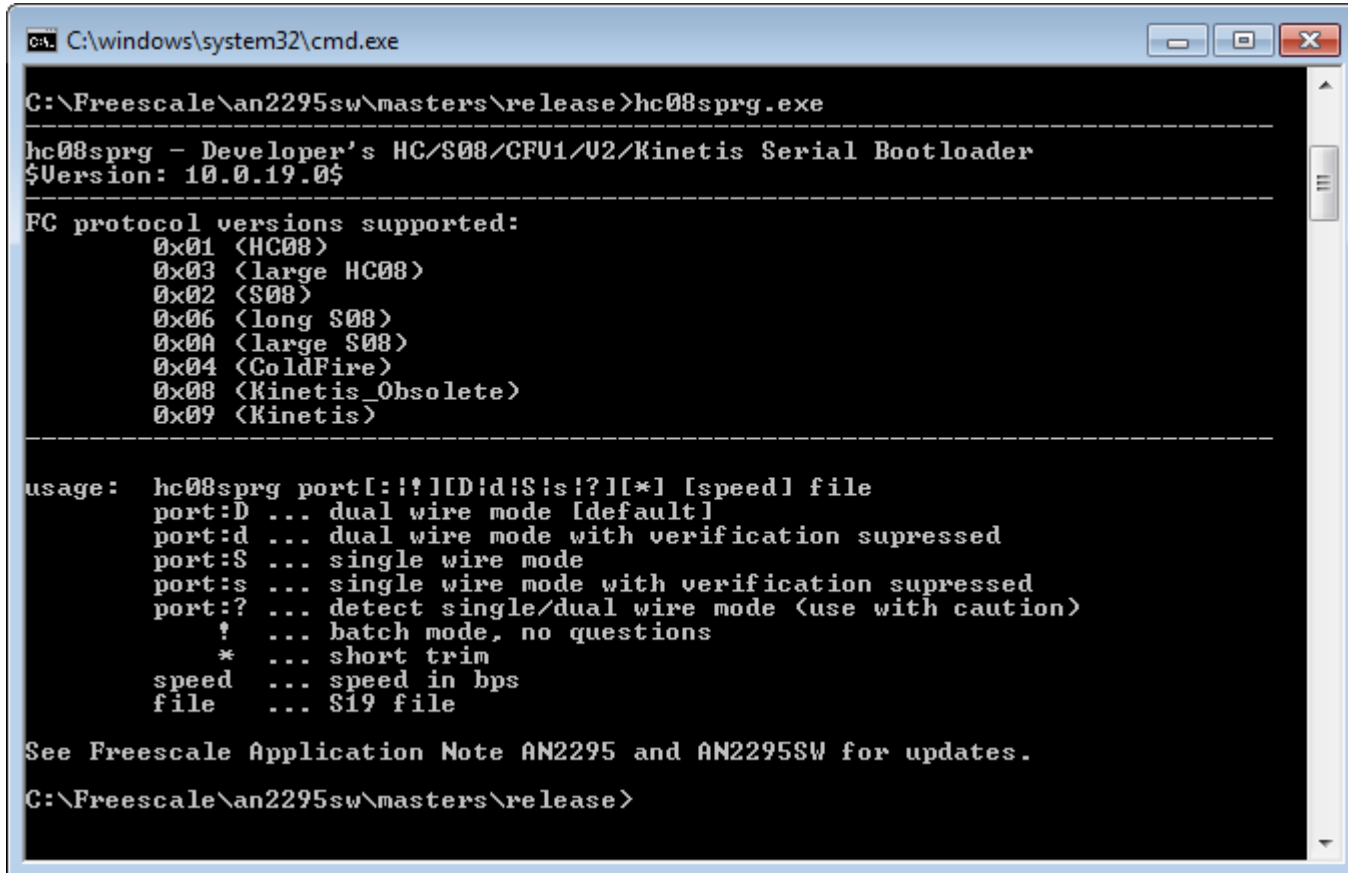
# Boot-loading procedure with master PC application

1. If the procedure was done correctly, application is running right now:



# Boot-loading procedure with master PC application

1. The same procedure can be achieved by using our command line “hc08sprg.exe” application which is in the sw package.



```
C:\windows\system32\cmd.exe

C:\Freescal...an2295sw\masters\release>hc08sprg.exe
-----
hc08sprg - Developer's HC/S08/CFU1/U2/Kinetis Serial Bootloader
$Version: 10.0.19.0$
-----
PC protocol versions supported:
  0x01 (HC08)
  0x03 (large HC08)
  0x02 (S08)
  0x06 (long S08)
  0x0A (large S08)
  0x04 (ColdFire)
  0x08 (Kinetis_Obsolete)
  0x09 (Kinetis)
-----

usage:  hc08sprg port[:!?!][D!d!S!s!?!][*] [speed] file
port:D ... dual wire mode [default]
port:d ... dual wire mode with verification supressed
port:S ... single wire mode
port:s ... single wire mode with verification supressed
port:? ... detect single/dual wire mode (use with caution)
      ! ... batch mode, no questions
      * ... short trim
speed  ... speed in bps
file   ... S19 file

See Freescale Application Note AN2295 and AN2295SW for updates.
C:\Freescal...an2295sw\masters\release>
```

# Q&A

1. [Document AN2295 application note](#)

**THANK YOU FOR YOUR  
ATTENTION**





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