

Application Software Pack: ML-based State Monitor for FXLS8974CF

Revision 9 January 2024



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1 Lab Overview

This lab will cover how to use the ML-based fan state monitor application code in conjunction with the **Building and benchmarking Deep Learning models for Smart Sensing Appliances on MCUs** application note (AN13562). This document will cover how to gather the data that the model will be trained on, how to run the Jupyter notebook scripts that will train the model, and how to deploy the trained model to the board.

This lab was written for the i.MX RT1170, but the same steps can be used for the following boards:

- <u>LPCXpresso55S69</u>
- <u>i.MX RT1170-EVK</u>

This lab document is for the <u>FXLS8974CF</u> accelerometer which can be found on the following sensor boards:

- <u>ACCEL_4_CLICK board</u> combined with <u>Arudino UNO click shield interposer</u> board.
- FRDM-STBI-A8974 sensor board.

The software for this accelerometer uses a new updated version of the application code that includes the ability to evaluate several different time series models like CNN, LightCNN, LightResNet, and MLP. If using the accelerometer on the EVK or the FRDM-STBC-AGM01 board please refer to the other lab document as those use the FXOS8700CQ accelerometer.

2 Software and Hardware Installation

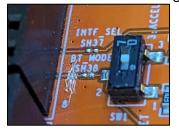
This section will cover the steps needed to install the elQ software and TensorFlow on your computer.

2.1 Hardware Requirements

- i.MX RT1170 EVK board (or other supported board like LPC55S69)
- A board with the FXLS8974CF accelerometer:
 - o ACCEL_4_CLICK board combined with Arudino UNO click shield interposer board.



- o FRDM-STBI-A8974 sensor board.
 - The signal connected to SH38 needs to be cut to isolate it to prevent the accelerometer from being put into an incorrect mode.





- microSD card (formatted for FAT32)
- microSD card reader to transfer data to a PC
- A fan, motor, or other vibration source to train the model on that can provide vibrations that will be gathered by the sensor. This <u>fan</u> for example.

2.2 TensorFlow Installation

- Download and install Python 3.10. **The 64-bit edition is required and it is highly recommended to use Python 64-bit 3.10.x to ensure compatibility with this lab**: https://www.python.org/downloads/
- 2. Open a Windows command prompt and verify that the python command corresponds to Python 3.10.x.

python -V

3. Update the python installer tools:

python -m pip install -U pip python -m pip install -U setuptools

4. Install the Tensorflow libraries and support for python. To ensure software compatibility, it should be these version numbers:

python -m pip install tensorflow==2.8 python -m pip install keras==2.8 python -m pip install protobuf==3.20 python -m pip install pandas==1.5.3

5. Install other useful python packages. Not all of these will be used for this lab but will be useful for other eIQ demos and scripts.

python -m pip install numpy scipy matplotlib ipython jupyter sympy nose imageio python -m pip install netron seaborn west pyserial scikit-learn opency-python pillow

2.3 Download Enablement Software

- 1. Install the latest version of MCUXpresso IDE
- 2. Install a terminal program like **TeraTerm**.
- 3. Install Git

2.4 eIQ Tool Installation

The model inference can be done with TensorFlow Lite for Microcontrollers or Glow. If using Glow, You will need to install the latest <u>Glow package</u>. This will put the Glow compiler and helper programs into **C:\NXP\Glow** and add it to your executable path.

3 Import the App Software Pack into MCUXpresso IDE

There are two methods to get the application software pack. This section will cover both options, but only one needs to be done. It is recommended to use the first option as it is more straight forward.

3.1 Option #1: Get the App Software Pack with MCUXpresso IDE

1. Open MCUXpresso IDE and select a workspace location in an empty directory.

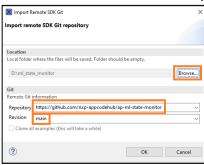


Right click in the blank area of the Installed SDKs panel at the bottom and select Import remote SDK Git repository...

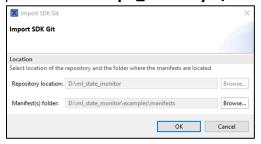


- In the dialog box that comes up:
 - a) In the **Location** field, click on the Browse button and select or create an empty directory for the application software pack to be downloaded to. Make note of this location as it'll be used throughout this lab.
 - b) In the Repository field put: https://github.com/nxp-appcodehub/ap-ml-state-monitor
 - c) In the **Revision** field put: **main**

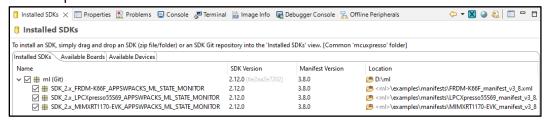
Then hit OK to download the application software pack



4. A dialog box will then come up asking for the location of the Manifests folder. Make sure to point it to the **<repo_directory>\examples\manifests** folder if it is not already.



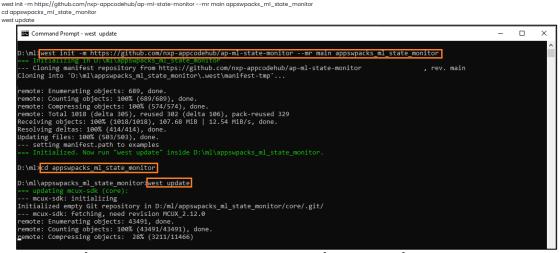
5. Once imported the Installed SDKs tab will look like this:





3.2 Option #2: Use the Command Line

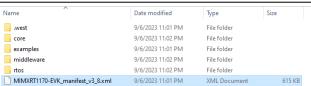
1. Open up a Windows command line and execute the following lines:



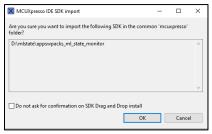
Go to the \appswpacks_ml_state_monitor\examples\manifests folder and find the MIMXRT1170-EVK_manifest_v3_8.xml file. If using a different board copy that board's .xml file instead.



3. Copy that MIMXRT1170-EVK_manifest_v3_8.xml file into the root \appswpacks_ml_state_monitor\ directory. It should look like the following when done:



- 6. Next open MCUXpresso IDE and select a workspace location in an empty directory.
- 7. Drag-and-drop the **\appswpacks_ml_state_monitor** directory that was created in the previous step into the **Installed SDKs** window, located on a tab at the bottom of the screen named "Installed SDKs". You will get the following pop-up, so hit OK.



8. Once imported, the Installed SDK panel will look something like this





4 Gather the Data

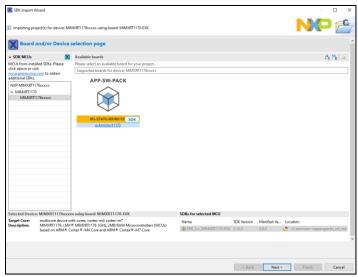
To train a model, sensor data must be collected. For this lab the on-board accelerometer will be used and the data that is collected will be stored on a microSD card.

4.1 Import the ML-based System State Monitor project

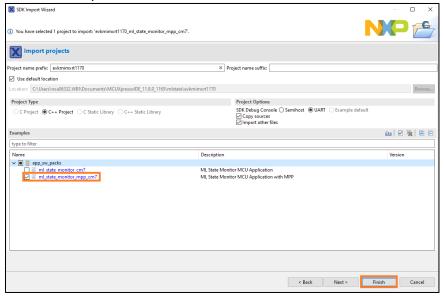
1. In the Quickstart Panel in the lower left corner, click on Import SDK examples(s)...



Select the APP-SW-PACK ML-State-Monitor for evkmimxrt1170 and click on Next



3. Expand the **app_sw_packs** category and select the ml_state_monitor_mpp_cm7 example which is compatible with the FRDM-STBI-A8974 board. Then click on **Finish**





Once imported it should look like the following:

4.2 Collect data

The project will need to be modified to collect accelerometer data and store it on an SD card.

- 1. Put in a microSD card into the board and set the fan on top of the board. Also make sure nothing is in the M.2 slot in the board as it shares data lines with the SD card.
- In MCUXpresso IDE, open the app_config.h file and on line 23 change the #define for SENSOR_COLLECT_LOG to 1 as shown in the image below. This will put the firmware into data capture mode, so that the vibrations generated by the fan or motor will be stored on an SD card.

```
Project Explorer X IIII Registers 🎋 Faults 🚼 Peripherals+ 📅 🗖 🖟 version.h 🖟 *app_config.h X
                                         □ 🕏 ७ | ■ • 8
                                                                              1⊖ /*
2 * Copyright 2022-2023 NXP
 ✓ 👺 evkmimxrt1170_ml_state_monitor_mpp_cm7 < Debug>
                                                                                  * SPDX-License-Identifier: BSD-3-Clause */
   > Project Settings
> Includes
> CMSIS
   > A CMSIS driver
   > 🕮 board
> 🕮 component
   > 🔑 device
    > 🕮 drivers
                                                                                  * Application parameters
                                                                                 *This section provides a template for the application parameters.
*These application parameters can be configured to other supported values
*/
   > 🕮 freertos
                                                                             18 j /* SELECT data source: 0 - live accelerometer sensor data; 1 - static validation data */ 20 #define SOURCE_STATIC_ACCEL_DATA 0 21
   > 🕮 sdmmc
    sensors
                                                                           23 #define SENSOR_COLLECT_LOG_EXT 1
   ✓ ∰ source

→ ⊜ inf-eng
      > 🌦 models
                                                                            25 /* Available ML inference engines */
26 #define INFERENCE_ENGINE_TFLM 0
27 #define INFERENCE_ENGINE_GLOW 1
      > (=> sdcard

> (=> sensor

> (h) labels.h

    h app_config.h

    h FreeRTOSConfig.h

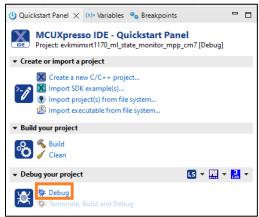
    c main.c
                                                                                 #define INFERENCE_ENGINE INFERENCE_ENGINE_TFLM
                                                                                  /* Available ML NN models for inference */
        semihost_hardfault.c
```

Next build the project by clicking on "Build" in the Quickstart Panel and make sure there are no errors.





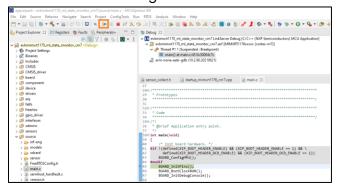
- 4. Plug the micro-B USB cable into the board at J11 on the i.MXRT1170 board.
- 5. Open TeraTerm or other terminal program, and connect to the COM port that the board enumerated as. Use 115200 baud, 1 stop bit, no parity.
- 6. Debug the project by clicking on "Debug" in the Quickstart Panel.



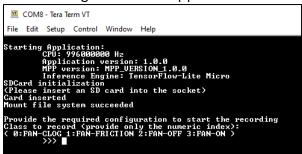
7. It will ask what interface to use. Select CMSIS-DAP.



8. The debugger will download the firmware and open up the debug view. Click on the Resume button to start running.



9. The following text should appear in the terminal program:





- 10. For this demo there are four fan states that are going to be detected:
 - FAN-OFF
 - FAN-ON (normal operation)
 - FAN-CLOG (something covering the fan so it does not get the normal airflow)
 - FAN-FRICTION (something creating drag on the blades like a piece of tape or cardboard)
- 11. Physically put the fan in the desired state. For this first run, lets put the fan into the normal ON state
- 12. In the terminal, type of the number of the fan state that corresponds with what the physical fan state is. So for this example, type '3' for FAN-ON.
- 13. The next selection is how many minutes to gather data. There is no hard and fast rule on how much data needs to be collected, but at a minimum several minutes worth will be required. For this simple example we'll select 5 minutes, but for more complex examples it could be significantly longer to ensure good training results. The ML-based System State Monitor Dataset Creation Guide provides a much deeper exploration into the optimal data collection techniques, but the key goal is to cover every corner case as much as possible and to not use the same data for training and validation.

14. Next give a filename where this data will be stored in CSV (Comma Separated Value) format. It can be any name but should be descriptive and cannot be more than 12 characters in length. For this example lets use fanon.csv

15. Finally, it will display your selections. Type 'y' to then start the data collection:



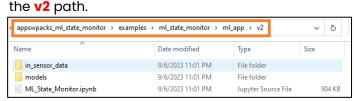
- 16. You will see the status as it collects the data.
- 17. Once completed, then you can either remove the SD card to look at the data on your computer or hit the Reset button on the board to start the process again to collect validation data for FAN-ON or to collect the other fan states. You'll want to collect data for all 4 conditions and collect both Training data and Validation data so there should be at least 8 runs. The same amount of data collection time should be used for all data sets.

5 Train Data and create a model

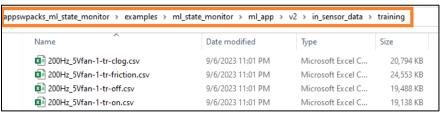
5.1 Copy Training Data to PC

Once all the data required has been saved to the microSD card, remove it from the RT1170 EVK and put it into a card reader for your PC so the data can be copied to the hard drive.

Inside the project folder there is a folder named
 \appswpacks_ml_state_monitor\examples
 \ml_state_monitor\ml_app\v2\in_sensor_data. Locate that directory. Make sure to use

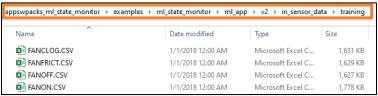


 Inside that folder there are two subfolders, one named training and the other validation. By default they contain pre-created data store in .csv files that were gathered from a simple 5V fan.



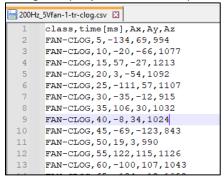


3. These files should be deleted, and the newly collected data placed inside these folders in order to create a new custom model. The file name does not matter but should end in .csv. The files should cover all the possible classes and should be updated for both the **training** and **validation** folders with their respective training and validation data.



If you did not collect new data, you can use the pre-existing .csv files as that has data collected with a simple 5V brushless DC motor.

4. The Python scripts that will be used in the next section will assume the files will be in the following Comma Separated Value format, which is how the data was written to the files by using the projects from the previous section, so no modifications should be needed.



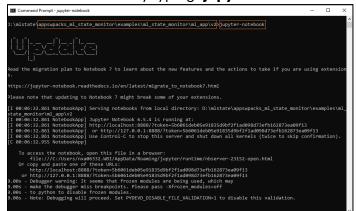
5.2 Train The Model

With the data ready, now use the Jupytr notebook to train the model.

- 1. Open a Windows command prompt
- 2. Navigate to the

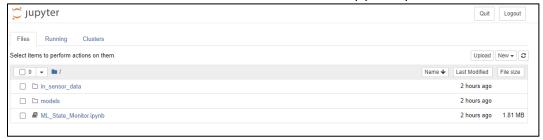
\appswpacks_ml_state_monitor\examples\ml_state_monitor\ml_app\v2\
directory

3. Start the notebook by typing "jupyter-notebook" into the command prompt





4. A web browser window should automatically open up and look like the following. If it does not, there are links in the terminal window that can be copy and pasted into a browser.

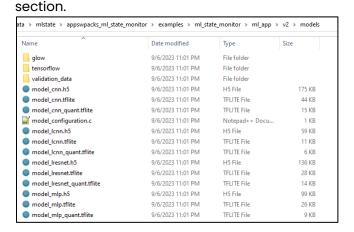


- 5. Click on ML_State_Monitor.ipynb to open the notebook
- 6. It will look like the following. Press the **Run** button to execute each section of the script. While executing an asterisk (*) will appear and the dot in the upper right will be dark. Don't press Run again until the previous section has finished executing.



- 7. You may see some warning messages when executing certain blocks of the script but you should not get any error/failure messages.
- 8. The end of the script will export the models to \appswpacks_ml_state_monitor\examples\ml_state_monitor\ml_app\v2\models.

 There will also be C array versions of those models in the tensorflow directory and Glow compiled versions of those models in the glow directory. Those files will be used in the next

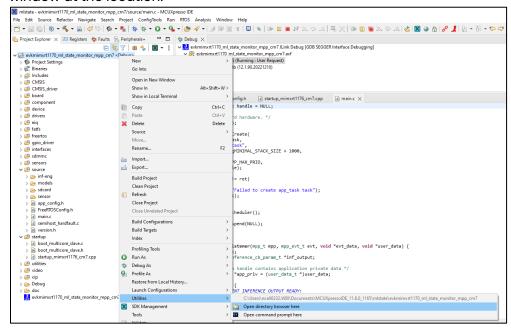




6 Update Model for Inference Engines

It is now possible to use all 3 elQ inference engine options for microcontrollers (TFLM, Glow, and DeepViewRT) to run this newly created model on the i.MX RT1170 EVK.

First find the location on your PC where the ML-based system state monitor application
resides after it was imported into MCUXpresso IDE in the previous section. So inside
MCUXpresso IDE, right click on the evkmimxrt1170_ml_state_monitor_cm7 project name
and go down to Utilities and select Open directory browser here to open a Windows Explorer
window at the location.

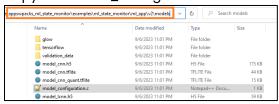


6.1 Update Model Configuration File

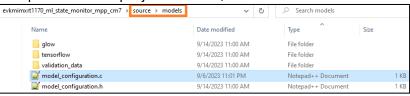
1. Some pre-processing parameters for your data was generated during the training phase and put into a file at

\examples\ml_state_monitor\ml_app\v2\model_configuration.c. This new file needs to replace the default model_configuration.c file in the project under **\source\models**.

2. Copy the model_configuration.c file from:



And put it into the project source \models folder:

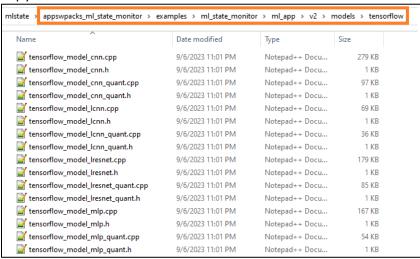




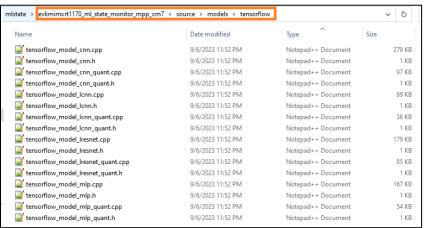
6.2 TensorFlow Lite for Microcontrollers

- 3. The Jupyter notebook already has created the C files needed by the TFLM inference engine, so those newly generated files just need to replace the default files in the project
- 4. Navigate to the <MCUXpresso IDE Workspace>/source/models/tensorflow directory.
- Copy the generated .h and .cpp files from the previous section that were placed in the \examples\ml_state_monitor\ml_app\models\tensorflow\ folder and paste them into this directory.

Copy from:



Paste into:



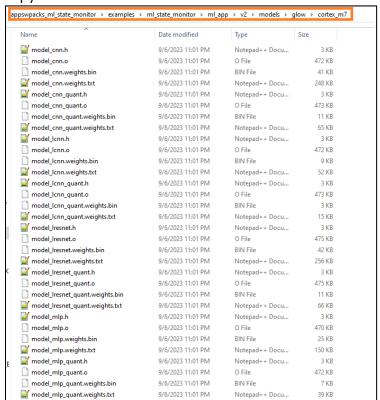
6.3 Glow

- The Jupyter notebook already has created the Glow bundled needed by the Glow inference engine, so those newly generated files just need to replace the default files in the project. For details on the exact commands used to generate the Glow bundle see cell 29 in that Jupyter notebook.
- 2. Navigate to the <MCUXpresso IDE Workspace>/source/models/glow directory.

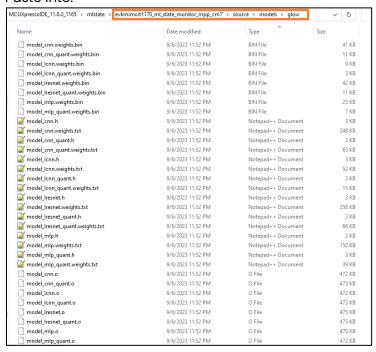


3. Copy the Glow bundle files from the previous section that were placed in the **\examples** \ml_state_monitor\ml_app\v2\models\glow\cortex_m7 folder and paste them into this directory. Note that you should select the directory in that folder that corresponds with the core architecture in the device that will be used.

Copy from:



Paste into:





7 Deploy Model To Board

Now the models can be executed on the i.MX RT1170 EVK.

- 1. In MCUXpresso IDE, the **evkmimxrt1170_ml_state_monitor_cm7** project should already be imported into your workspace from the previous data collection section.
- Open the app_config.h file under source folder by double clicking on it. The modify line 23 to change the #define SENSOR_COLLECT_LOG_EXT to 0 to tell the project to now run the inference of the model

```
□ □ In version.h In *app_config.h × Ic startup_mimxrt1176_cm7.cpp
Project Explorer 🗴 👭 Registers 🔅 Faults 🚼 Peripherals+
                                   □ $ 7 | # % | ■ ▼ 8
                                                                      * Copyright 2022-2023 NXP
evkmimxrt1170_ml_state_monitor_mpp_cm7 < Debug>
 > Project Settings
                                                                      * SPDX-License-Identifier: BSD-3-Clause
  > 🖓 Binaries
 > 🔊 Includes
                                                                  7 #ifndef _APP_CONFIG_H
8 #define _APP_CONFIG_H
 > 🕮 CMSIS
 > 🕮 CMSIS_driver
 > 🕮 board
                                                                 > 🐸 component
 > 🕮 device
 > 🕮 drivers
 > 🕮 eia
                                                                 15 * This section provides a template for the application parameters.
16 * These application parameters can be configured to other supported values
 > 🕮 fatfs
  > 🕮 freertos
  > 🕮 gpio_driver
                                                                 19 /* SELECT data source: 0 - live accelerometer sensor data; 1 - static validation data */
  interfaces
                                                                 20 #define SOURCE_STATIC_ACCEL_DATA 0
  > 🎮 sdmmc
  > 🕮 sensors
                                                                                                         nference; 1 - run SD log data capturing */
                                                                23 #define SENSOR_COLLECT_LOG_EXT 0

✓ 

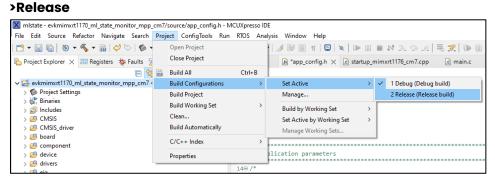
Source

    > 📂 inf-eng
                                                                 25 /* Available ML inference engines */
    > 📂 models
                                                                 26 #define INFERENCE ENGINE TFLM 0
    > 📂 sdcard
                                                                 27 #define INFERENCE_ENGINE_GLOW 1
      😕 sensor
   > h app_config.h
                                                                    /* SELECT the ML inference engine *
       h FreeRIOSConfig.h
                                                                 30 #define INFERENCE_ENGINE INFERENCE_ENGINE_TFLM
                                                                 32 /* Available ML NN models for inference */
     > 底 semihost_hardfault.c
                                                                 33 #define MODEL_CNN
34 #define MODEL_CNN
```

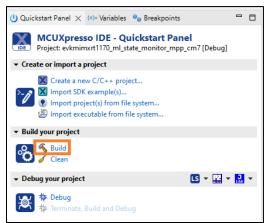
3. There are several other options to modify the inference engine between Glow and TFLM on line 30. By default the project will use TensorFlow Lite for Microcontrollers. It is also possible to select the desired model on line 39. Also a quantized version of the model can be selected on line 42. For the purposes of this lab none of these lines should be changed though.



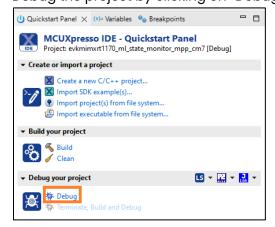
4. If using TensorFlow Lite for Microcontrollers, make sure to set the Build Configuration to the "Release" target which does a high compiler optimization. This setting has a minor effect when using Glow or DeepViewRT but significantly reduces inference time when using TFLM. Click on the project name and then go to Project->Build Configurations->Set Active-



Next build the project by clicking on "Build" in the Quickstart Panel and make sure there are no errors.

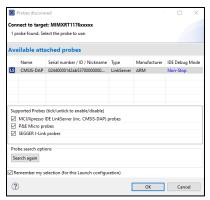


- 5. Plug the micro-B USB cable into the board at J11 on the i.MXRT1170 board.
- 6. Open TeraTerm or other terminal program, and connect to the COM port that the board enumerated as. Use 115200 baud, 1 stop bit, no parity.
- 7. Debug the project by clicking on "Debug" in the Quickstart Panel.

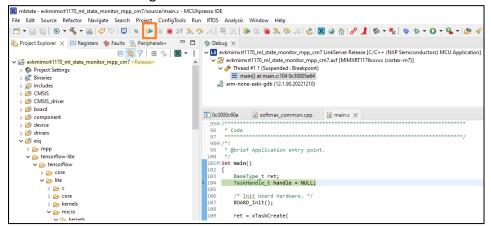




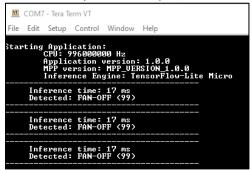
8. It will ask what interface to use. Select CMSIS-DAP.



9. The debugger will download the firmware and open up the debug view. Click on the Resume button to start running.



10. The following text should appear in the terminal program and the current state detected will continue to print out. Try the fan in different states and see it change.



8 Conclusion

This lab demonstrated how to gather and train sensor data to a classification model and deploy it on an i.MX RT device.

This same lab can be used for other types of sensor data models that detect vibrations. By enabling machine learning in embedded systems, there's a wide world of opportunity for new smarter applications.