

AUTOSAR Adaptive Software Framework for NXP's S32 Platform

Marius Rotaru (NXP)

Automotive Software Architect & Technical Director

Christoph Dietachmayr (Elektrobit)

Solution Manager – Car infrastructure Automotive Software

October 2019 | Session #AMF-AUT-T3834



SECURE CONNECTIONS
FOR A SMARTER WORLD

Agenda

- Introduction to Adaptive AUTOSAR
- NXP's Approach to AUTOSAR Adaptive Platform
- Elektobit's Adaptive AUTOSAR Solution for NXP Platform
- Q&A

Vehicle Architectures

Safe and Secure Mobility the semi value per car – today's standard car at \$380

Autonomy



- Different sensor types
- Data fusion:
 - Safe Processing with
 - Integrated AI capabilities
- Fail operation
- Big Data

Electrification



- Power Efficiency
- Battery Management
- Electrification Levels
 - Hybrid, full electric...
- Broad range of solution
- Need for standardization

Connectivity



- V2X, 5G, Digital Radio
- Prognostic Health Management
- OTA Update Management
- Analytics (edge to cloud)
- Software-centric solutions
- System security

Major Changes in Network Topology and E2E Architectures

Mega Trends Force Vehicle Architecture Transformation

Today: Flat



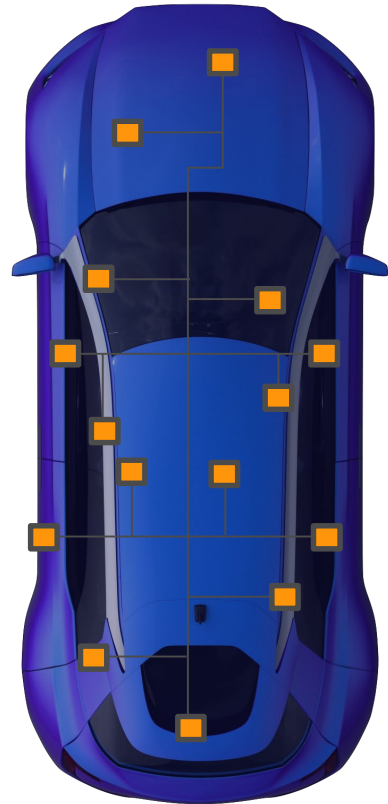
Flat to hierarchical

Tomorrow: Domains



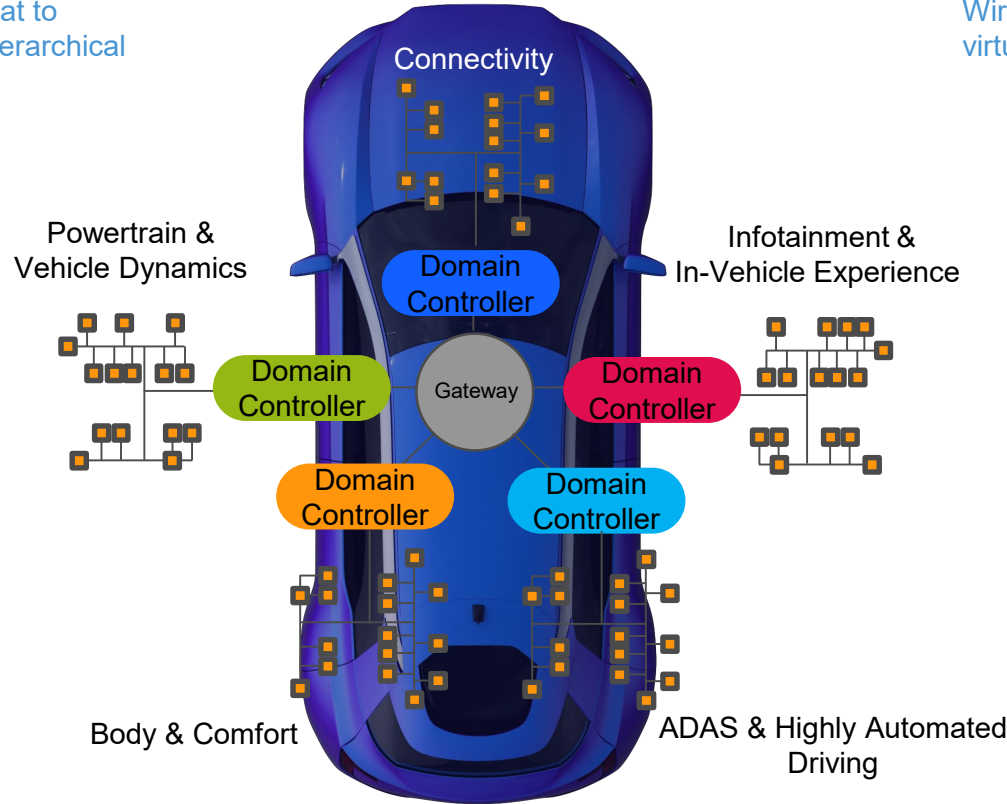
Wires go virtual

After Tomorrow: Zones



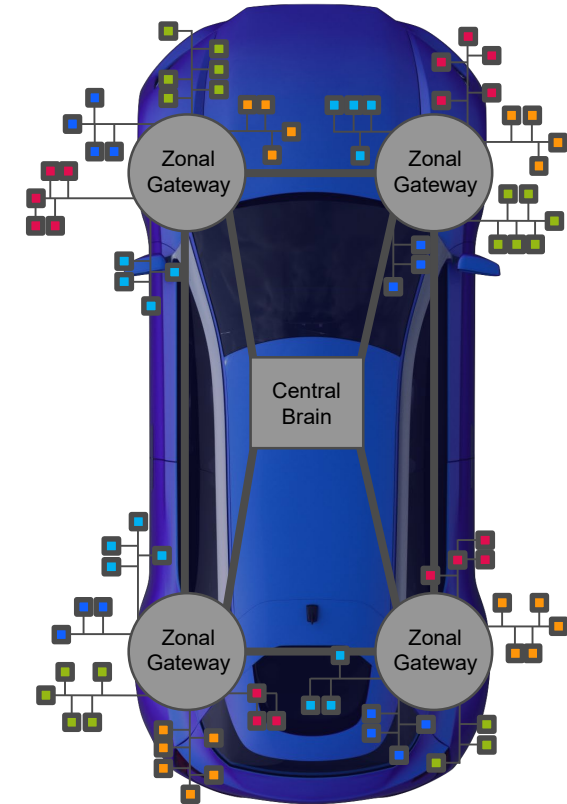
Low bandwidth, flat network
One MCU per application

Unfit for future mobility



High bandwidth network
Gateway key to communication between domains

Step to autonomous car



Domains virtualized by SW – enabling high flexibility
Easy enable/disable or update functions

Step to user-defined car

Vehicle Architectures

Mega Trends: Embedded Software become Software semi value per car – today's standard car at \$380

Technology Trends



Autonomy



Electrification

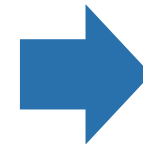
Connectivity



E/E Implication

- ECU Platform
- Topology
- Communication

- OSEK/VDX
- Signal Comm
- Static configuration



- Rich Operating Systems (e.g. Linux)
- Service Oriented Architecture
- Dynamic configuration

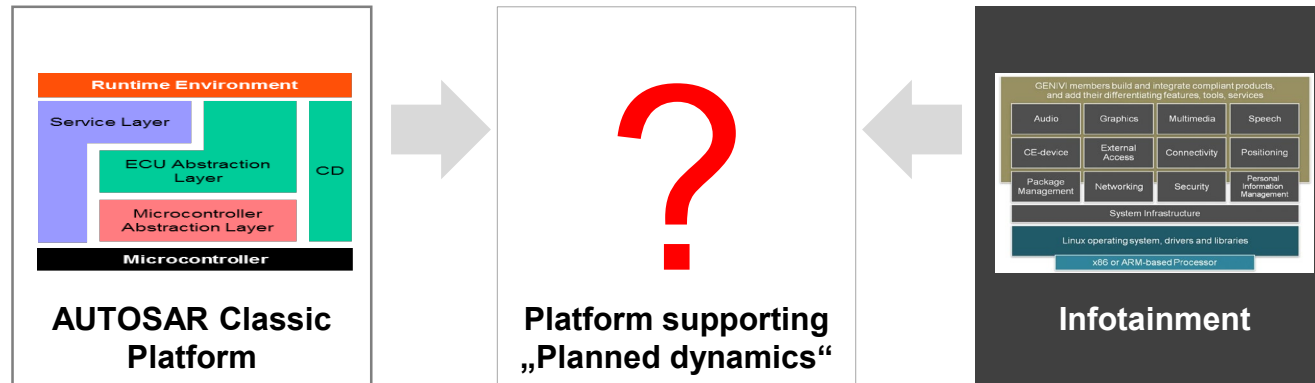
Adaptive Platform
AUTOSAR

AUTOSAR Adaptive – Motivation

Another Platform for Different Applications

Real time requirements

Safety criticality

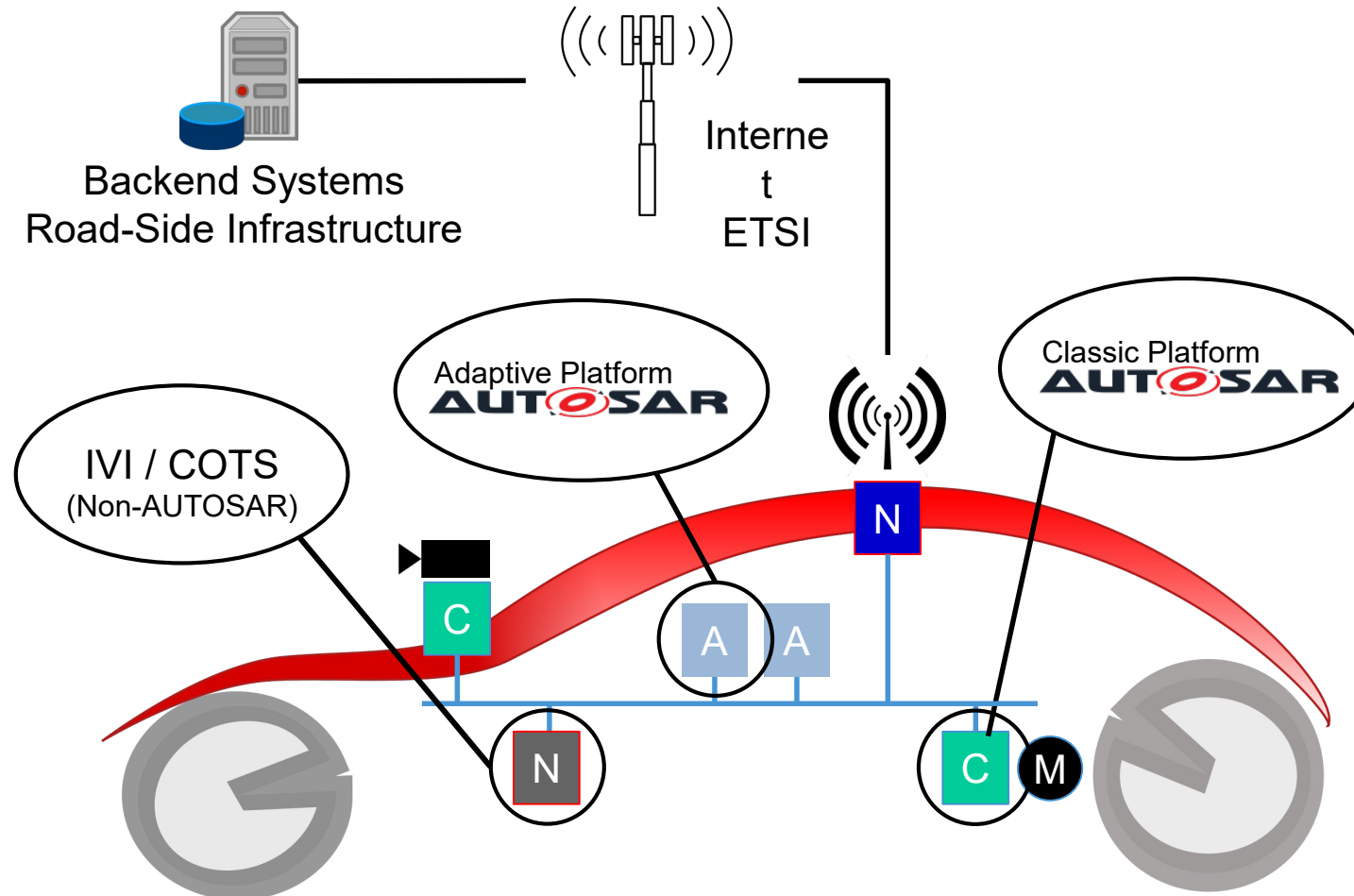


Computing power

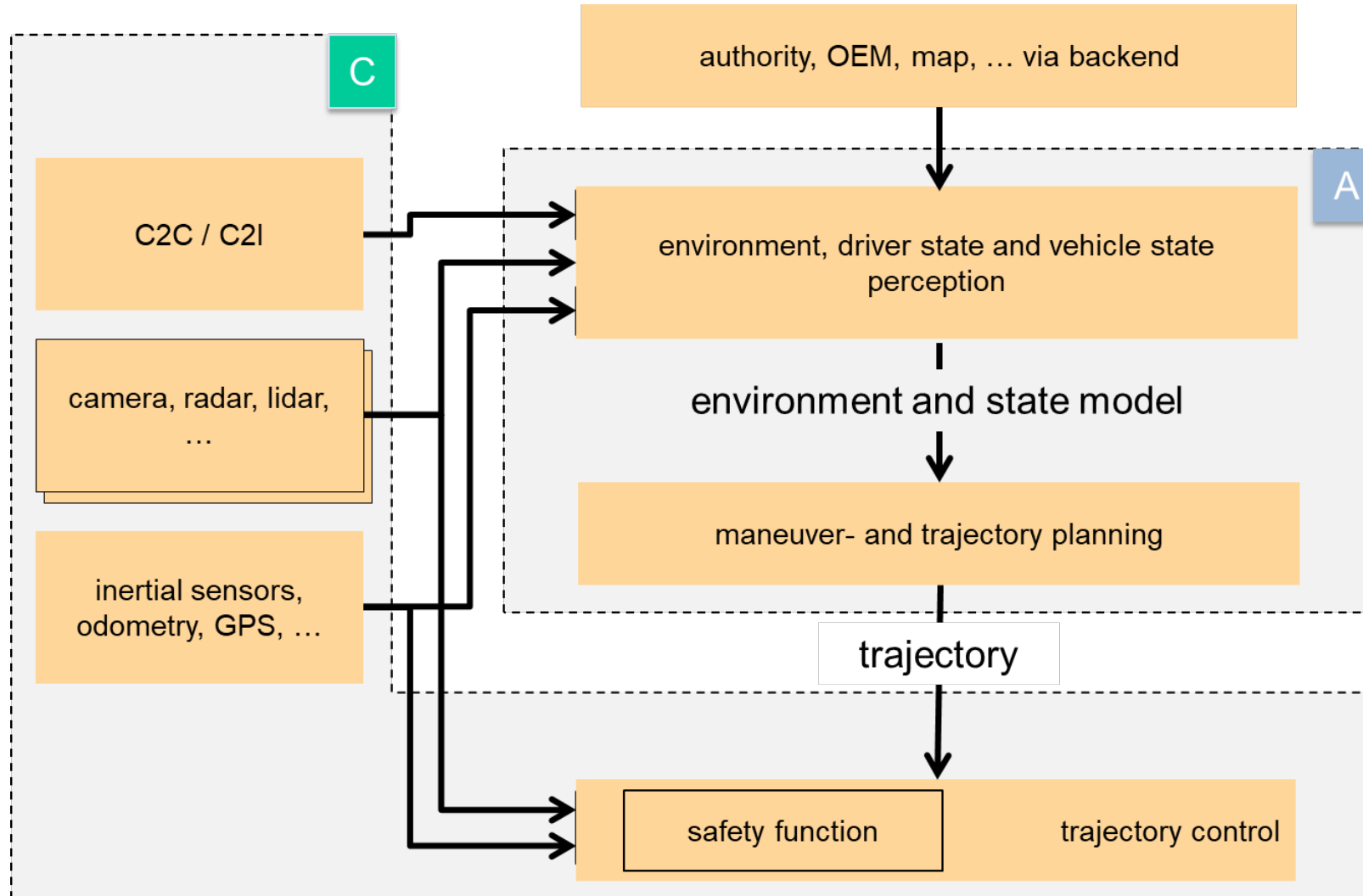
Real time Requirements	High, in the range of micro-sec	Mid, in the range of milli-sec	Low, in the range of sec
Safety Criticality	High, up to ASIL-D	High, at least ASIL-B	Low, QM
Computing power	Low, ~ 1000 DMIPs	High, > 20.000 DMIPs	High, ~ 10.000 DMIPs

Adaptive Platform – Comprehensive System Design

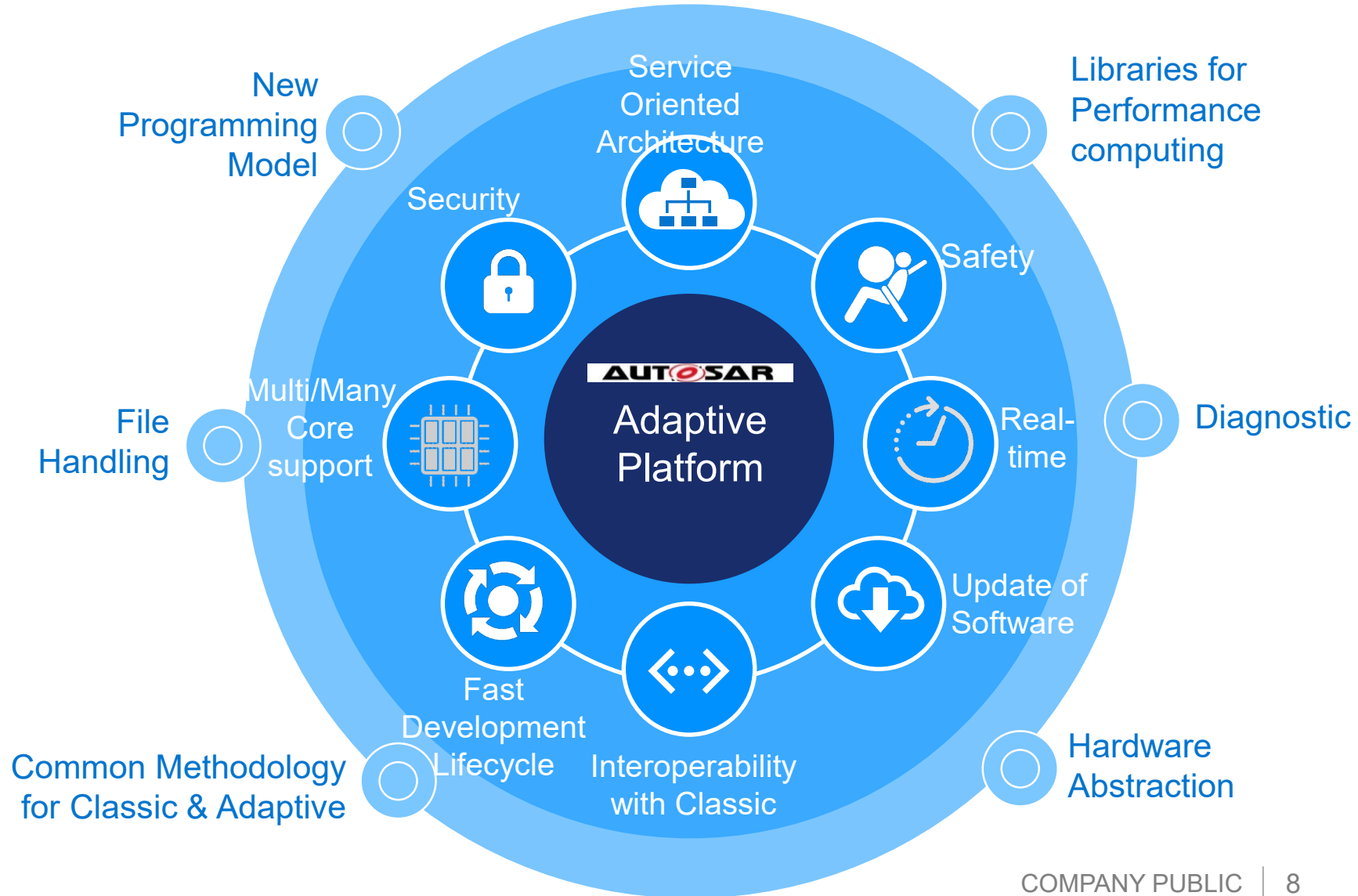
Integration of Classic-, Adaptive- and Non-AUTOSAR ECUs



Adaptive Platform – Architecture Logical View



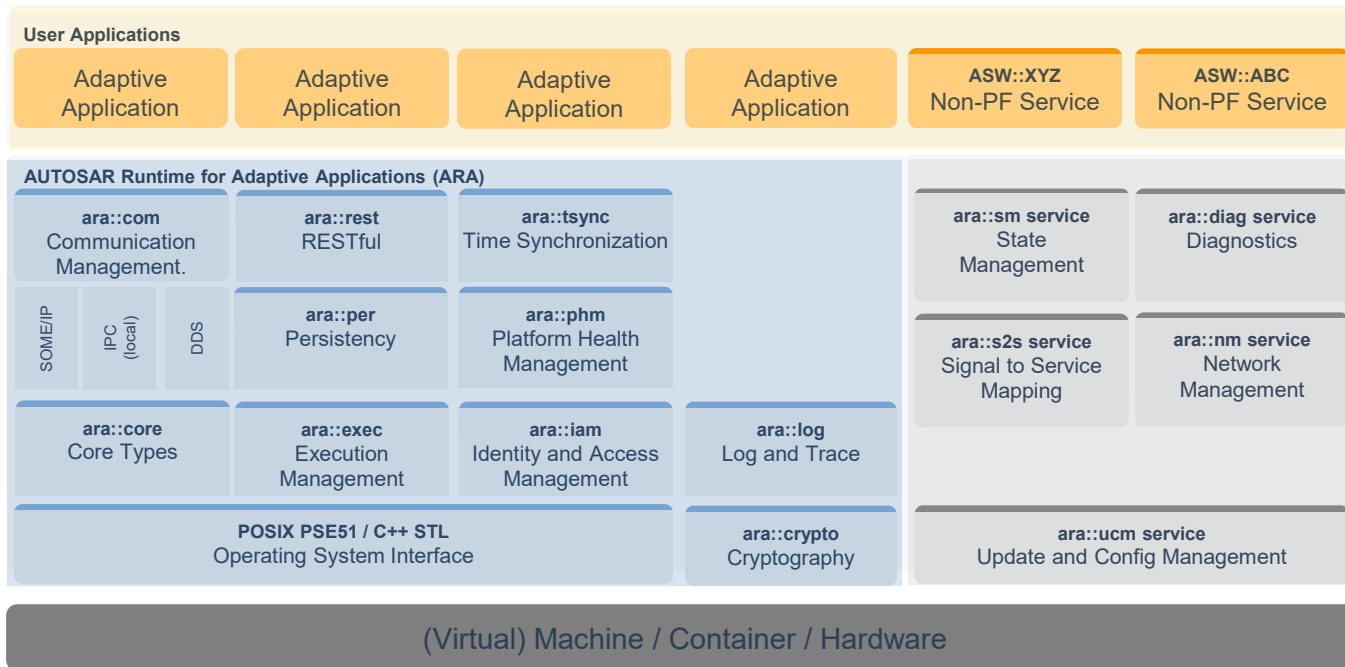
Adaptive Platform – Main Requirements



Adaptive Platform – Functional Clusters

AP Foundation

- Fundamental functionalities for AP
- Locally used by one AP instance
- Comparable BSW to CP

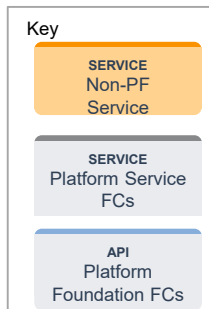


Application

- AAs run on top of ARA
- PSE51 API restricted

AP Services

- Standard services of AP
- Locally and/or remotely accessible by different AP instances



ATOSAR Runtime for Adaptive Applications = Σ of all Functional Cluster APIs / Services

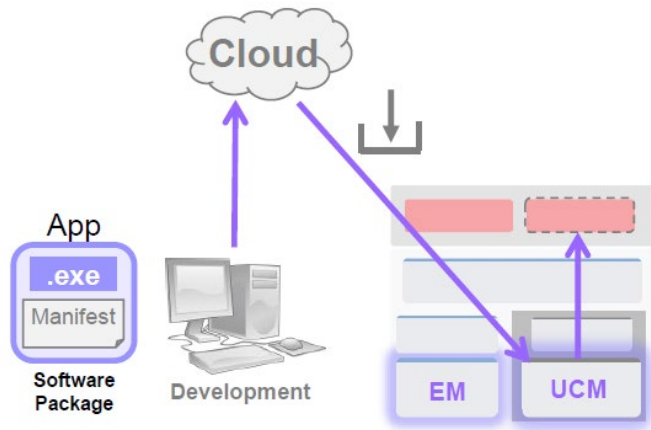
API or Service Interface of a Functional Cluster.

- Programming language specific API for a Functional Cluster as specified in SWS
- The first programming language supported by the Adaptive Platform will be C++

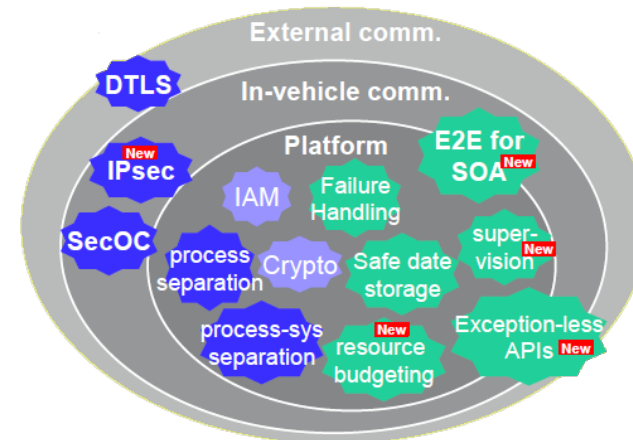
Adaptive Platform – Key Aspects



Dynamic & Updatable



Safe & Secure



Adaptive Platform – Strategy

Specifications

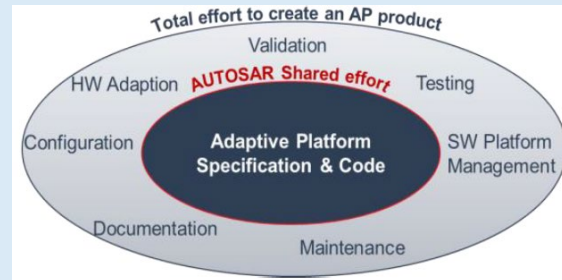
Identify needs & use-cases



Concepts, Features, Requirements

Reference Code

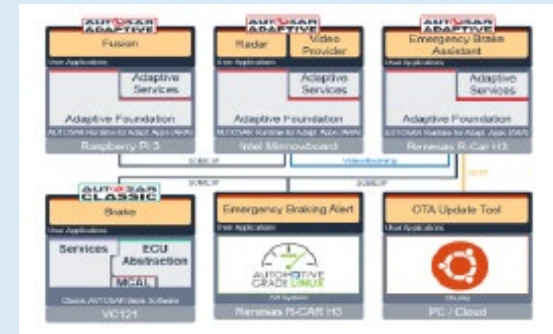
Specification validation
Training/dissemination of AP



Attracting environment for coders

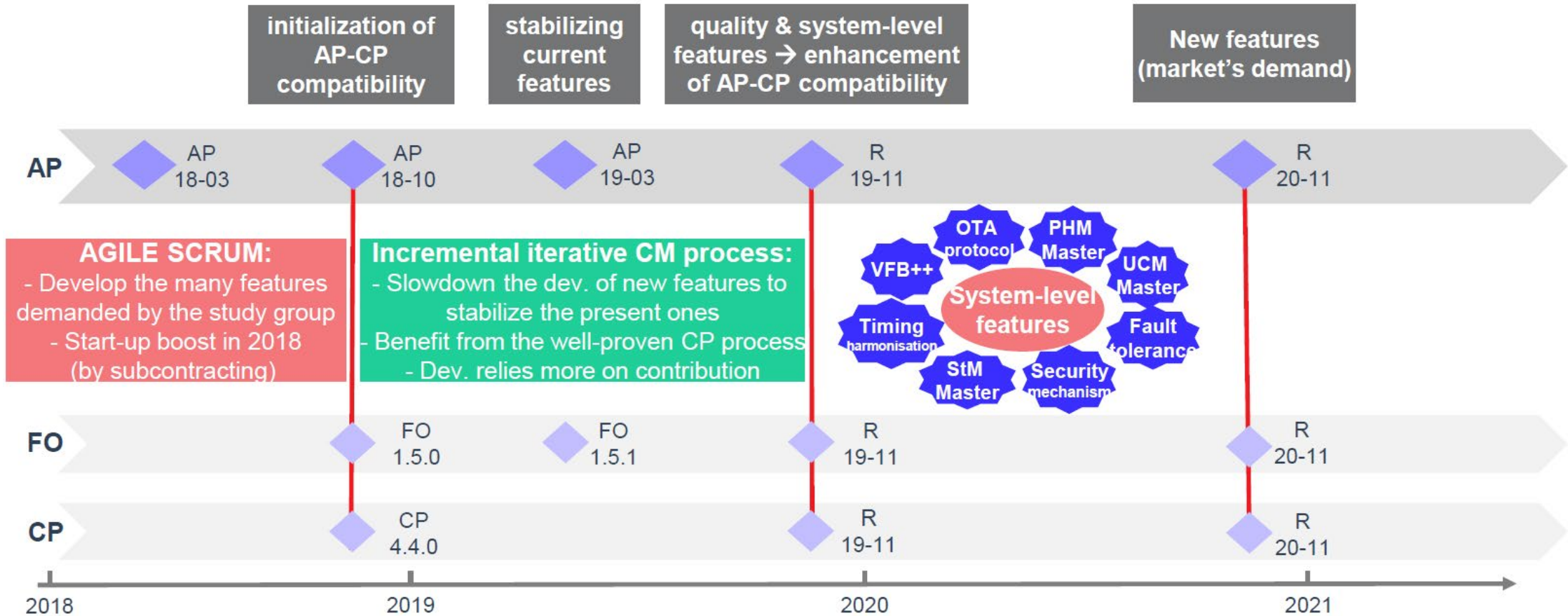
Platform Demonstrator

Highlights specific features
Prove interoperability



Showcase

Adaptive Platform – Roadmap

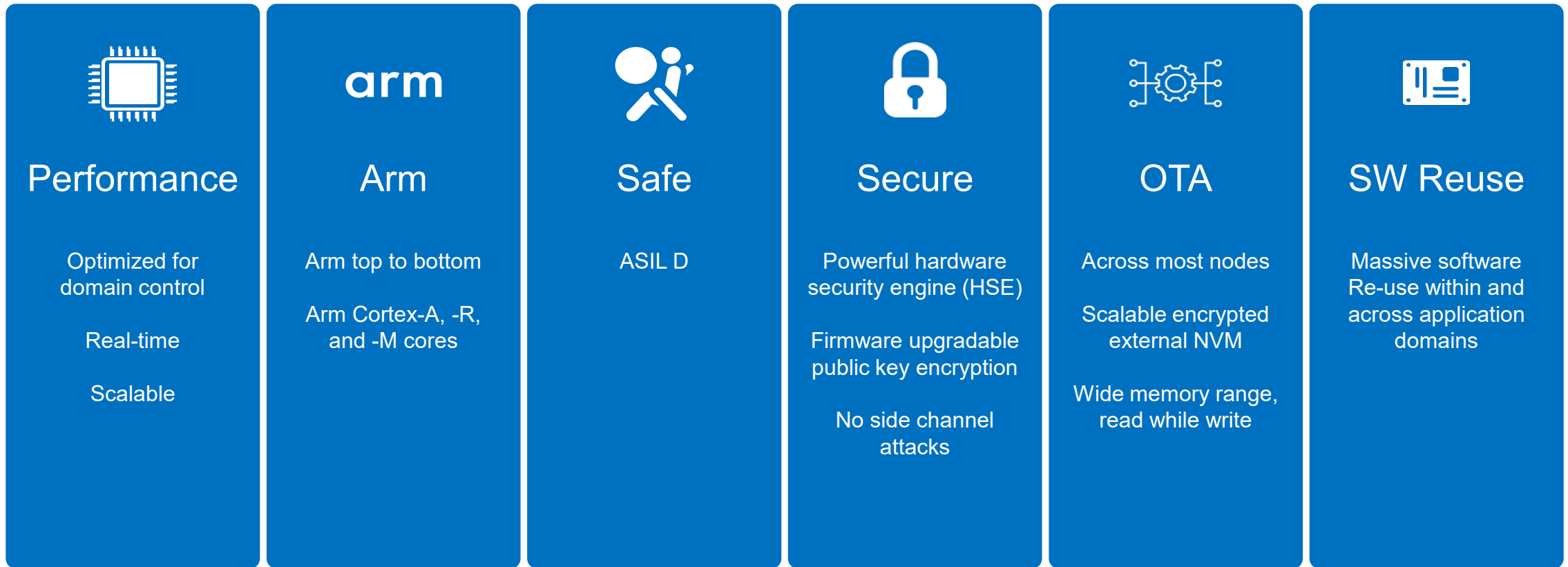


Source: **AUTOSAR**, Alan Belferrag
Adaptive AUTOSAR presentation at 11th AUTOSAR Open Conference

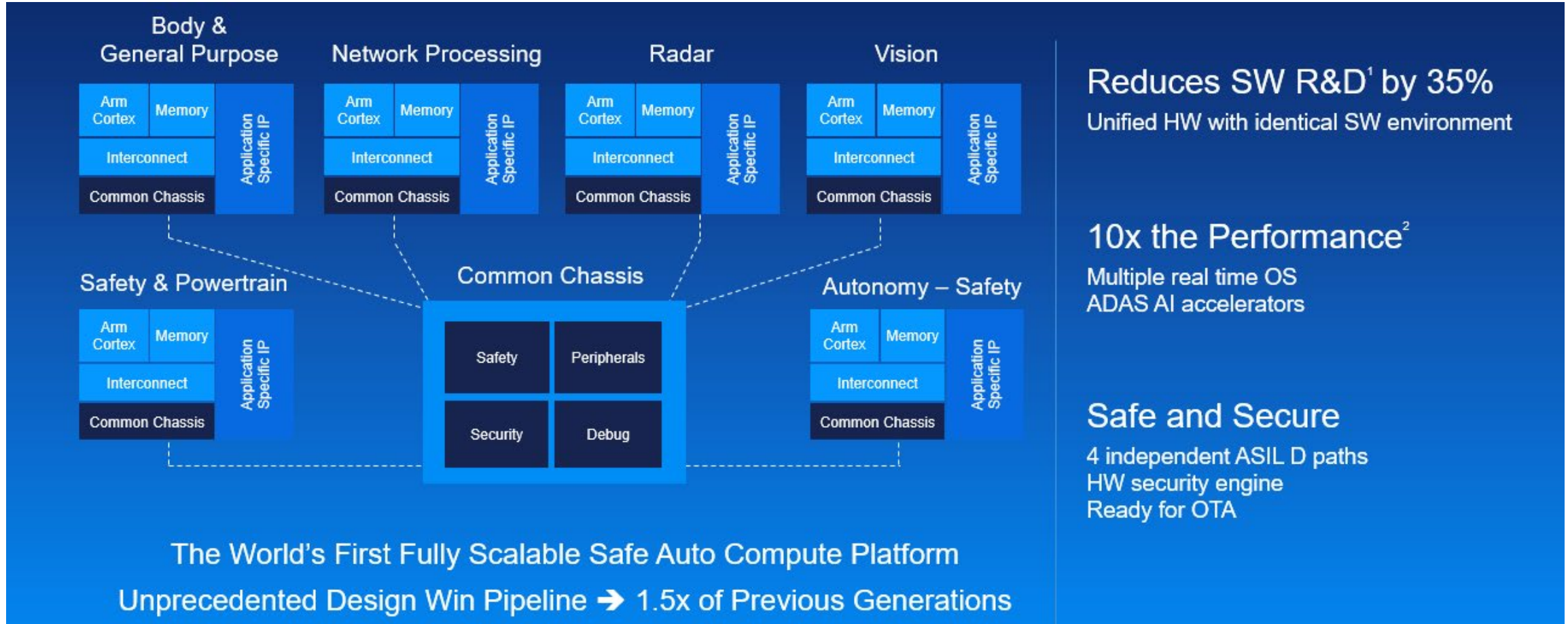
NXP's Approach to AUTOSAR Adaptive Platform



Auto Processors Tomorrow – Domain Architecture Requirements

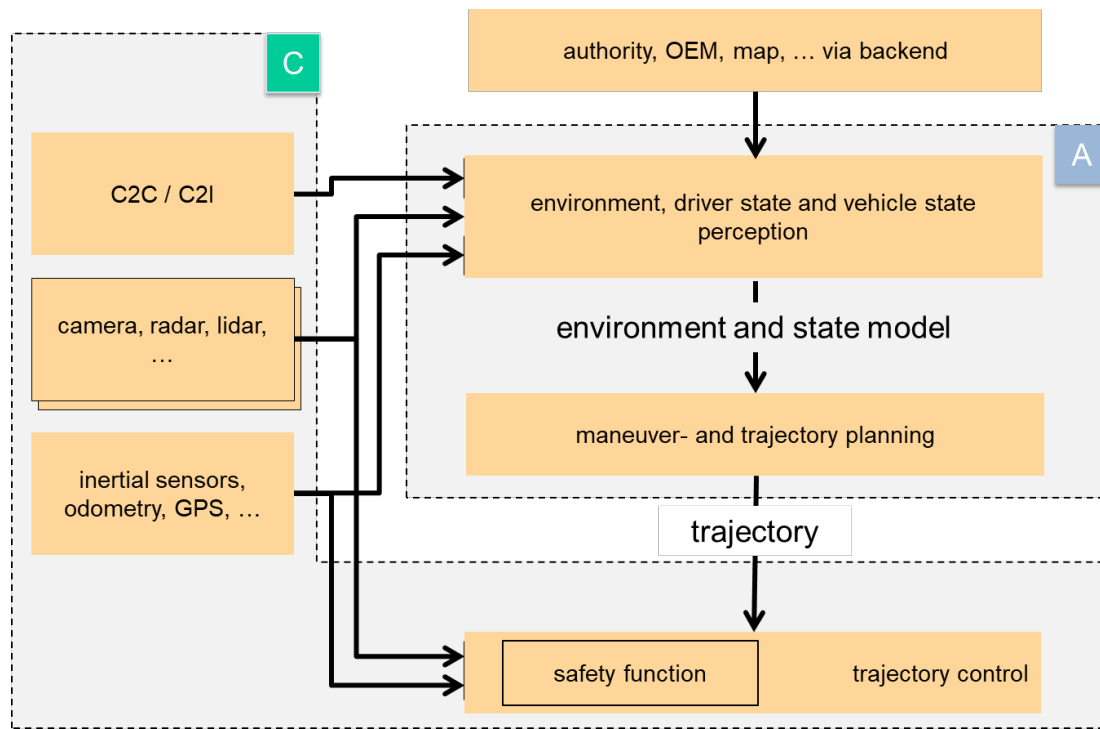


Auto Processors Tomorrow – NXP’s Unique S32 Platform



1. Based on analysis of existing NXP Software code in existing customers' applications
 2. Based on publicly available competitor roadmap performance statements versus today's best safe auto platform

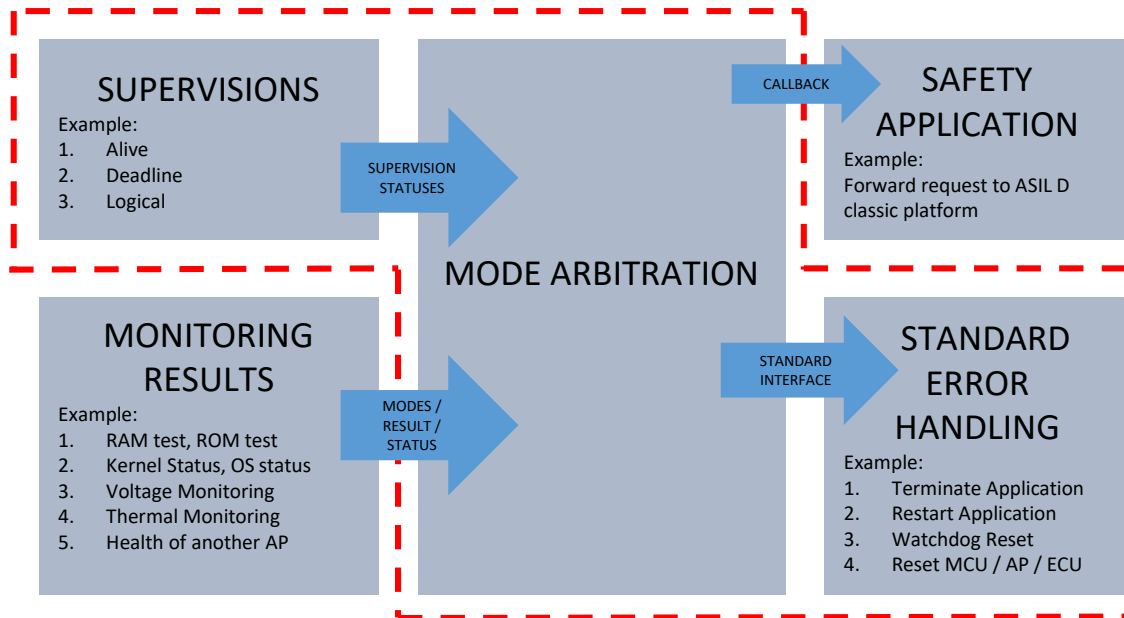
Auto Processors Tomorrow – NXP's Unique S32 Platform



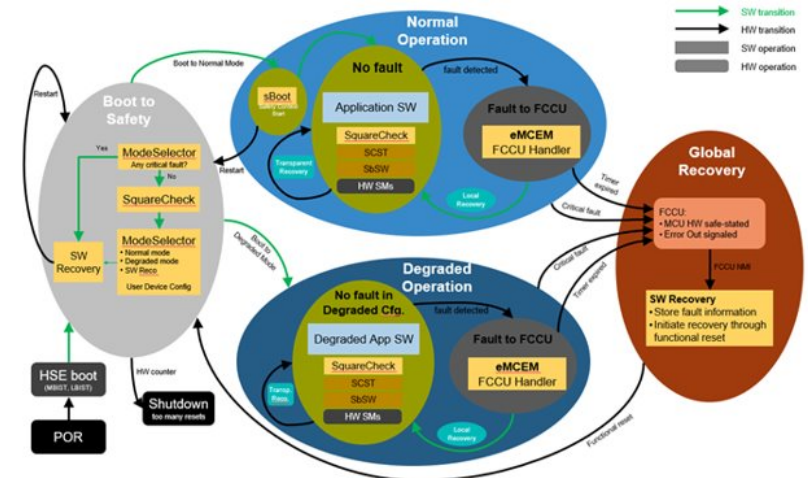
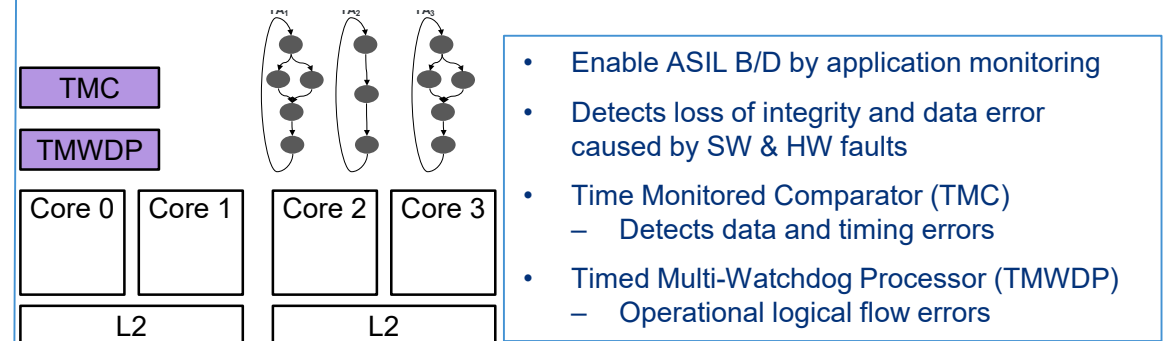
NXP's S32 – Scalable Safe Auto Compute Platform

Auto Processors Tomorrow – NXP’s Unique S32 Platform

AUTOSAR Adaptive – Platform Health Monitoring



S32 Safety (by Software) Concept

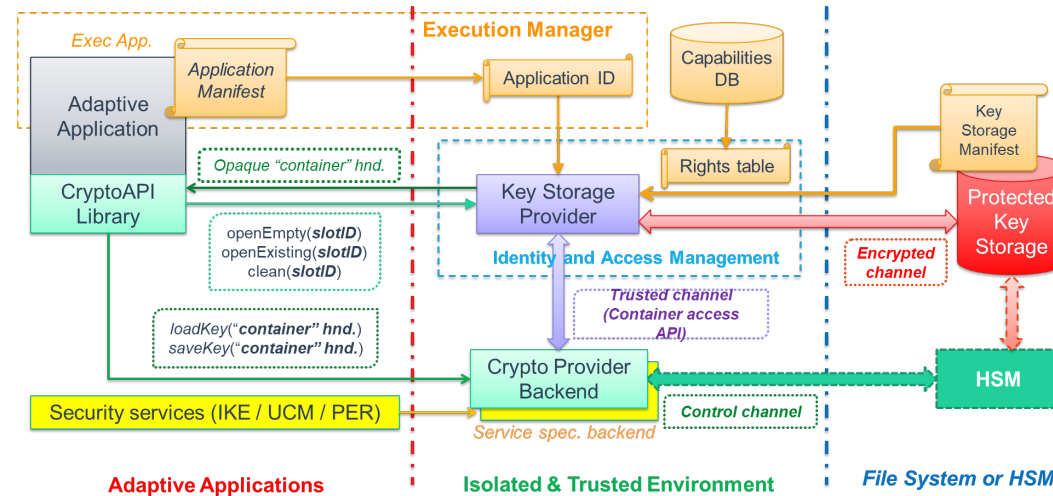
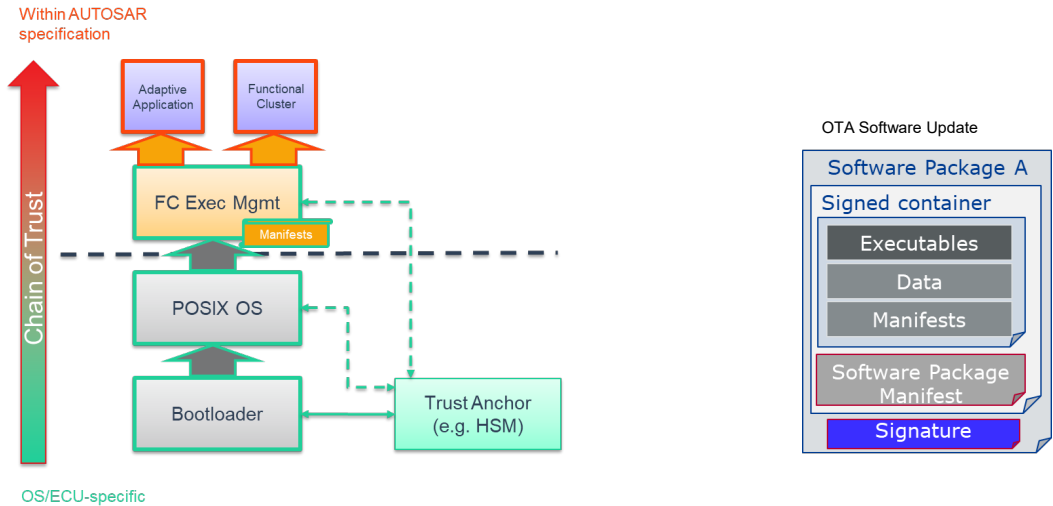


Safety by Software (SbSW) concept: <https://community.nxp.com/docs/DOC-343700>

NXP’s Safety Concept with the patented Safety by Software (SbSW) method, for performance cores, to efficiently enable the AUTOSAR Classic and Adaptive Platform Health Monitoring & Safety.

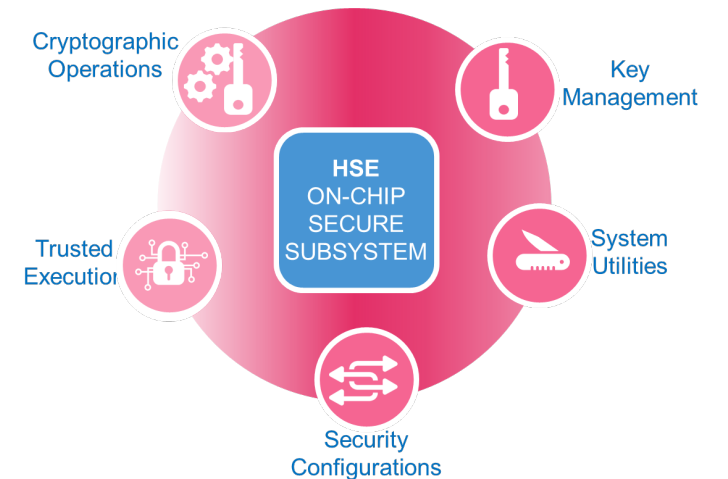
Auto Processors Tomorrow – NXP’s Unique S32 Platform

AUTOSAR Adaptive - Trusted Platform and the Security Stack



S32 HSE – More than a Cryptographic Engine

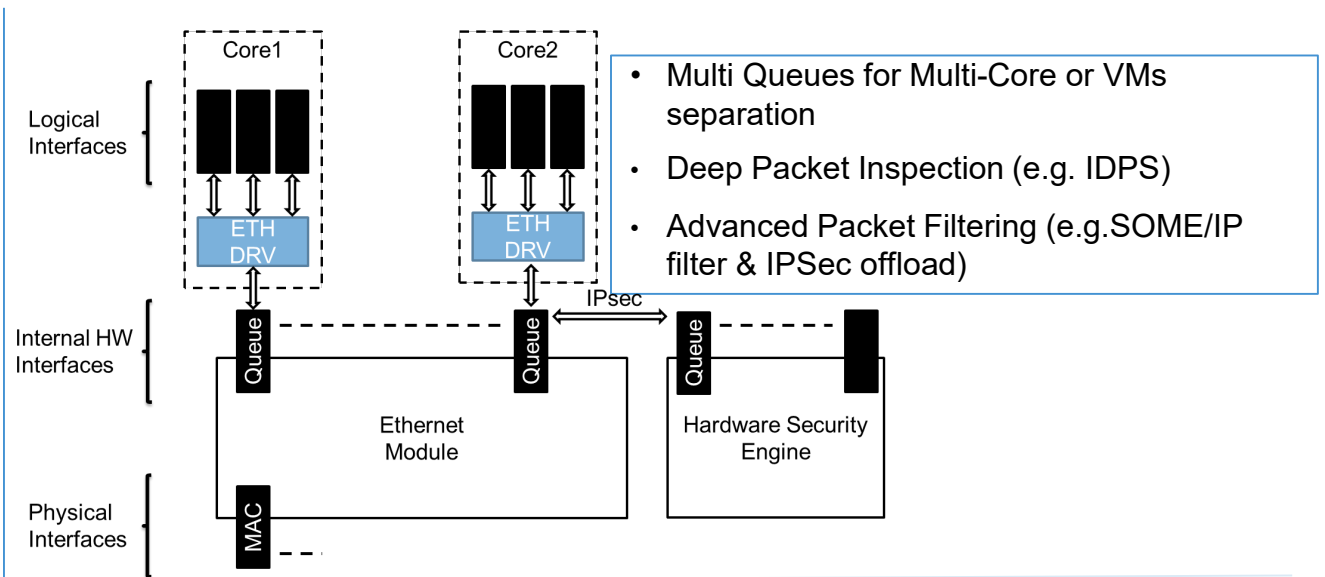
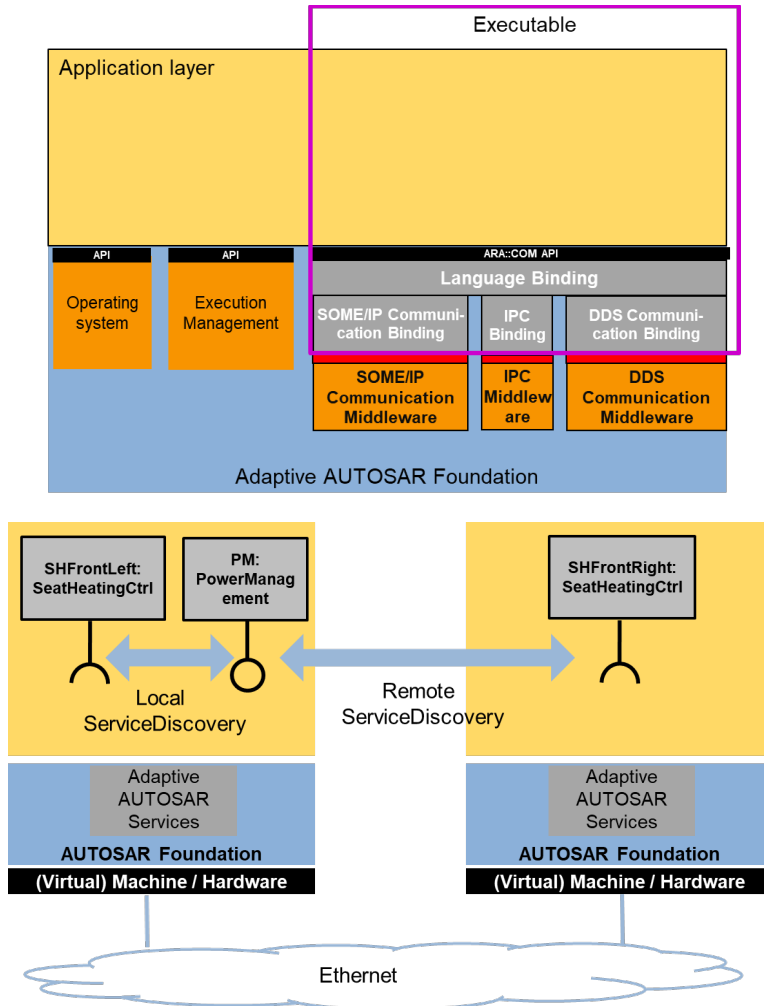
- Accelerates**
Cryptographic operations
- Offloads**
the app with a dedicated intelligence
- Establishes Trust**
Secure Boot + Root of Trust
- Controls**
The platform
- Easily Integrates**
In your design



Auto Processors Tomorrow – NXP’s Unique S32 Platform

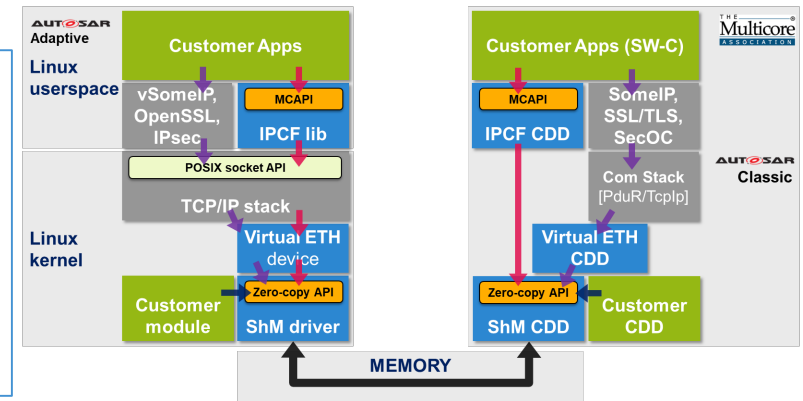
AUTOSAR Adaptive – Service Oriented Communication

S32 Ethernet Module & IPCF solution



- Multi Queues for Multi-Core or VMs separation
- Deep Packet Inspection (e.g. IDPS)
- Advanced Packet Filtering (e.g. SOME/IP filter & IPsec offload)

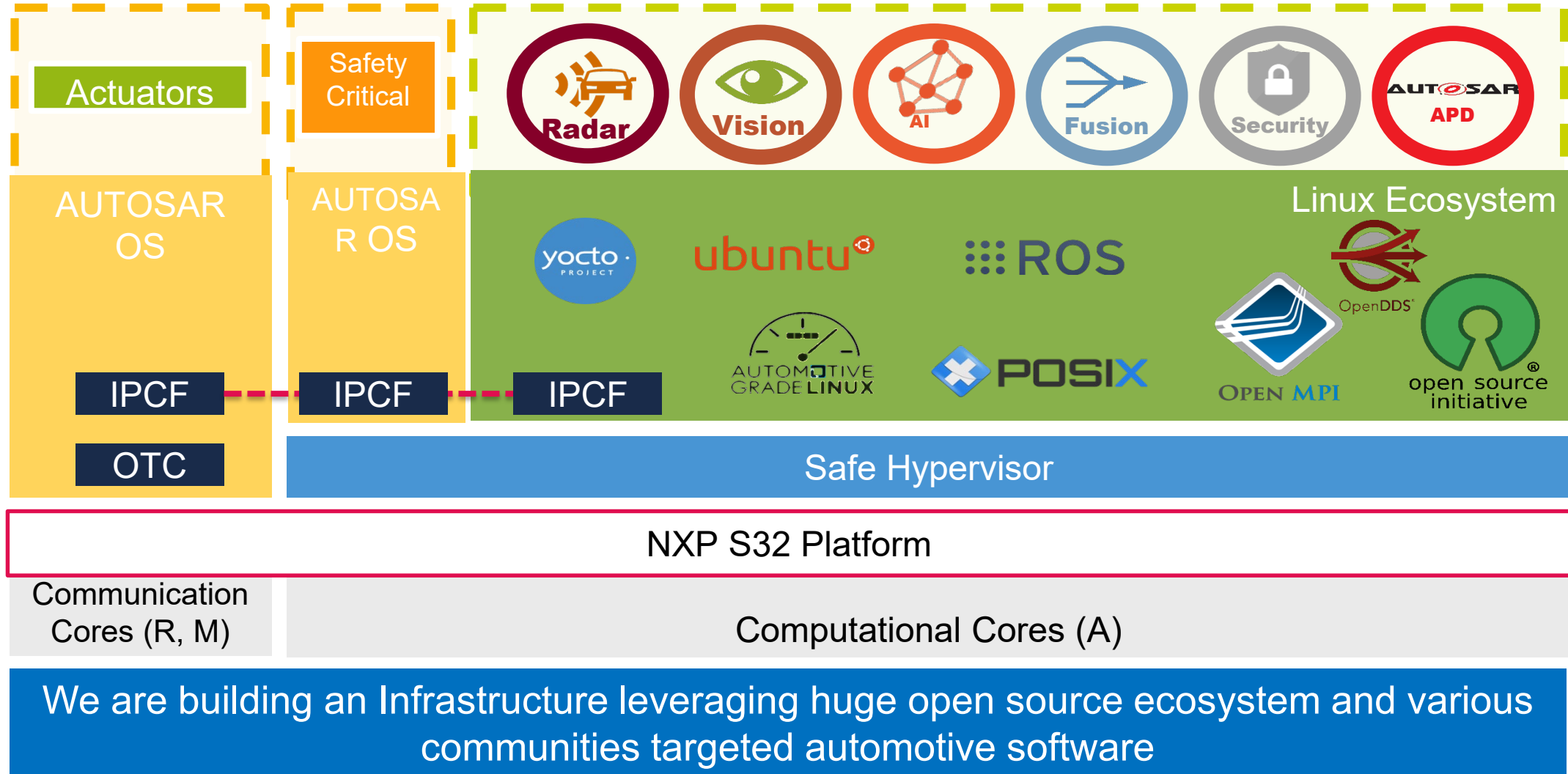
- Performance (zero-copy)
- Freedom from interference (ASIL-D)
- MCAPI over Shared Memory (SHM)
- Virtual Eth over SHM and PCIe
- OS/HW agnostic



S32 IPCF: <https://community.nxp.com/docs/DOC-334836>
 S32 SoA: <https://community.nxp.com/docs/DOC-343674>

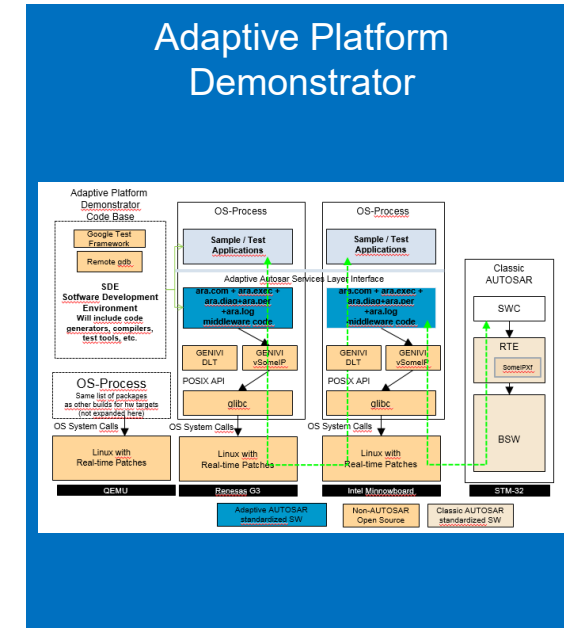
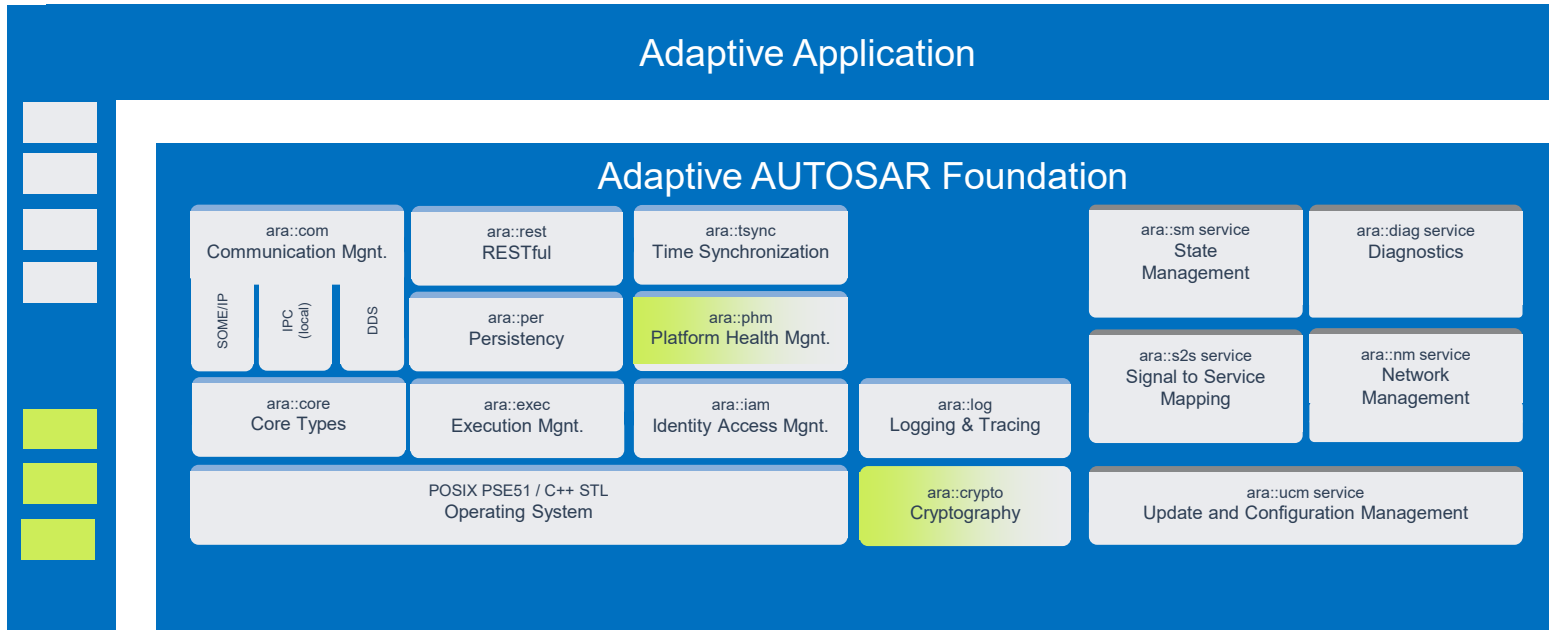


Software Infrastructure for AUTOSAR Adaptive Platform

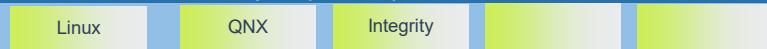


Software Infrastructure for AUTOSAR Adaptive Platform

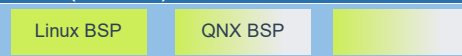
Adaptive AUTOSAR ready to use/build ecosystem



OS Abstraction Layer (OSAL)



OS (+ BSP)

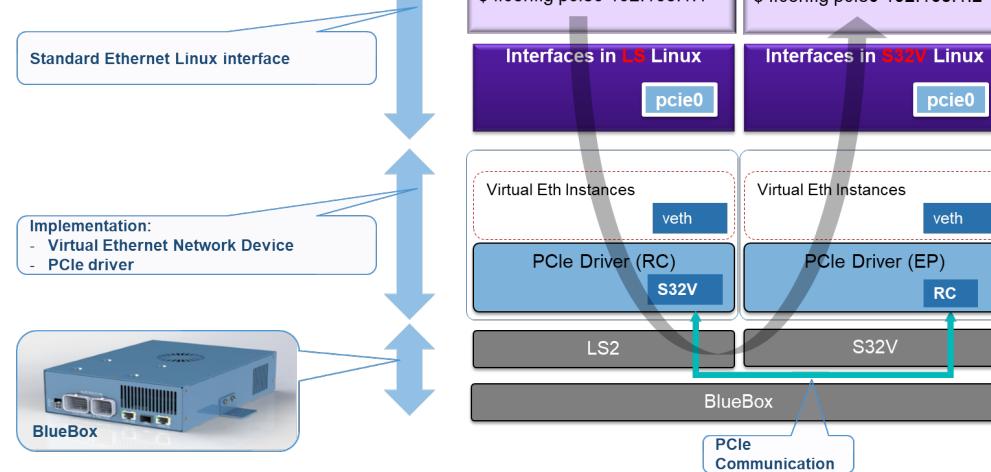


- Green: NXP Develop
- Light Green: NXP and/or 3rd party
- Grey: 3rd party

NXP Bluebox: Central Processing Unit For Autonomous Driving

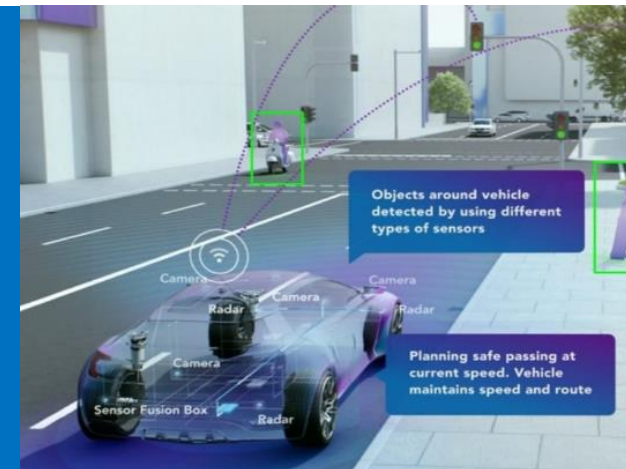
- **Highly Optimized Safe Central Compute**
 - Various sensor data streams: Radar, Vision, LiDAR, V2X
 - S32V234 automotive vision and sensor fusion processor
 - LS2084A embedded compute processor
 - S32R27 radar microcontroller
- **Ease of Development**
 - ROS Space
 - Open ROS Space Linux®-based system
 - Programmable in linear C
 - Easily customizable
 - Development environment for mainstream vehicles
 - AUTOSAR Adaptive Ready
- **Security**
 - CSE and ARM® TrustZone® technology
- **High Performance per Power**
 - Up to 90,000 DMIPS at < 40 W
 - Complete situational assessment
 - Supporting classification
 - Object detection and localization
 - Mapping
- **Decision Making**
 - Global Path Planning
 - Behavior Planning
 - Motion Planning

ARA::COM over Virtual Ethernet

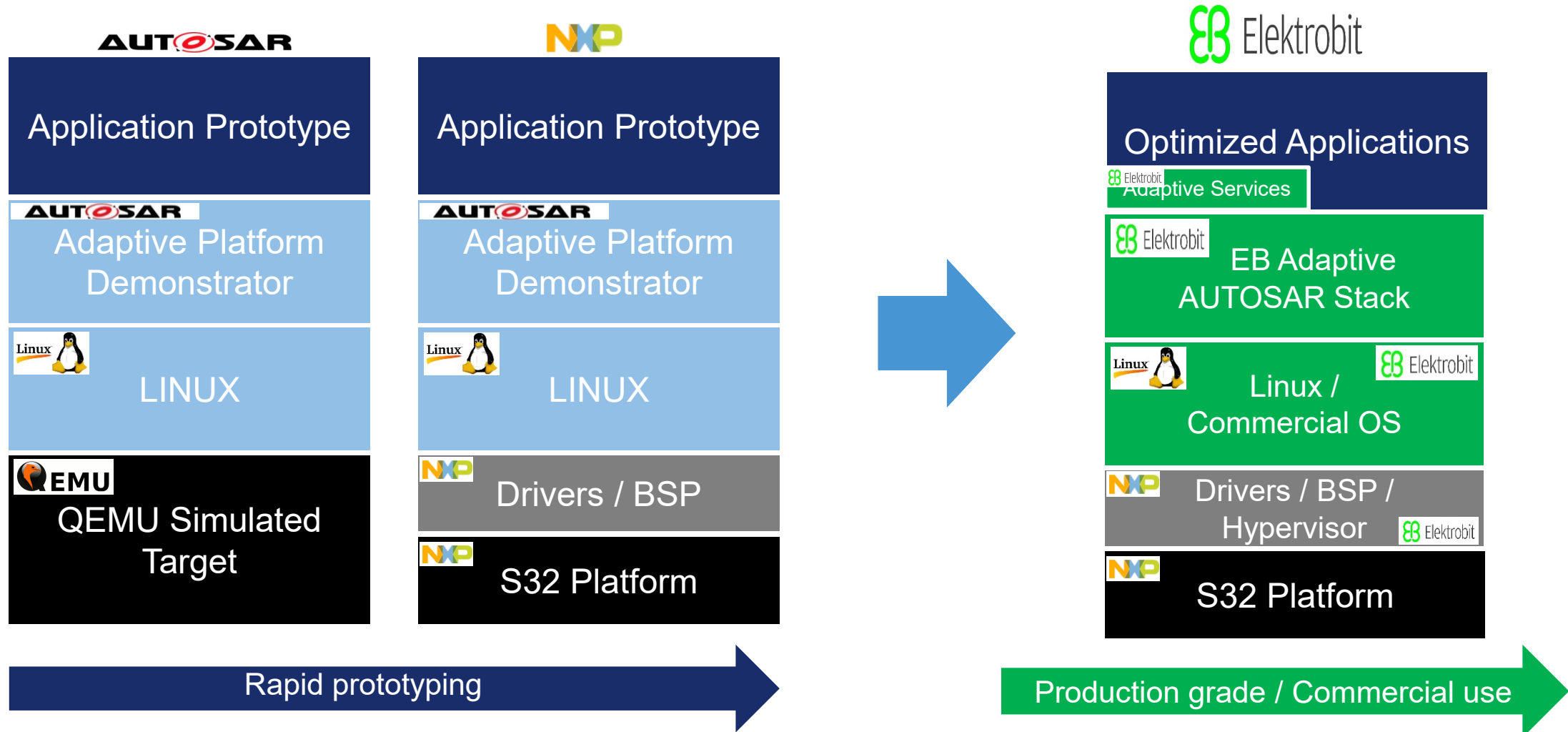


NXP Automated Drive Kit

- Computing: NXP BlueBox 2.0
- Vision: Front Camera Software with MIPI CSI2 Camera
- LiDAR: Selection of Lidars supported
- RADAR
- Inertial Measurement Unit & Integrated GPS
- Operating System
- Middleware: ROS (Robot Operating System)



Software Infrastructure for AUTOSAR Adaptive Platform



Elektrobit's Adaptive AUTOSAR Solution for NXP's Platforms



Placeholder for Elektrobit Presentation

- (TBC if it will be incorporated or need to stay separately)

Q&A





**SECURE CONNECTIONS
FOR A SMARTER WORLD**